

# Register Allocation

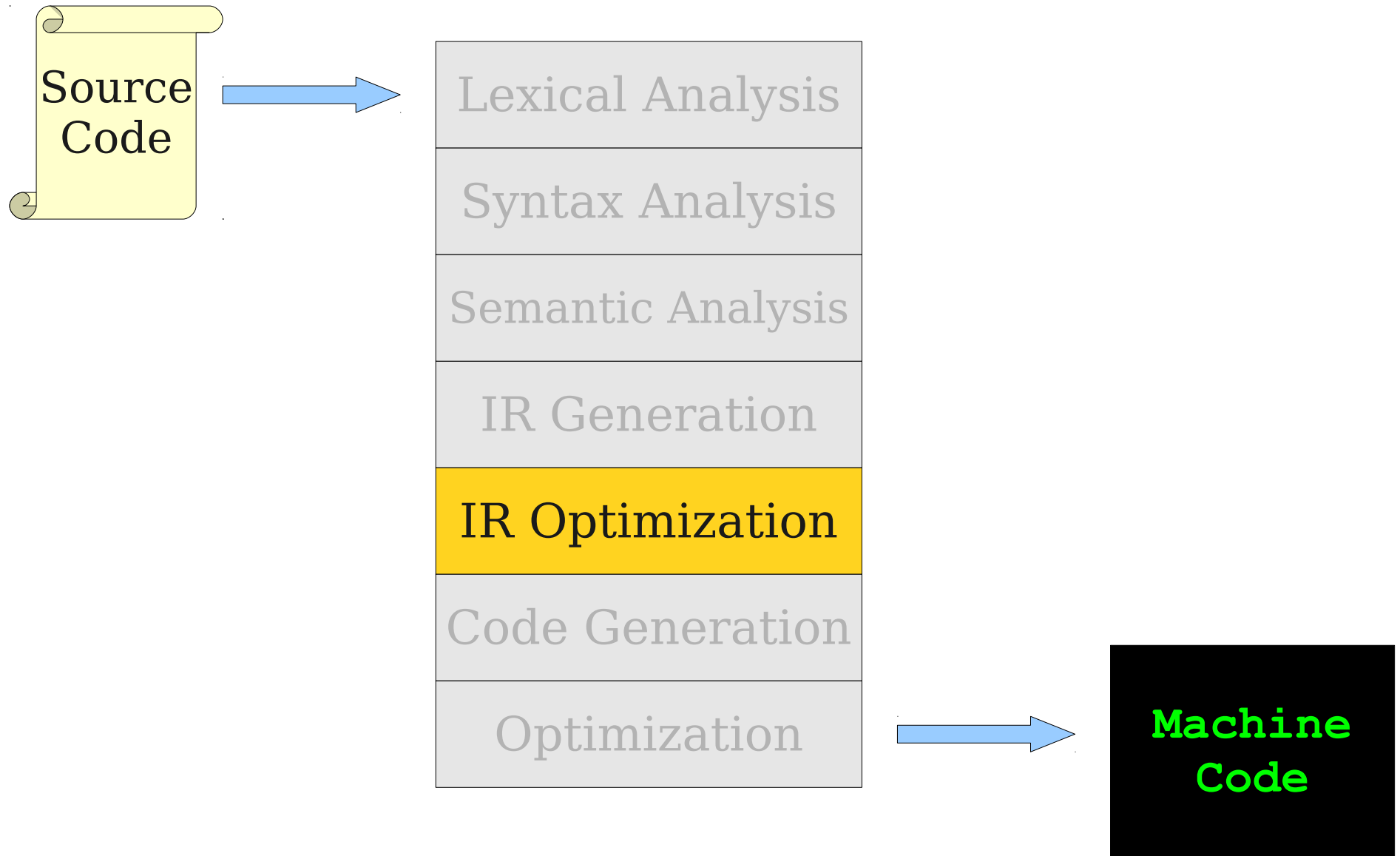
# Announcements

- Programming Project 4 due Saturday, August 18 at 11:30AM
  - OH all this week.
  - Ask questions via email!
  - Ask questions via Piazza!
  - **No late submissions.**

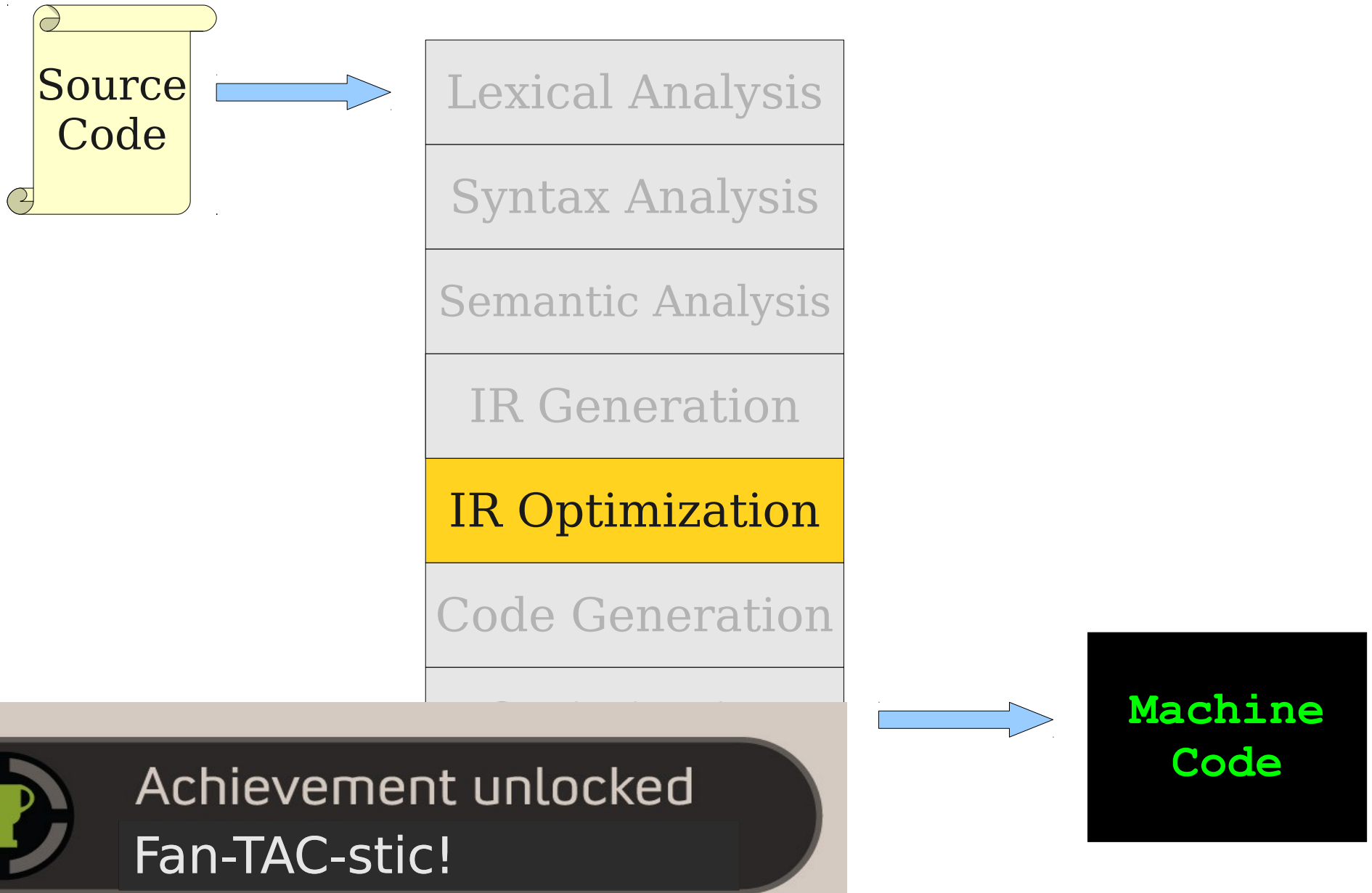
Please evaluate this course on Axess.

Your feedback really makes a difference.

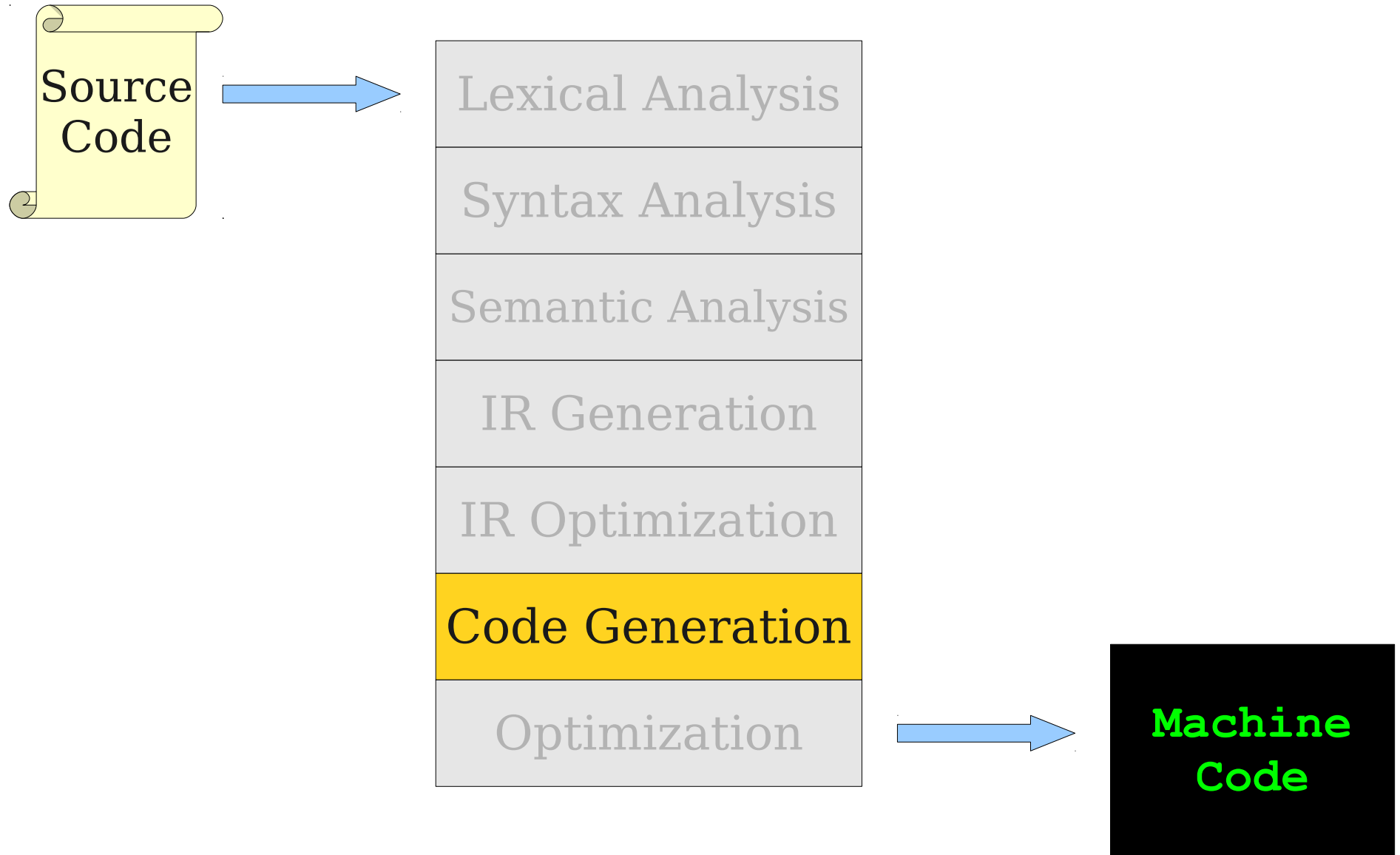
# Where We Are



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# Code Generation at a Glance

- At this point, we have optimized IR code that needs to be converted into the target language (e.g. assembly, machine code).
- Goal of this stage:
  - Choose the appropriate machine instructions for each IR instruction.
  - Divvy up finite machine resources (registers, caches, etc.)
  - Implement low-level details of the runtime environment.
- Machine-specific optimizations are often done here, though some are treated as part of a final optimization phase.

# Overview

- **Register Allocation** (Today)
  - How to assign variables to finitely many registers?
  - What to do when it can't be done?
  - How to do so efficiently?
- **Garbage Collection** (Monday)
  - How to detect reclaimable memory?
  - How to reclaim memory efficiently?



# Memory Tradeoffs

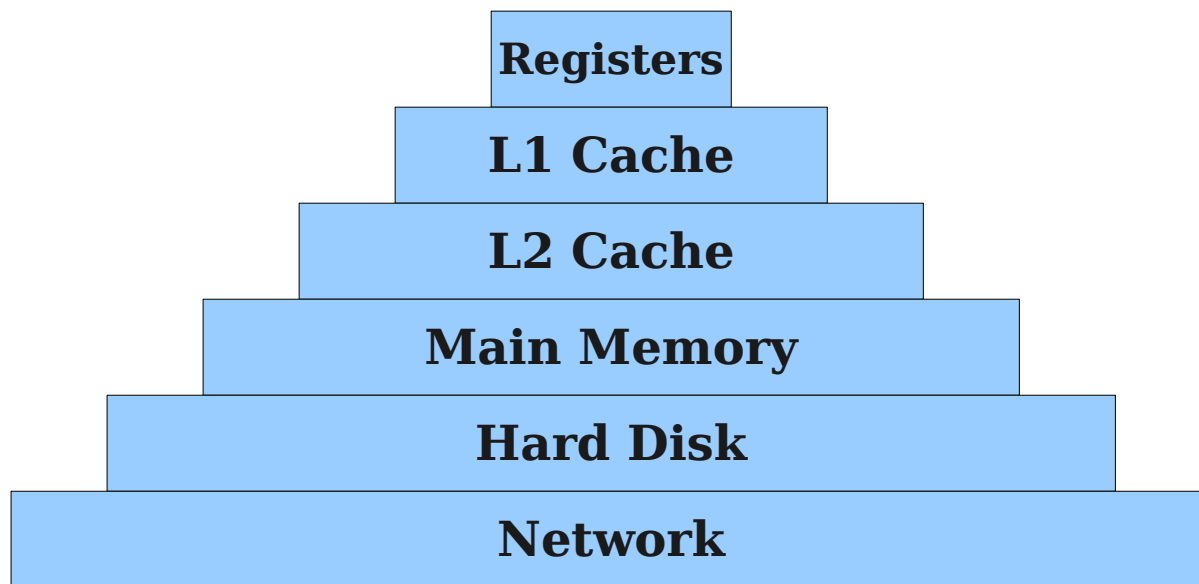
- There is an enormous tradeoff between *speed* and *size* in memory.
- SRAM is fast but very expensive:
  - Can keep up with processor speeds in the GHz.
  - As of 2007, cost is \$10/MB
  - Good luck buying 1TB of the stuff!
- Hard disks are cheap but very slow:
  - As of 2012, you can buy a 2TB hard drive for about \$100
  - As of 2012, good disk seek times are measured in ms (about two to four million times slower than a processor cycle!)

# The Memory Hierarchy

- **Idea:** Try to get the best of all worlds by using multiple types of memory.

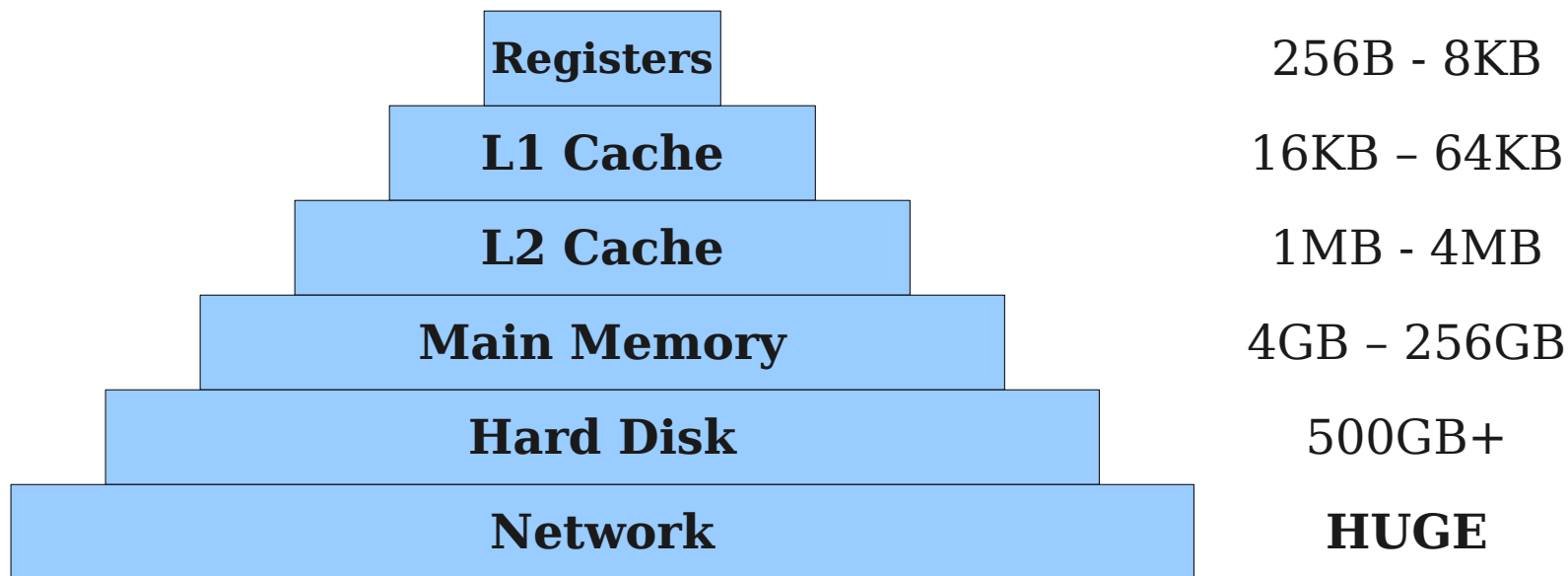
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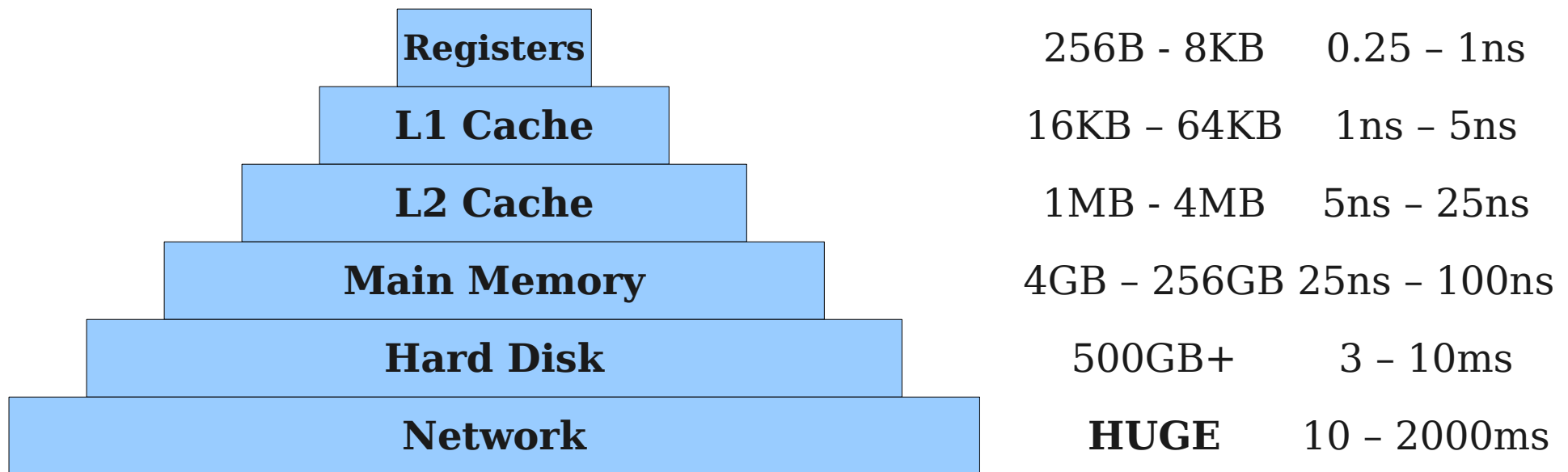
# The Memory Hierarchy

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# The Challenges of Code Generation

- Almost all programming languages expose a coarse view of the memory hierarchy:
  - All variables live in “memory.”
  - Disk and network explicitly handled separately.
- (Interesting exception: Stanford's **Sequoia** programming language)
- Challenges in code generation:
  - Position objects in a way that takes maximum advantage of the memory hierarchy.
  - Do so without hints from the programmer.

# Registers

- Most machines have a set of **registers**, dedicated memory locations that
  - can be accessed quickly,
  - can have computations performed on them, and
  - exist in small quantity.
- Using registers intelligently is a critical step in any compiler.
  - A good register allocator can generate code orders of magnitude better than a bad register allocator.

# Register Allocation

- In TAC, there are an unlimited number of variables.
- On a physical machine there are a small number of registers:
  - x86 has four general-purpose registers and a number of specialized registers.
  - MIPS has twenty-four general-purpose registers and eight special-purpose registers.
- **Register allocation** is the process of assigning variables to registers and managing data transfer in and out of registers.



# Challenges in Register Allocation

- **Registers are scarce.**
  - Often substantially more IR variables than registers.
  - Need to find a way to reuse registers whenever possible.
- **Registers are complicated.**
  - x86: Each register made of several smaller registers; can't use a register and its constituent registers at the same time.
  - x86: Certain instructions must store their results in specific registers; can't store values there if you want to use those instructions.
  - MIPS: Some registers reserved for the assembler or operating system.
  - Most architectures: Some registers must be preserved across function calls.

# Goals for Today

- Introduce register allocation for a MIPS-style machine:
  - Some number of indivisible, general-purpose registers.
- Explore three algorithms for register allocation:
  - Naïve (“no”) register allocation.
  - Linear scan register allocation.
  - Graph-coloring register allocation.

# An Initial Register Allocator

- **Idea:** Store every value in main memory, loading values only when they're needed.
- To generate a code that performs a computation:
  - Generate **load** instructions to pull the values from main memory into registers.
  - Generate code to perform the computation on the registers.
  - Generate **store** instructions to store the result back into main memory.

# Our Register Allocator In Action

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```
a = b + c;
```

```
d = a;
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c = a + d;
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<b>Param N</b>	<b>fp + 4N</b>
...	...
<b>Param 1</b>	<b>fp + 4</b>
<b>Stored fp</b>	<b>fp + 0</b>
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# Our Register Allocator In Action

**a = b + c;**      `lw $t0, -12(fp)`  
`d = a;`  
`c = a + d;`

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add   $t2, $t0, $t1
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```
sw    $t2, -8(fp)
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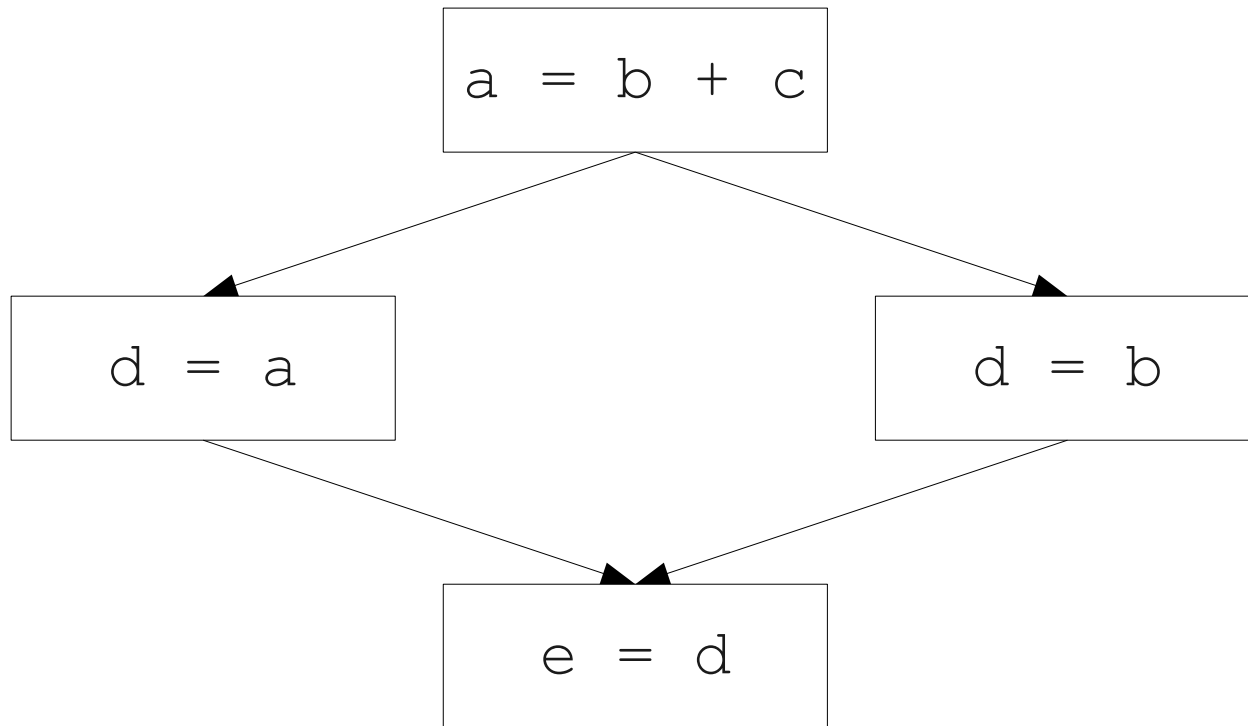
# Analysis of our Allocator

- Disadvantage: **Gross inefficiency**.
  - Issues unnecessary loads and stores by the dozen.
  - Wastes space on values that could be stored purely in registers.
  - Easily an order of magnitude or two slower than necessary.
  - Unacceptable in any production compiler.
- Advantage: **Simplicity**.
  - Can translate each piece of IR directly to assembly as we go.
  - Never need to worry about running out of registers.
  - Never need to worry about function calls or special-purpose registers.
  - Good if you just needed to get a prototype compiler up and running.

# Building a Better Allocator

- **Goal:** Try to hold as many variables in registers as possible.
  - Reduces memory reads/writes.
  - Reduces total memory usage.
- We will need to address these questions:
  - Which registers do we put variables in?
  - What do we do when we run out of registers?

# Register Consistency



# Register Consistency

- At each program point, each variable must be in the same location.
  - Does **not** mean that each variable is always stored in the same location!
- At each program point, each register holds at most one live variable.
  - Can assign several variables the same register if no two of them ever will be read together.

# Live Ranges and Live Intervals

- Recall: A variable is **live** at a particular program point if its value may be read later before it is written.
  - Can find this using global liveness analysis.
- The **live range** for a variable is the set of program points at which that variable is live.
- The **live interval** for a variable is the smallest subrange of the IR code containing all a variable's live ranges.
  - A property of the IR code, **not** the CFG.
  - Less precise than live ranges, but simpler to work with.



# Live Ranges and Live Intervals

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```
e = d + a
```

```
f = b + c
```

```
f = f + b
```

```
IfZ e Goto _L0
```

```
d = e + f
```

```
Goto _L1;
```

```
_L0:
```

```
d = e - f
```

```
_L1:
```

```
g = d
```

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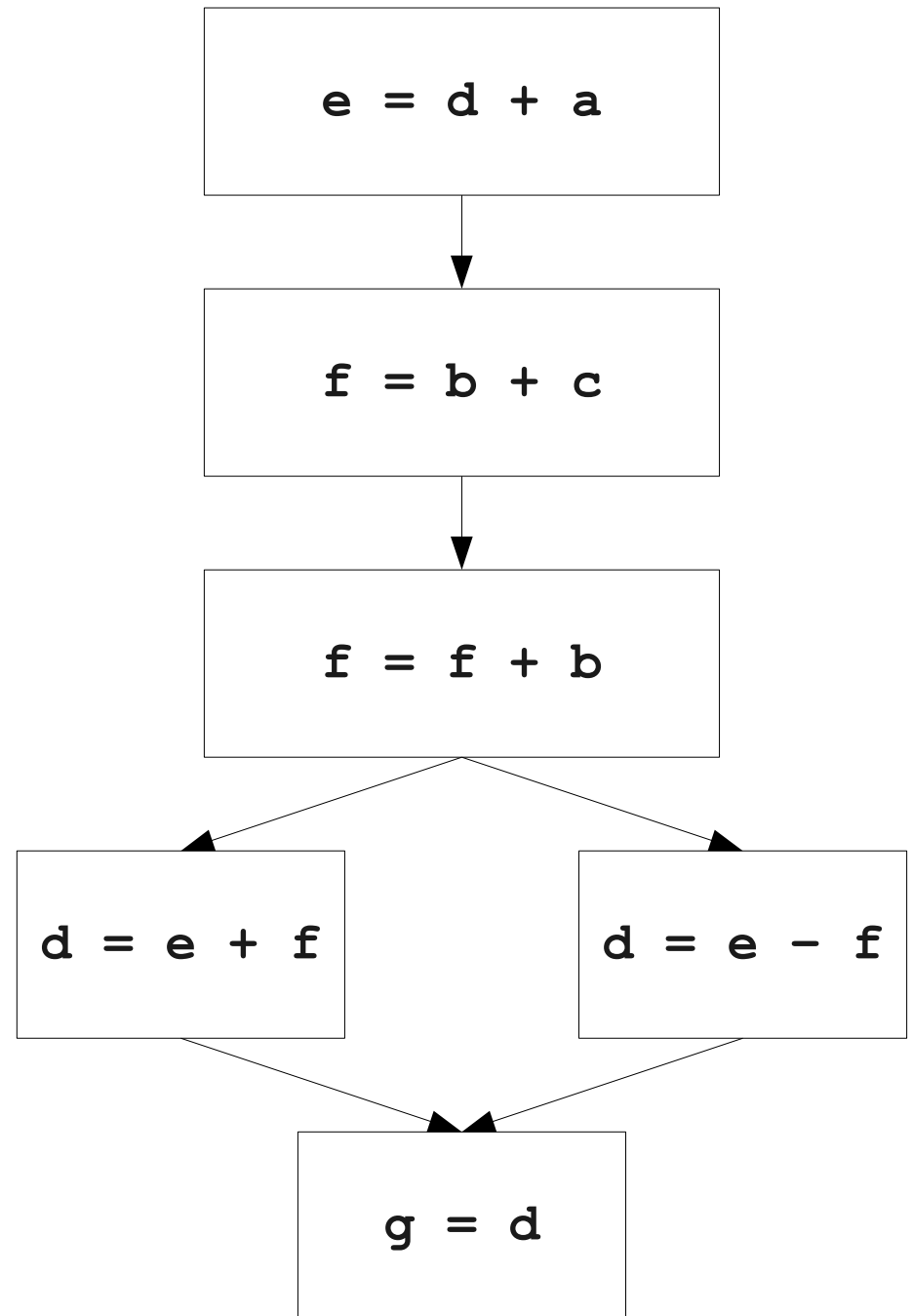
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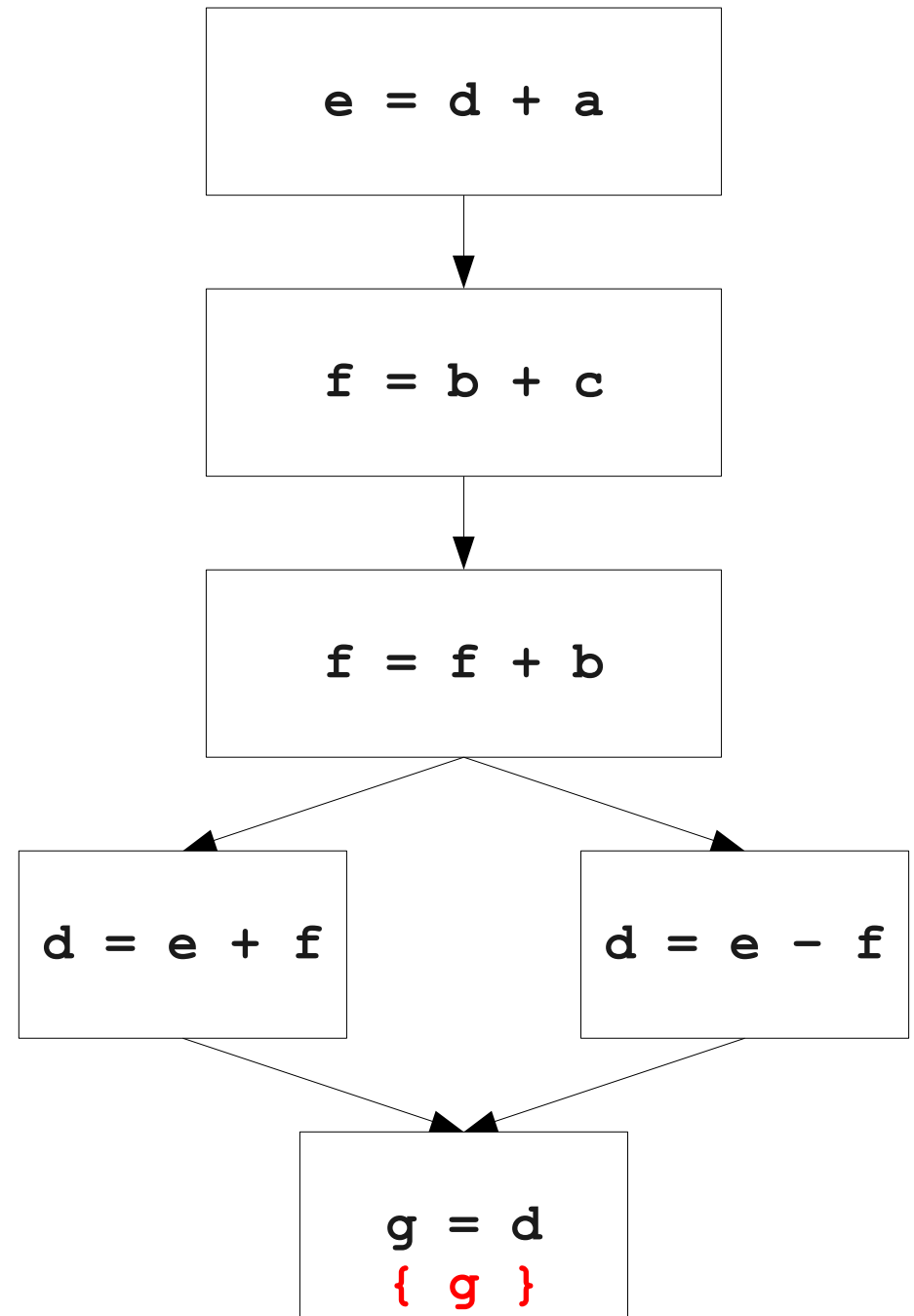
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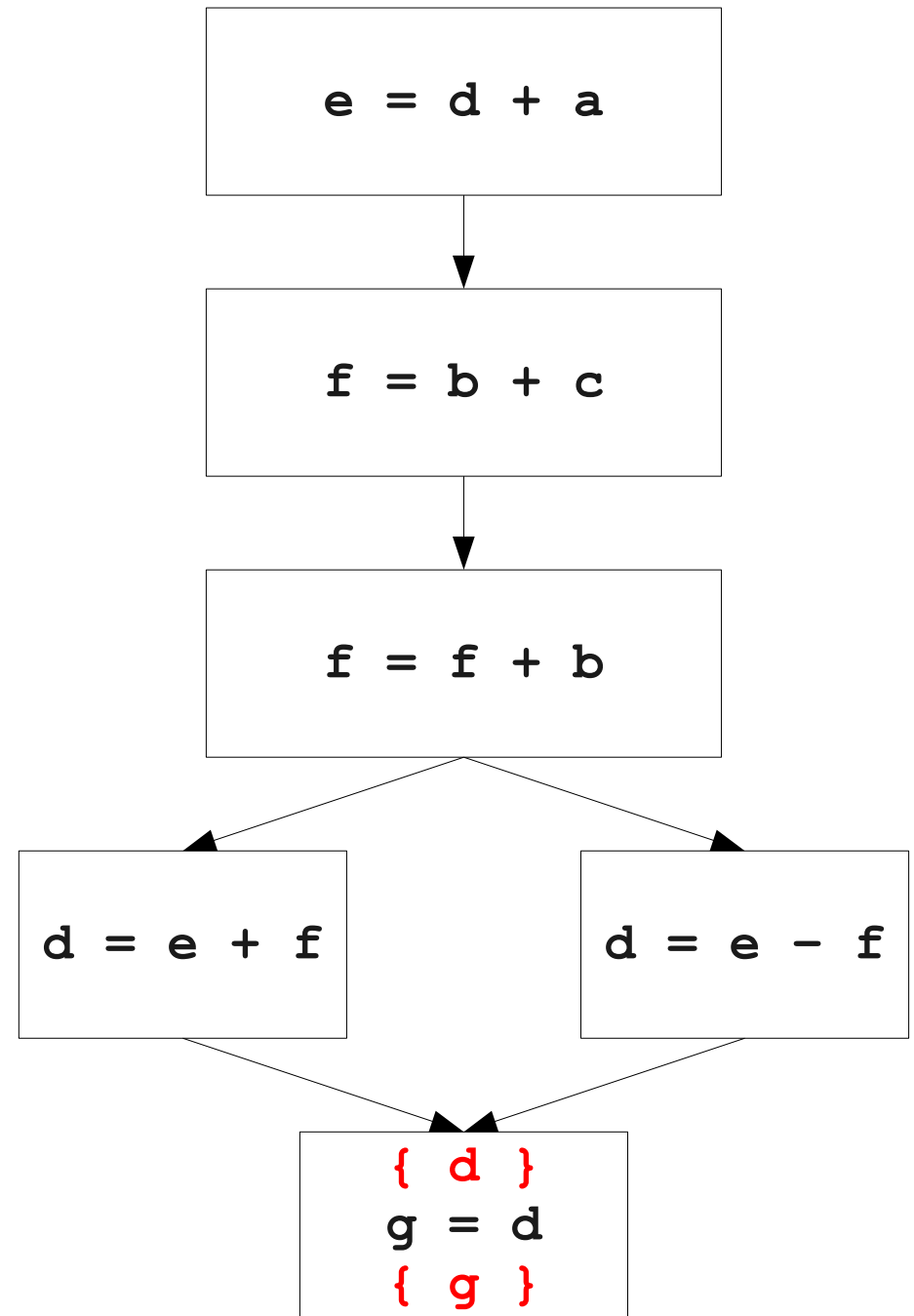
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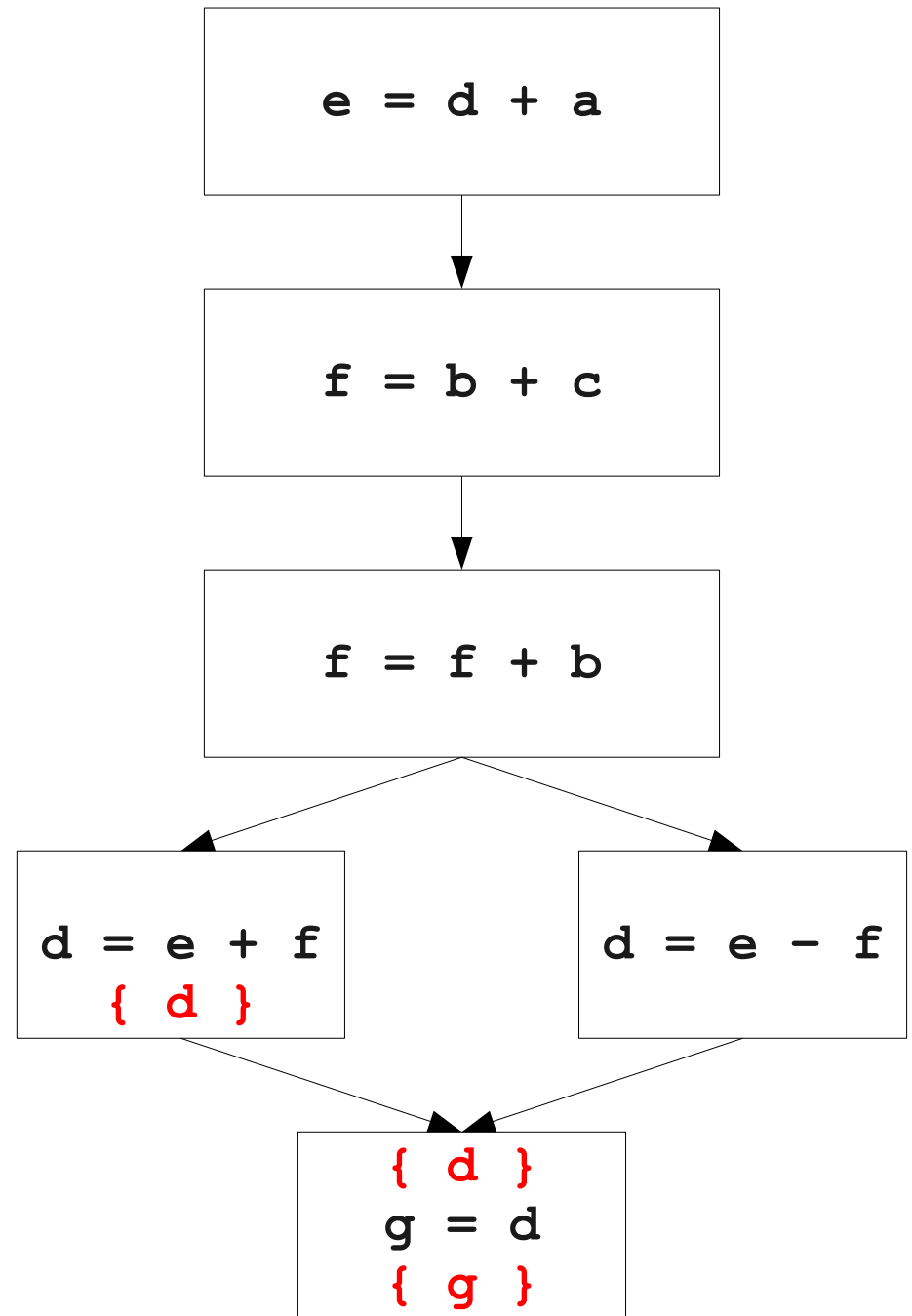
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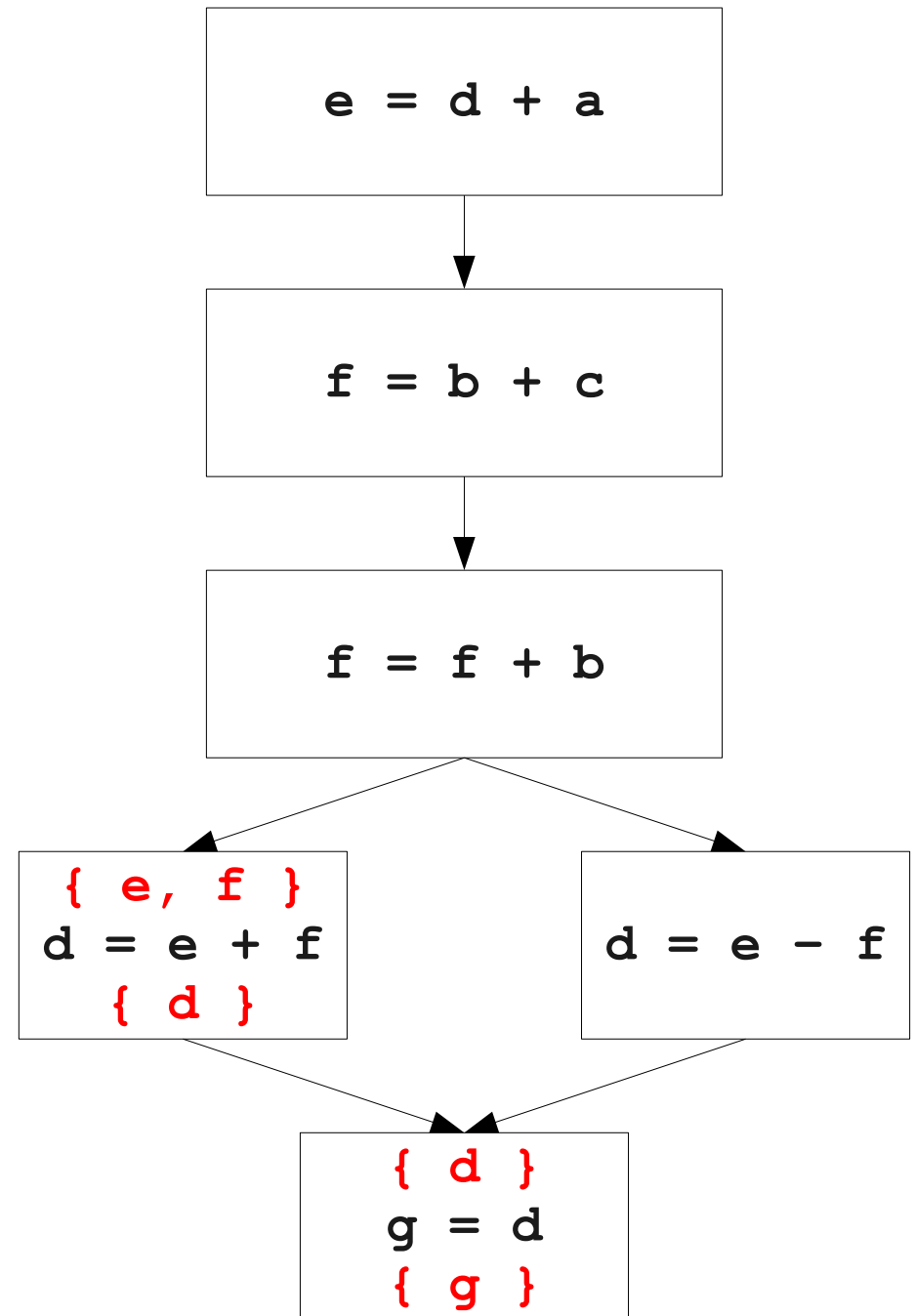
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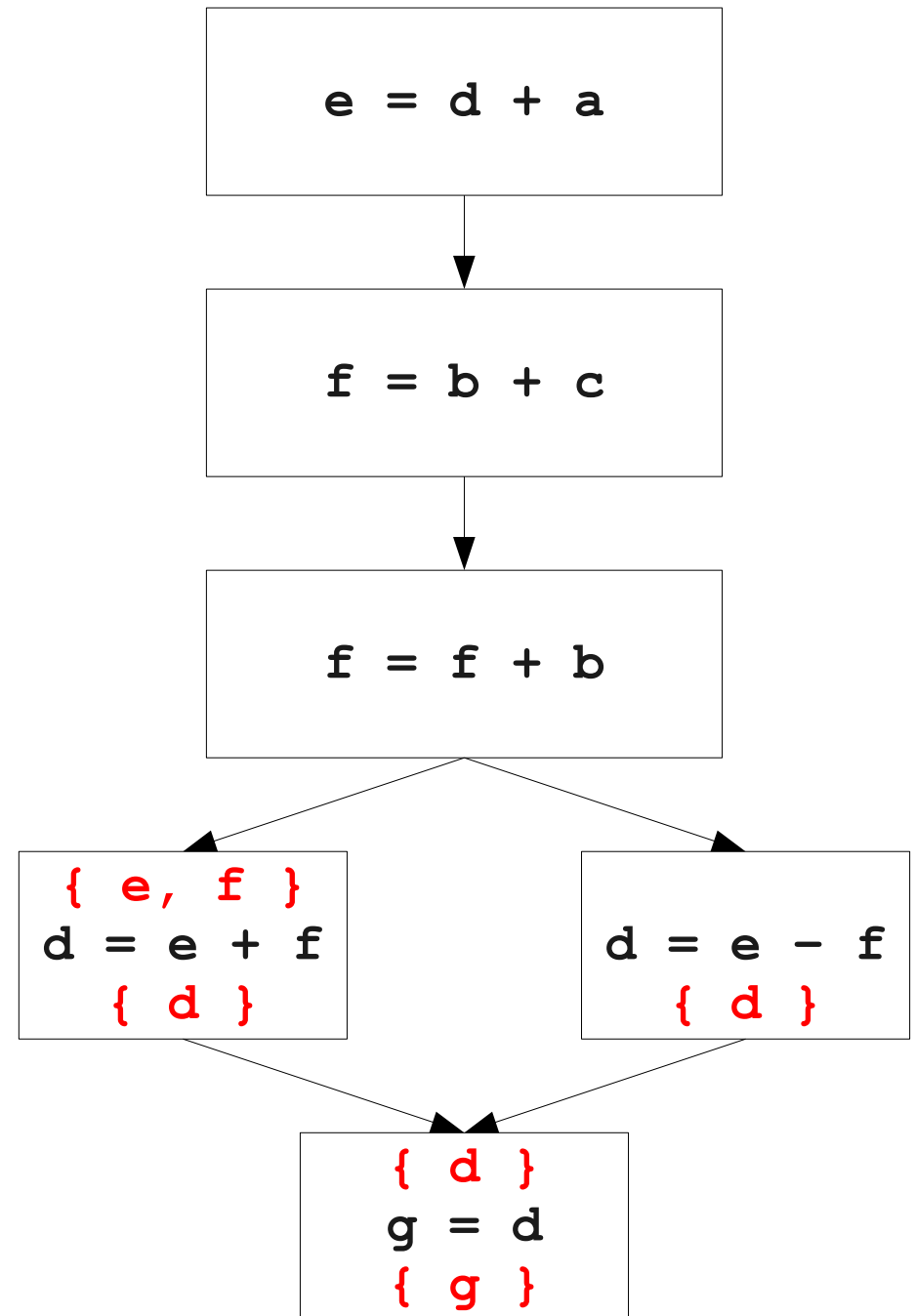
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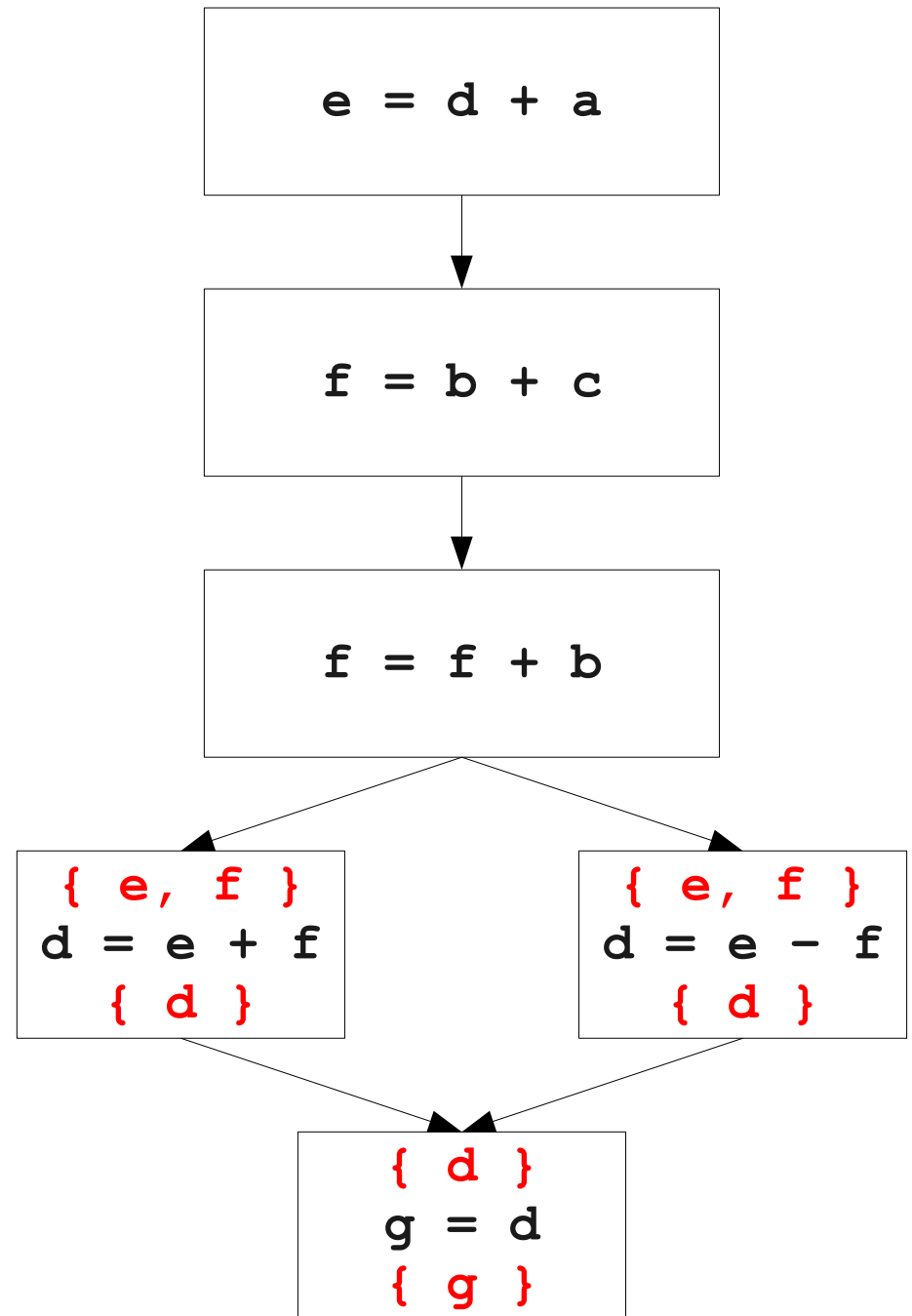
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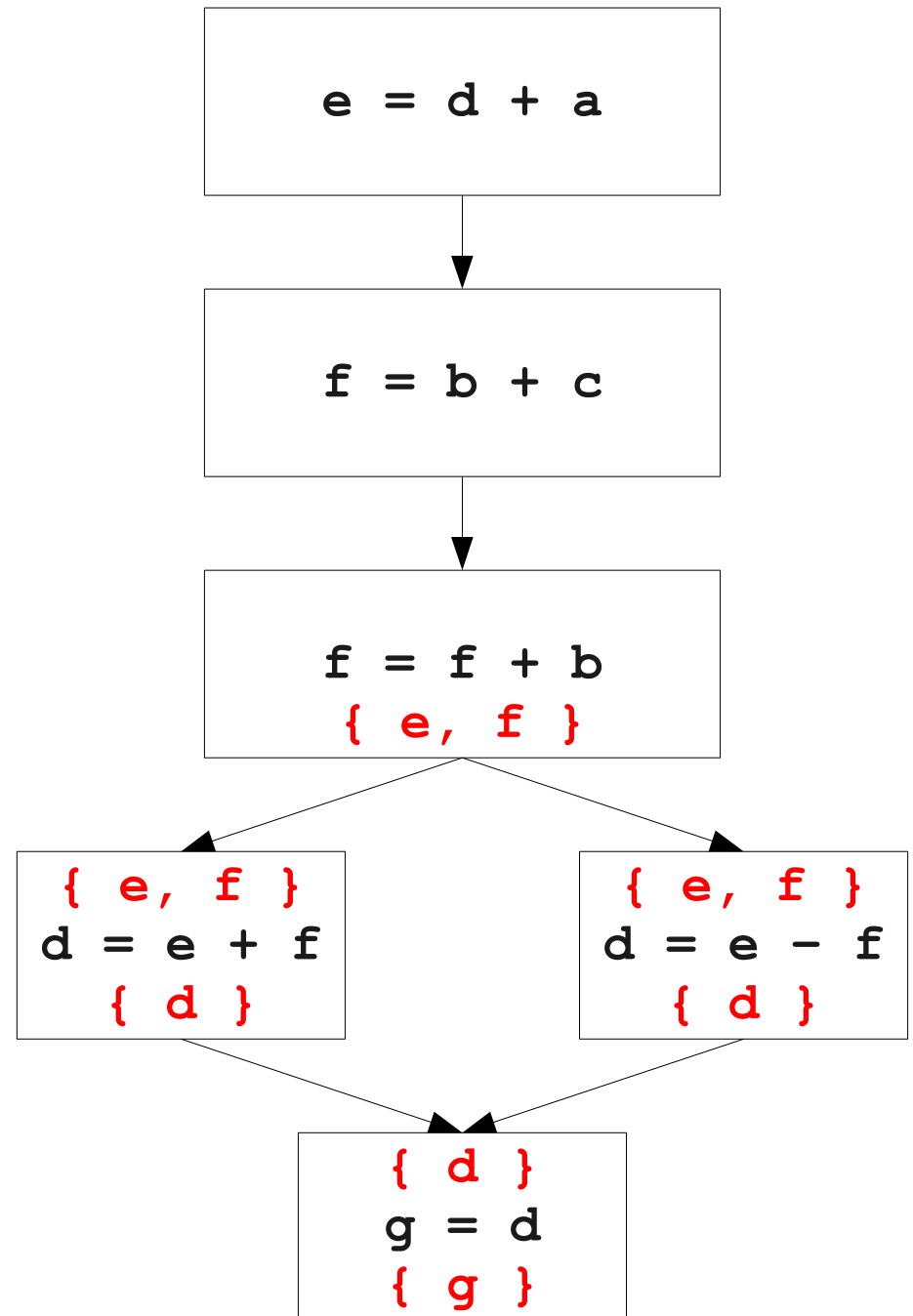
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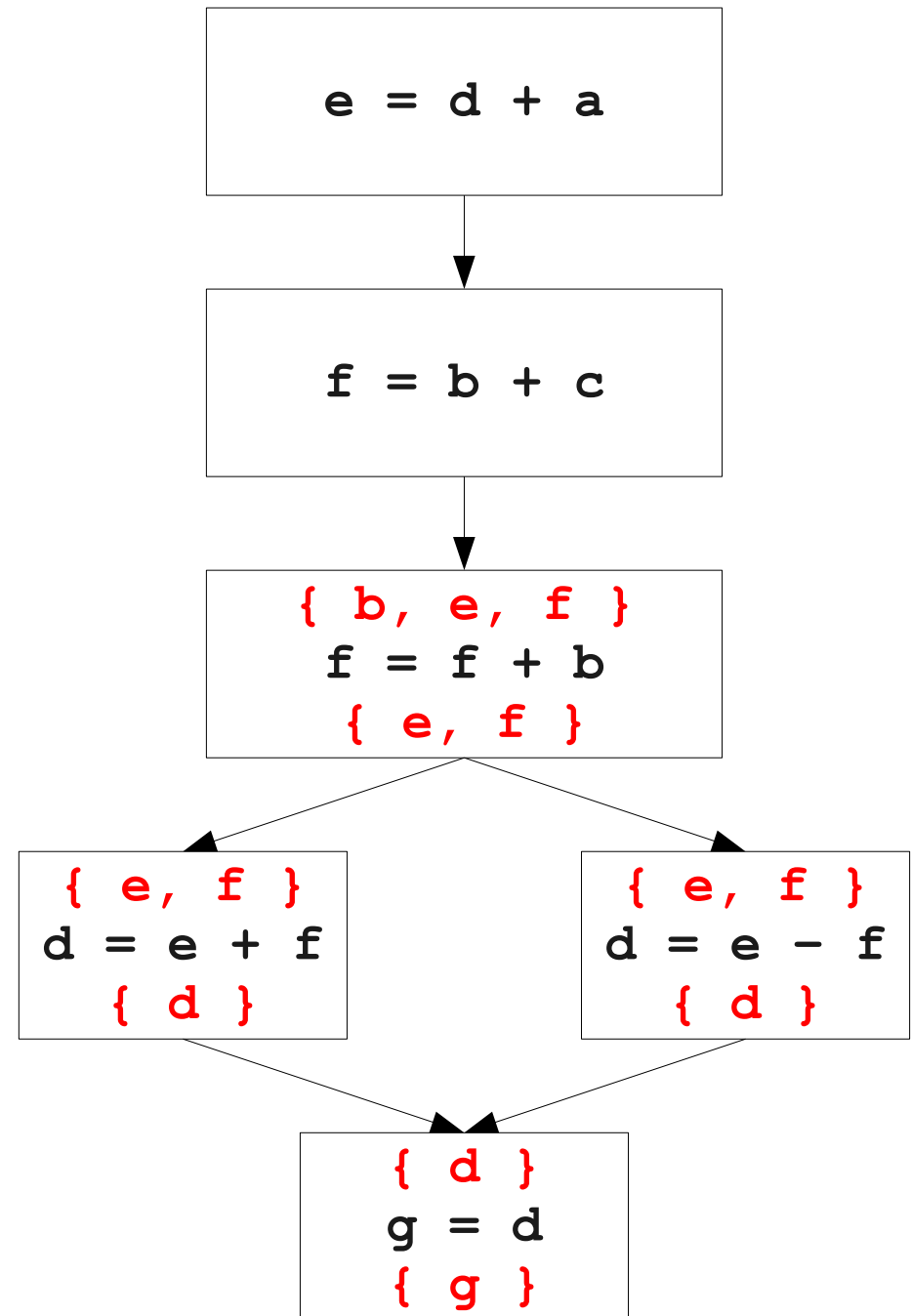
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d = e - f
```

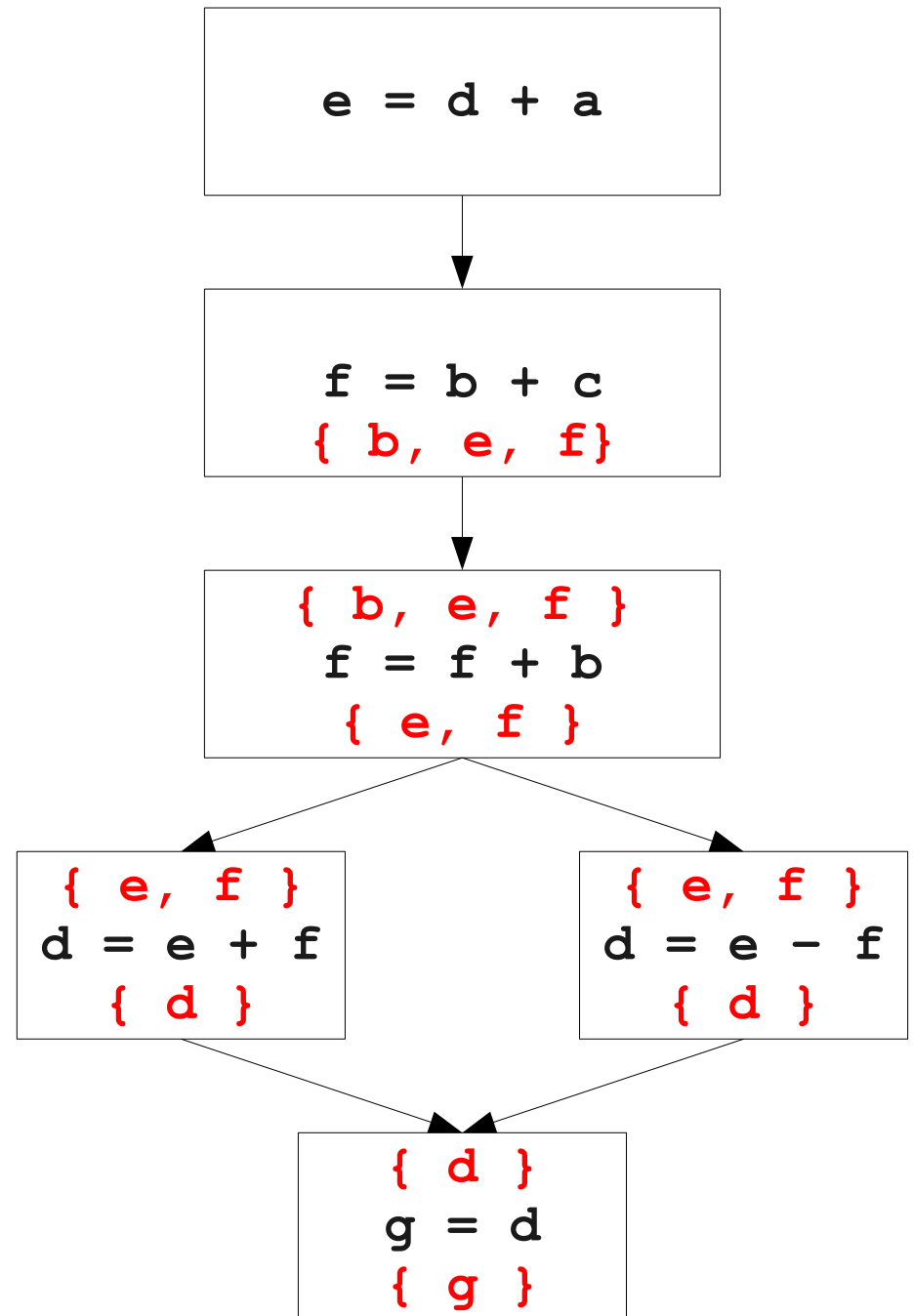
```
_L1:
```

```
g = d
```



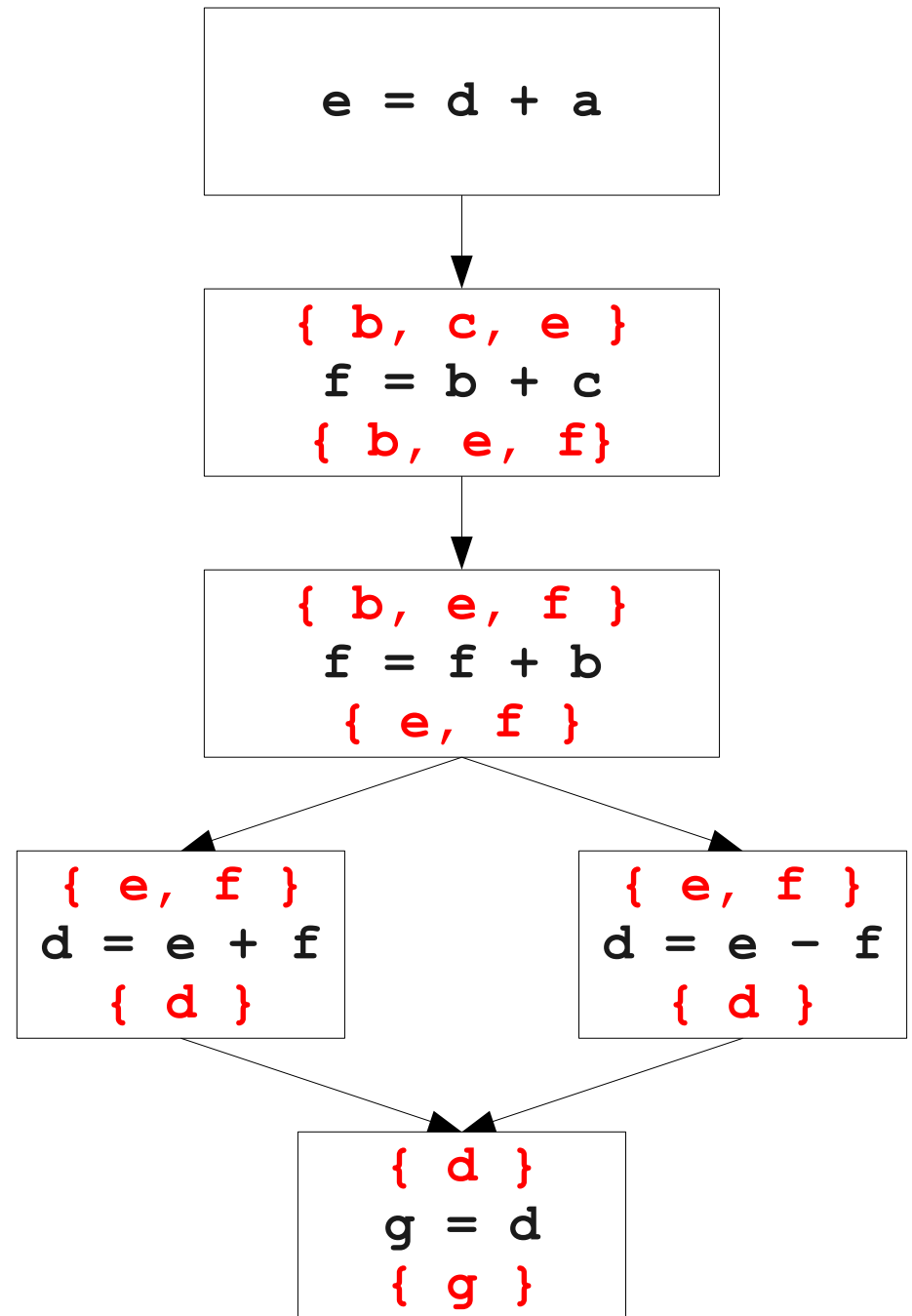
# Live Ranges and Live Intervals

```
e = d + a
f = b + c
f = f + b
IfZ e Goto _L0
d = e + f
Goto _L1;
_L0:
d = e - f
_L1:
g = d
```



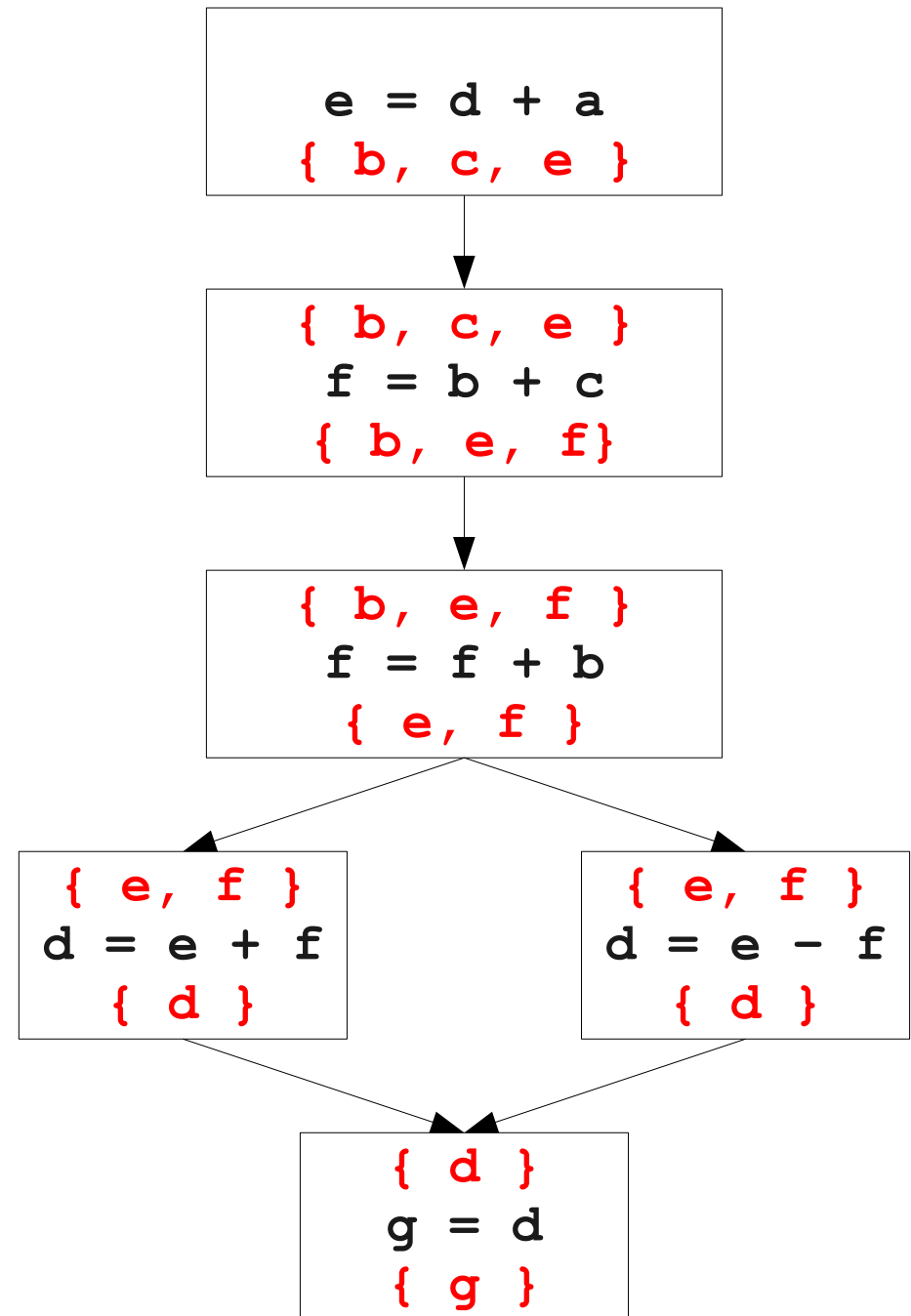
# Live Ranges and Live Intervals

```
e = d + a
f = b + c
f = f + b
IfZ e Goto _L0
d = e + f
Goto _L1;
_L0:
d = e - f
_L1:
g = d
```



# Live Ranges and Live Intervals

```
e = d + a
f = b + c
f = f + b
IfZ e Goto _L0
d = e + f
Goto _L1;
_L0:
d = e - f
_L1:
g = d
```



# Live Ranges and Live Intervals

```
e = d + a
```

```
f = b + c
```

```
f = f + b
```

```
IfZ e Goto _L0
```

```
d = e + f
```

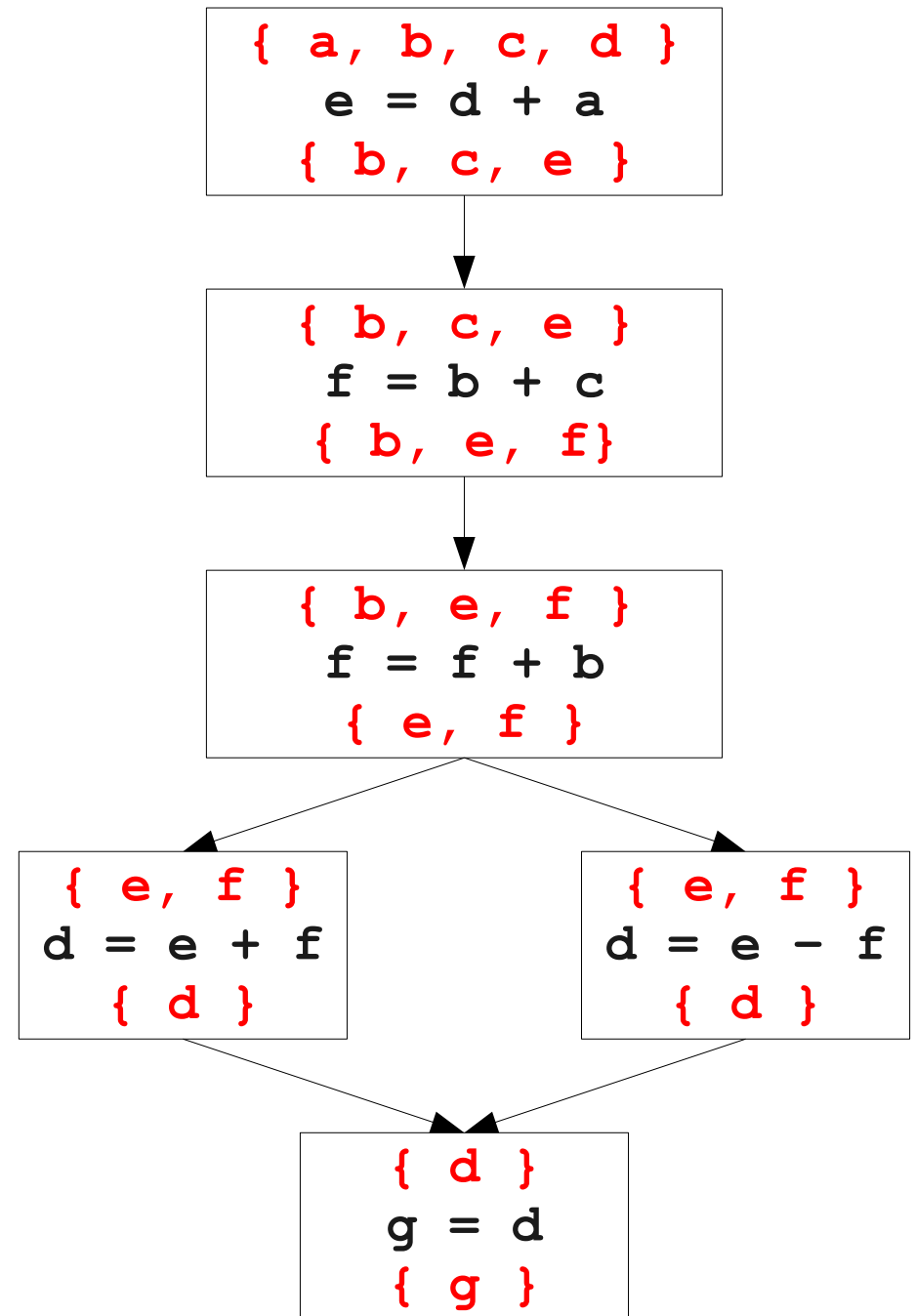
```
Goto _L1;
```

```
_L0:
```

```
d = e - f
```

```
_L1:
```

```
g = d
```



# Live Ranges and Live Intervals

---

```
e = d + a
```

---

```
f = b + c
```

---

```
f = f + b
```

---

```
IfZ e Goto _L0
```

---

```
d = e + f
```

---

```
Goto _L1;
```

---

```
_L0:
```

---

```
d = e - f
```

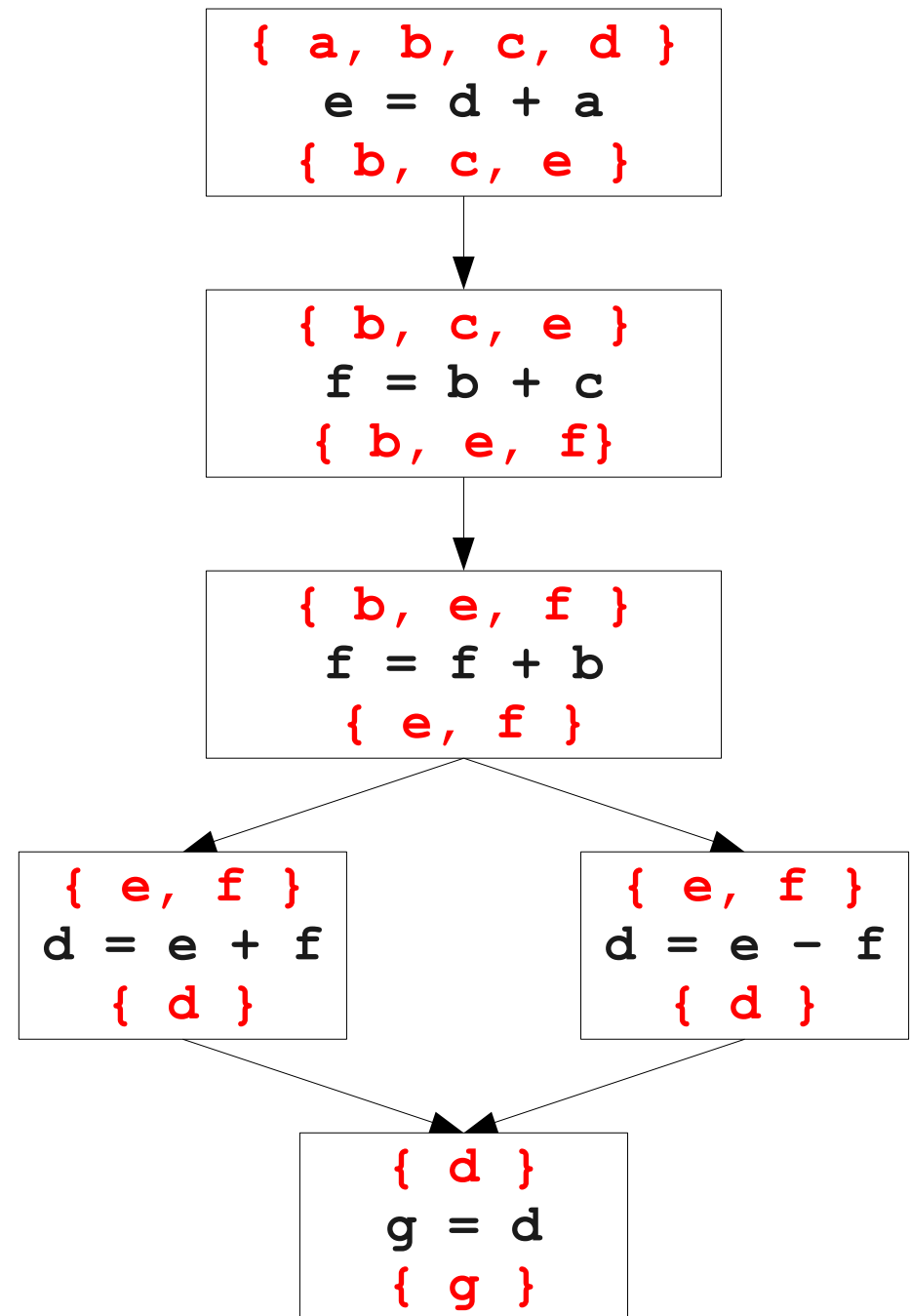
---

```
_L1:
```

---

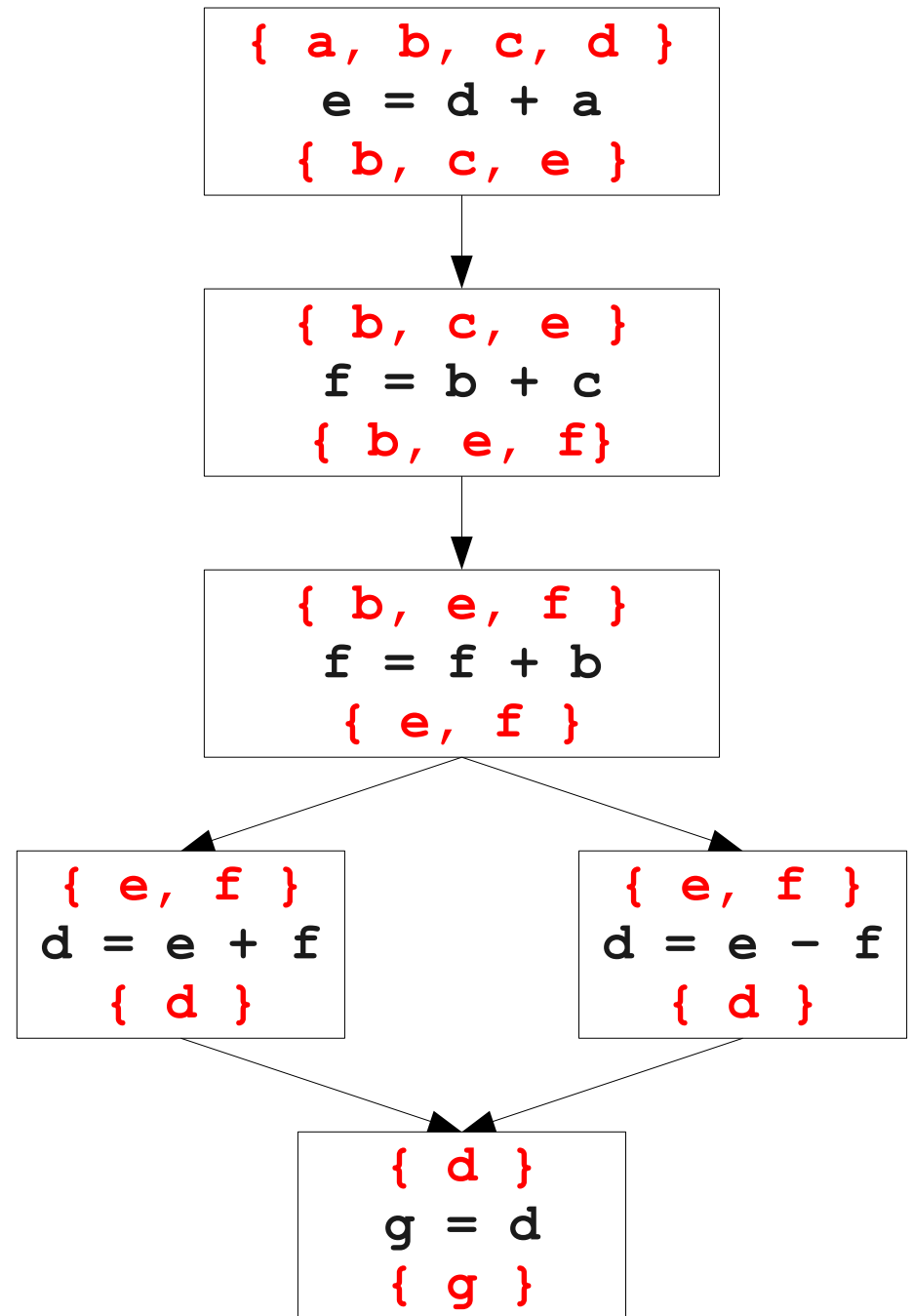
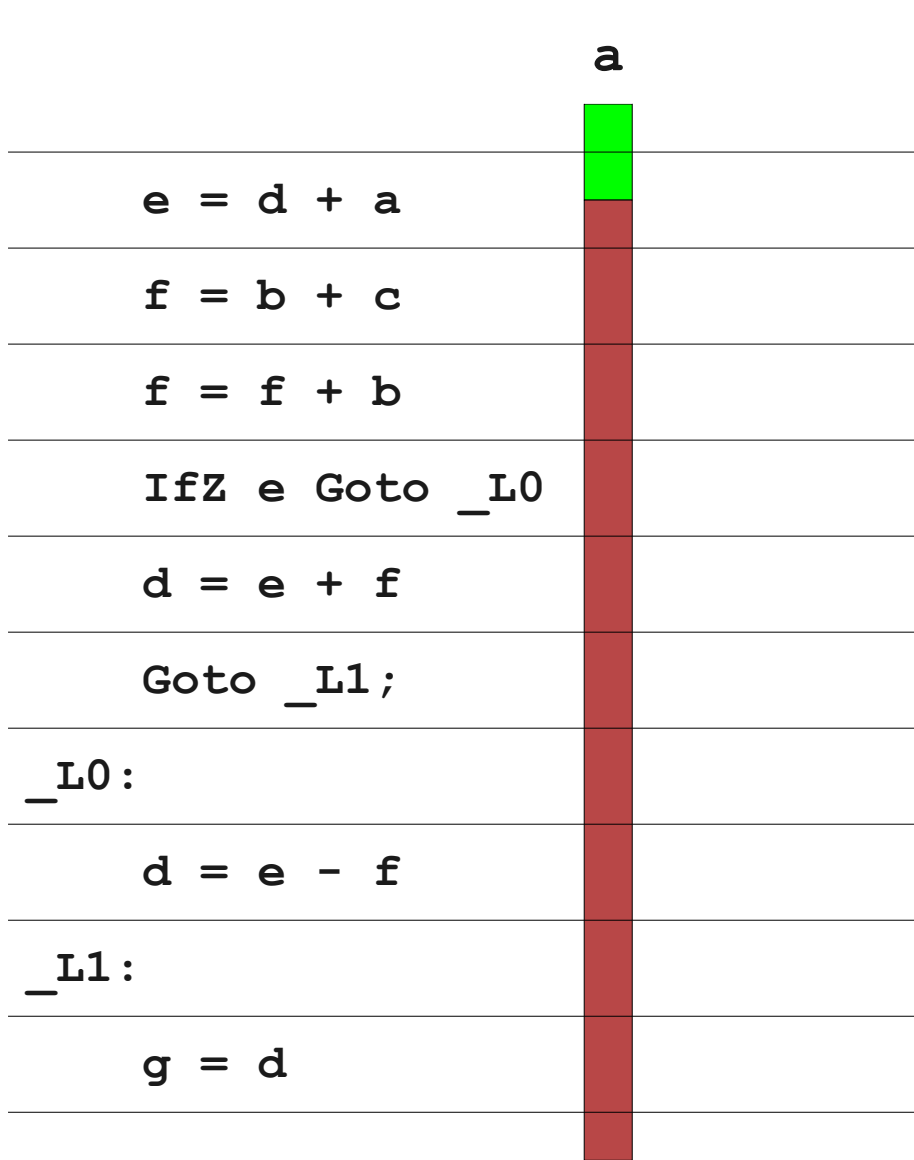
```
g = d
```

---

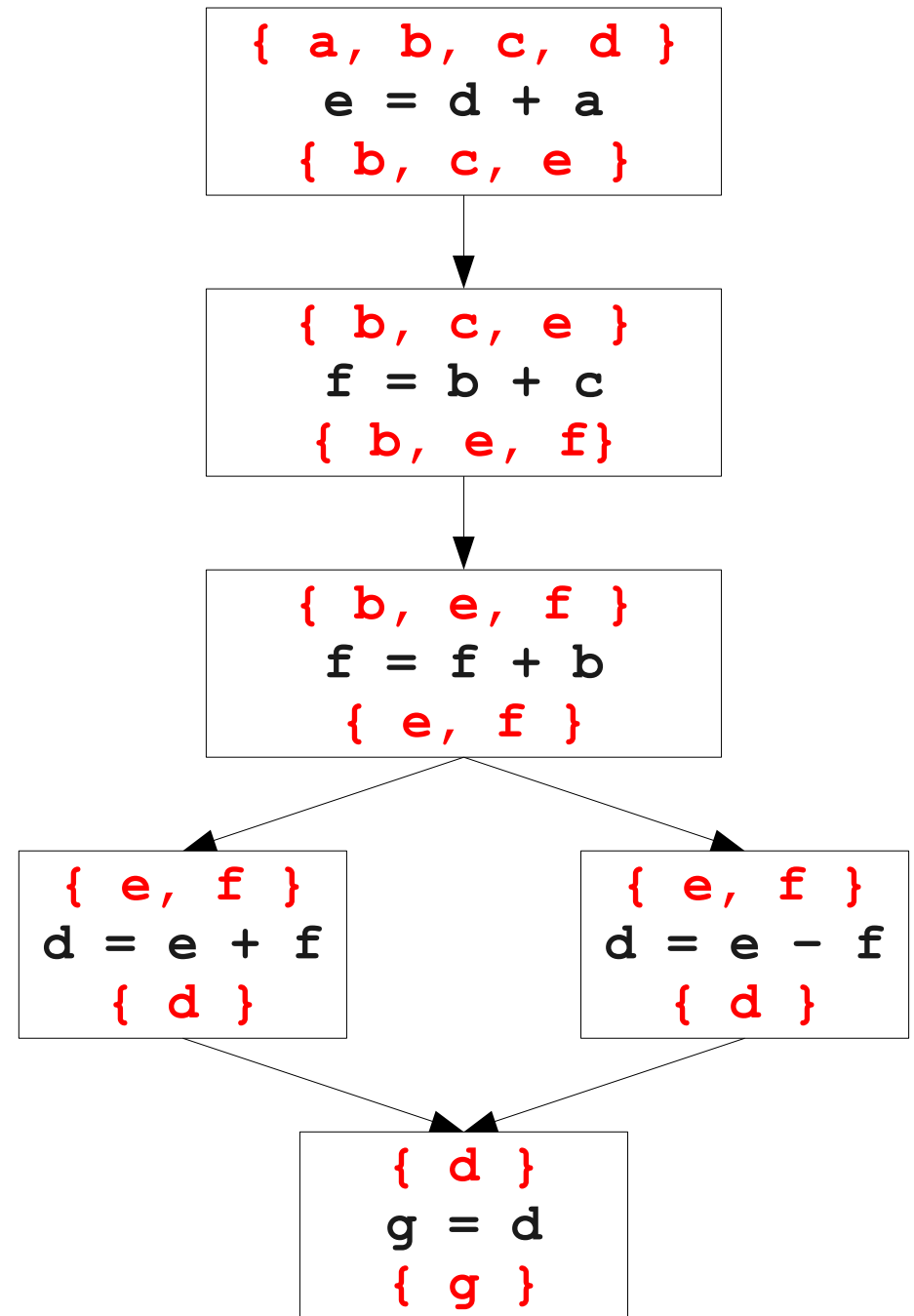
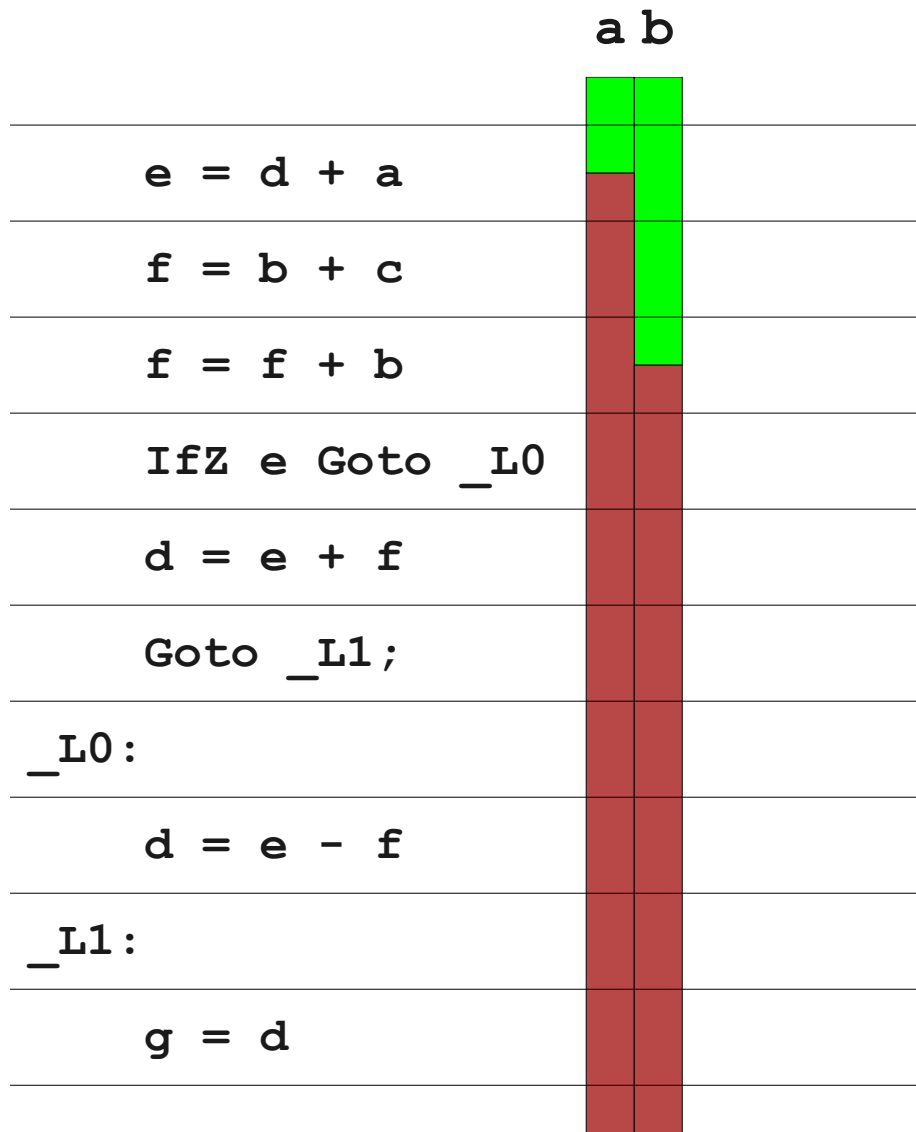




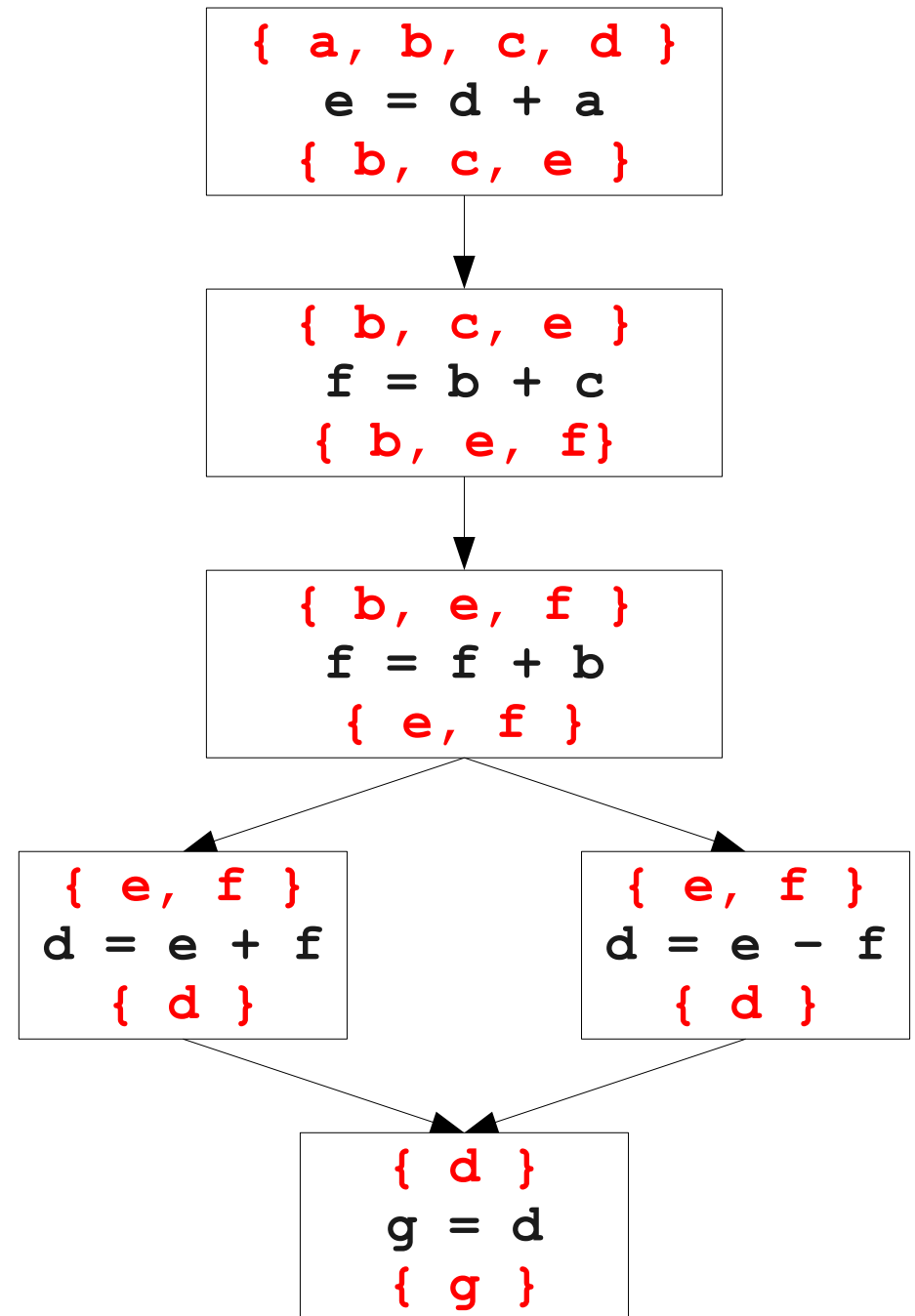
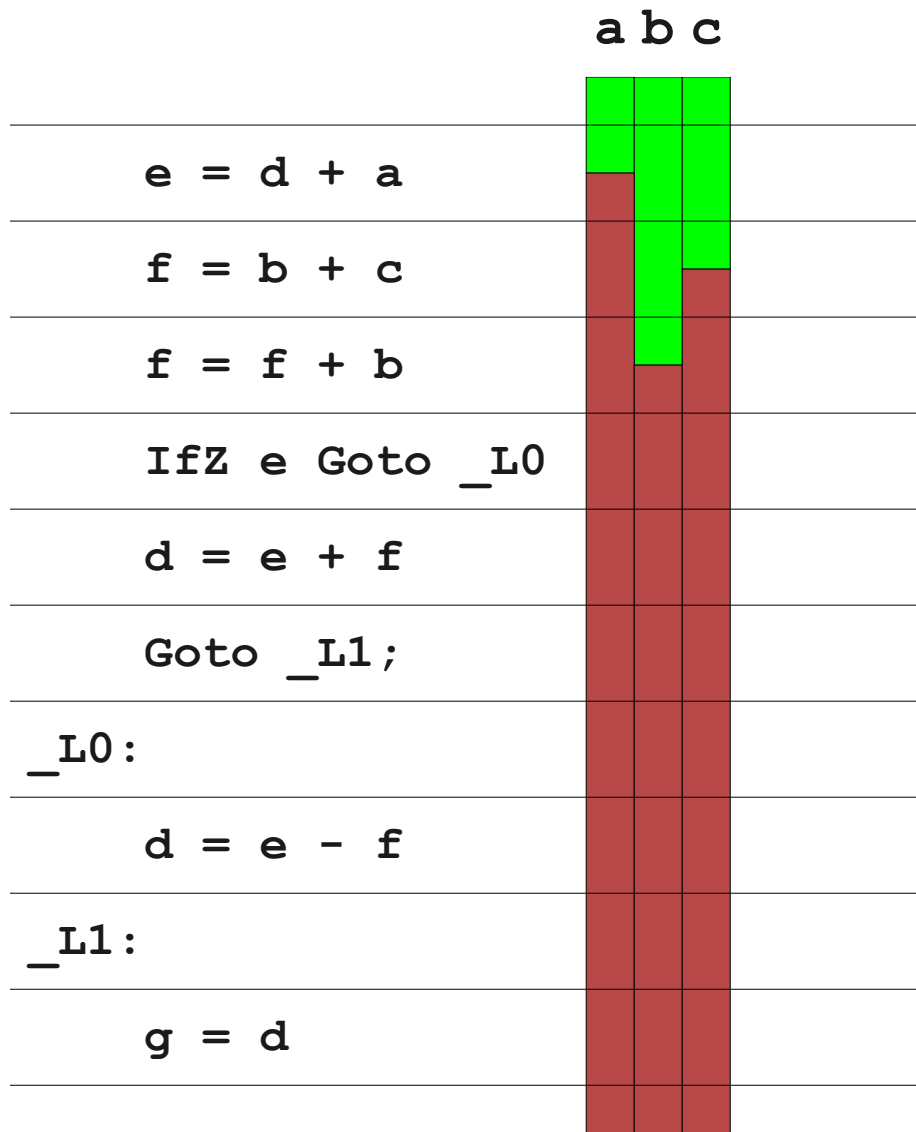
# Live Ranges and Live Intervals



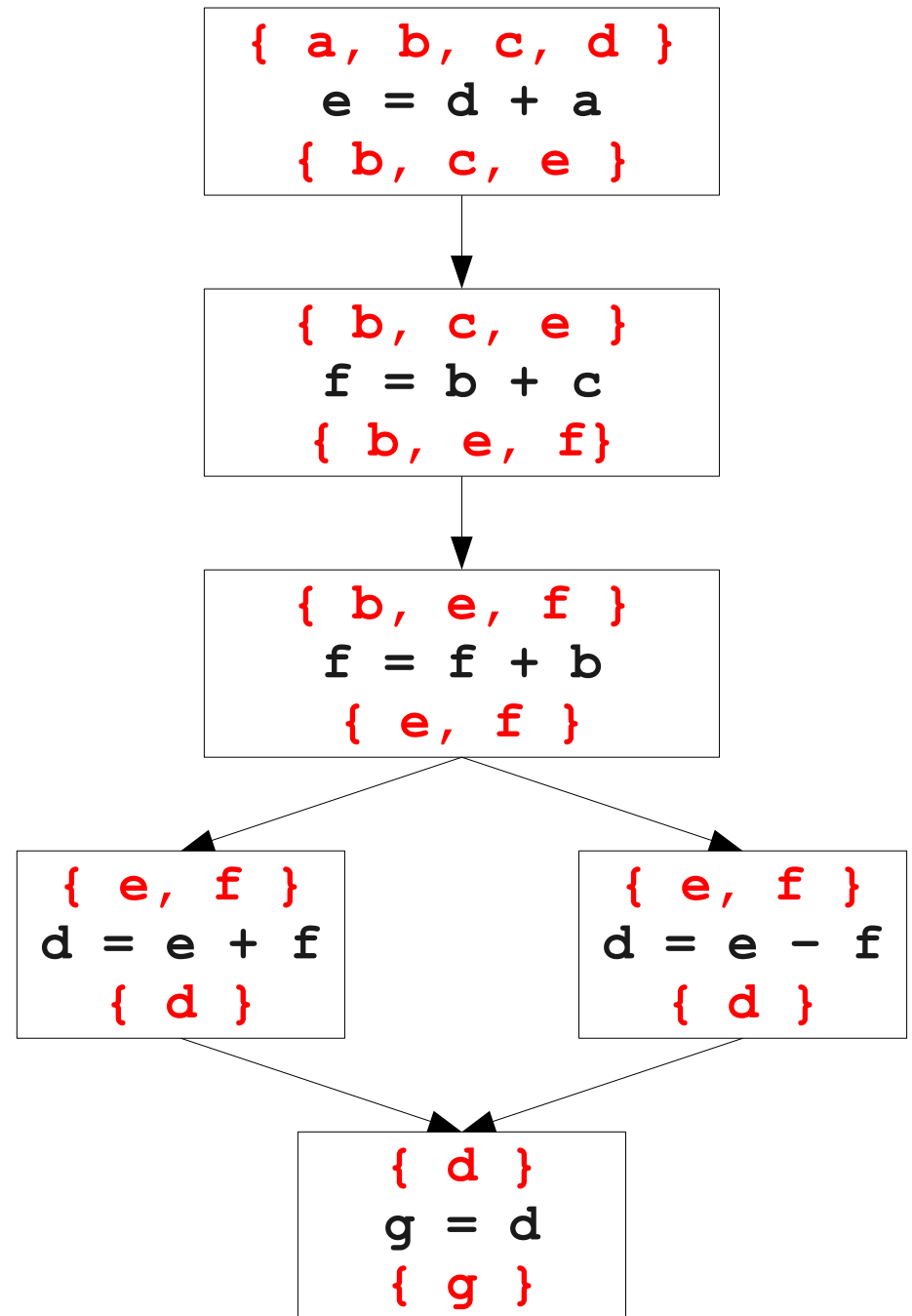
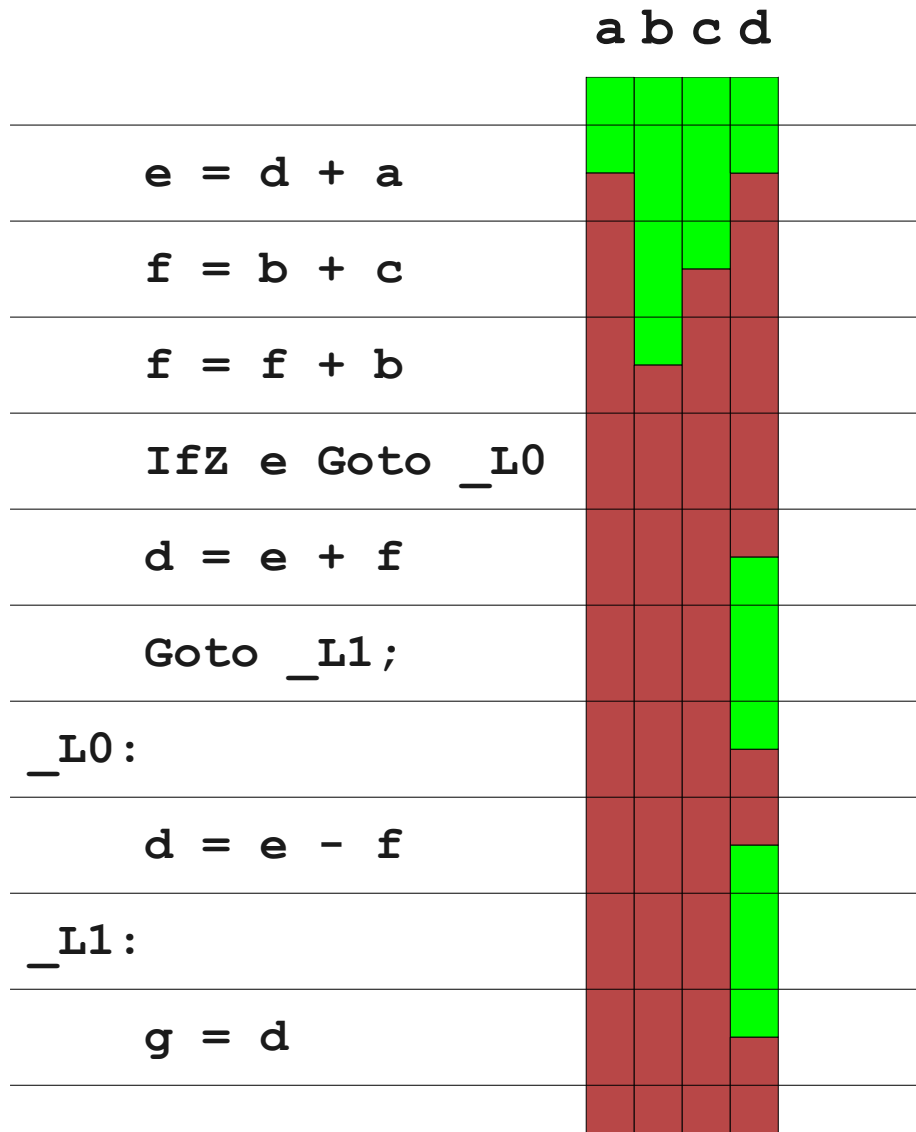
# Live Ranges and Live Intervals



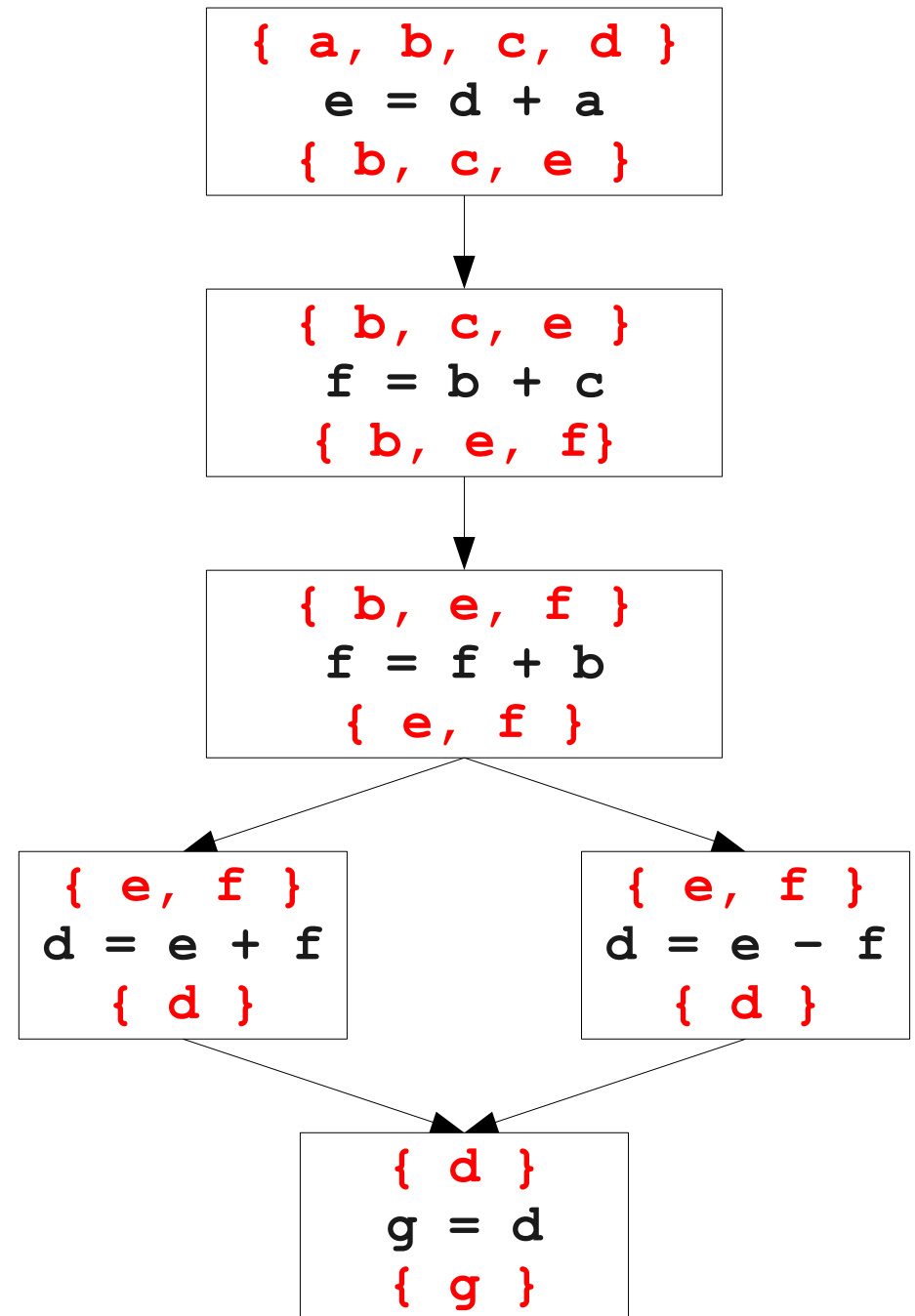
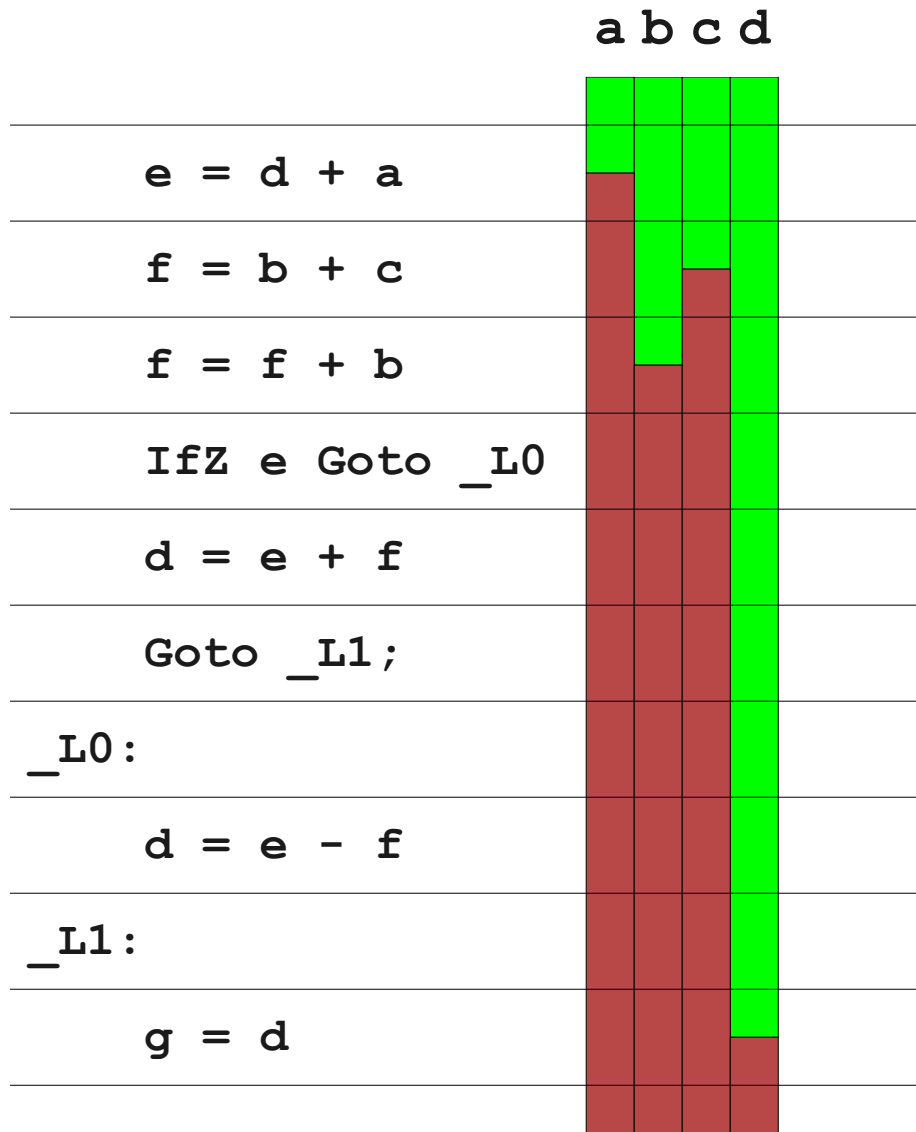
# Live Ranges and Live Intervals



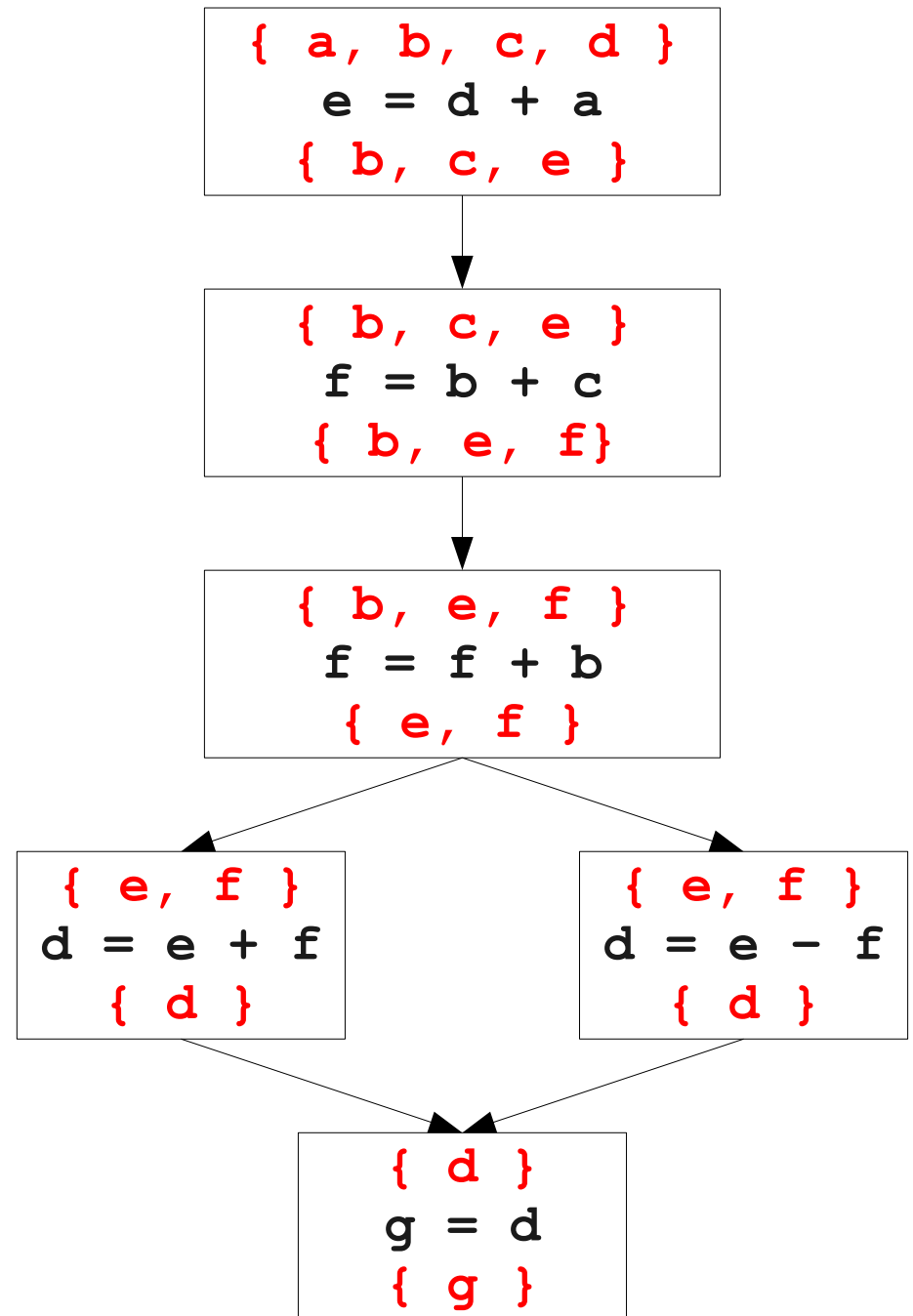
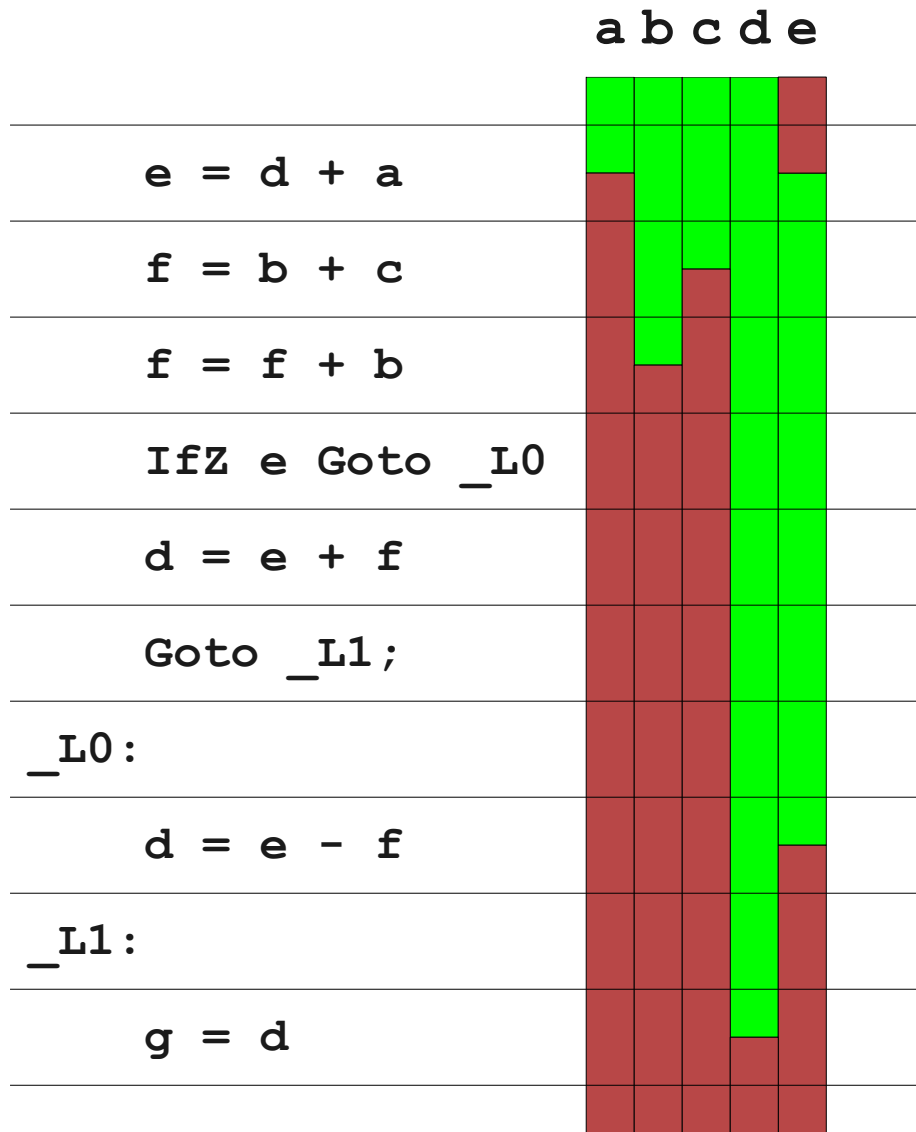
# Live Ranges and Live Intervals



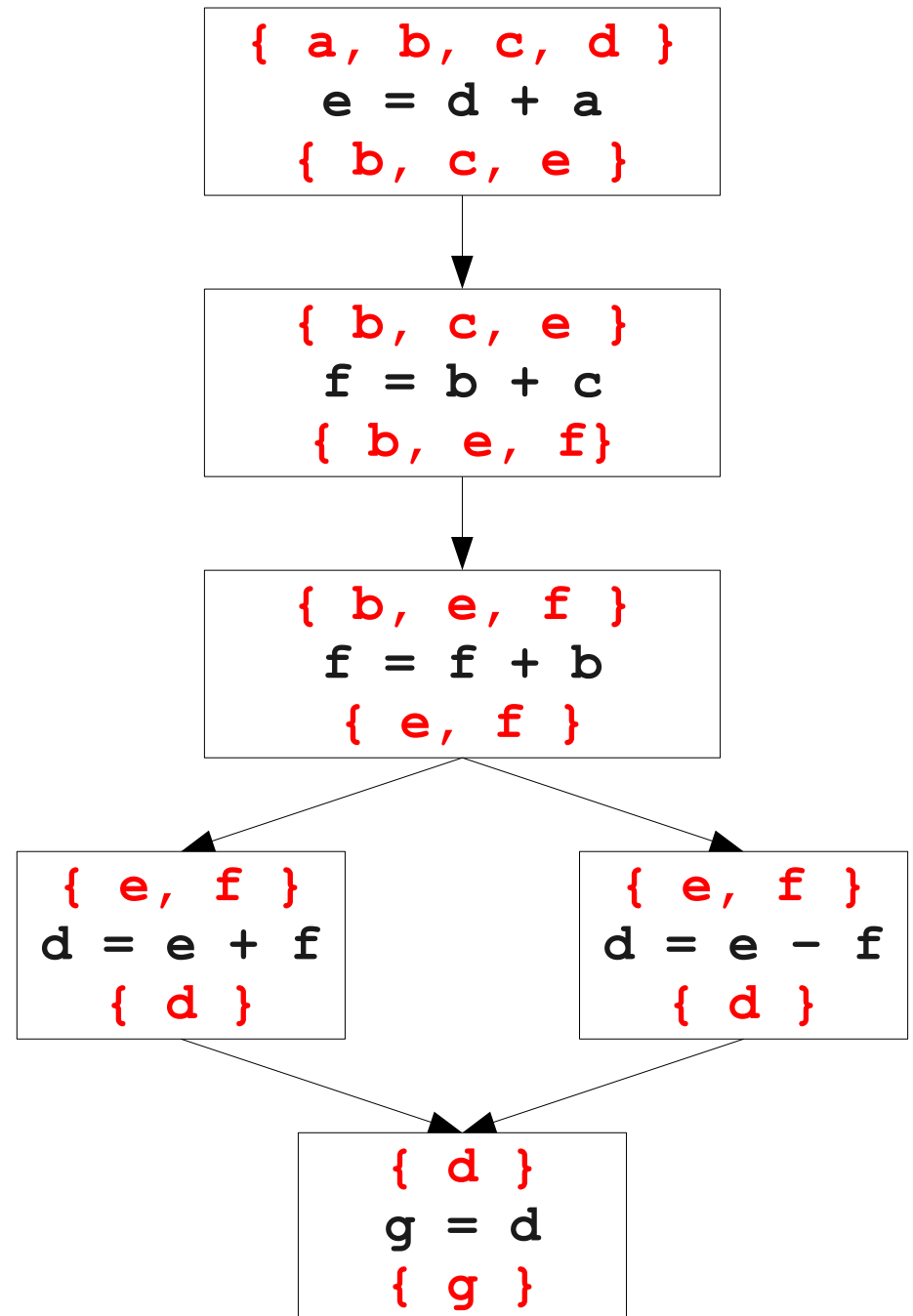
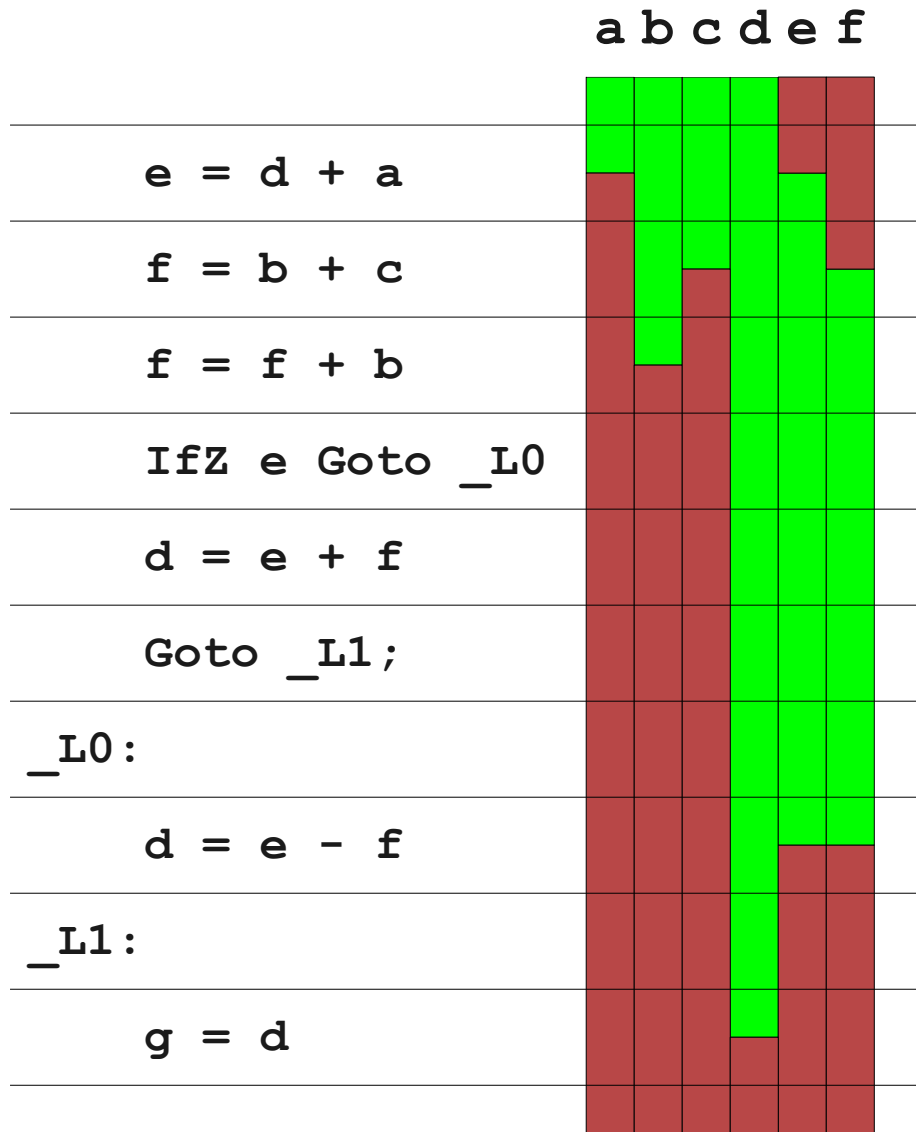
# Live Ranges and Live Intervals



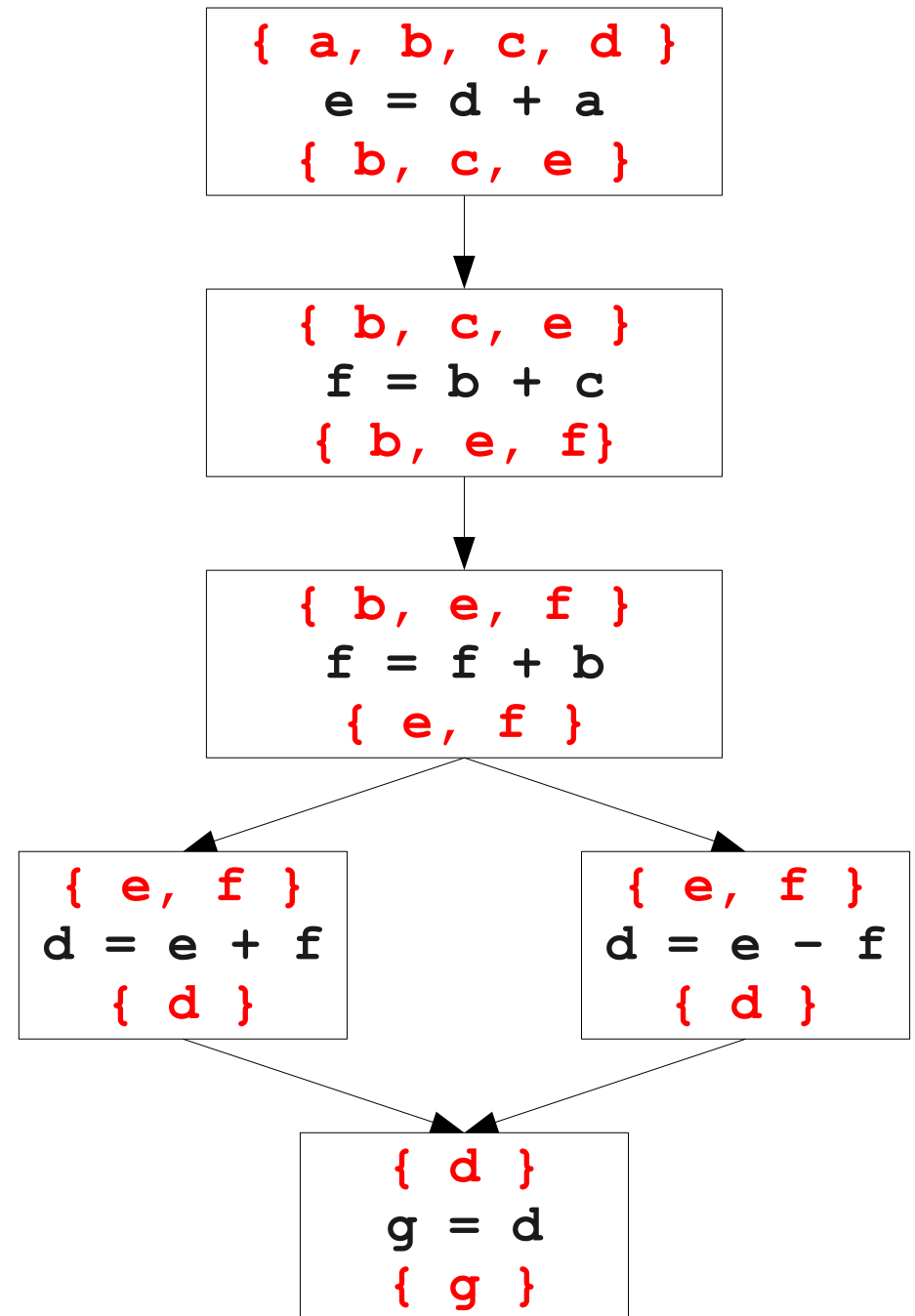
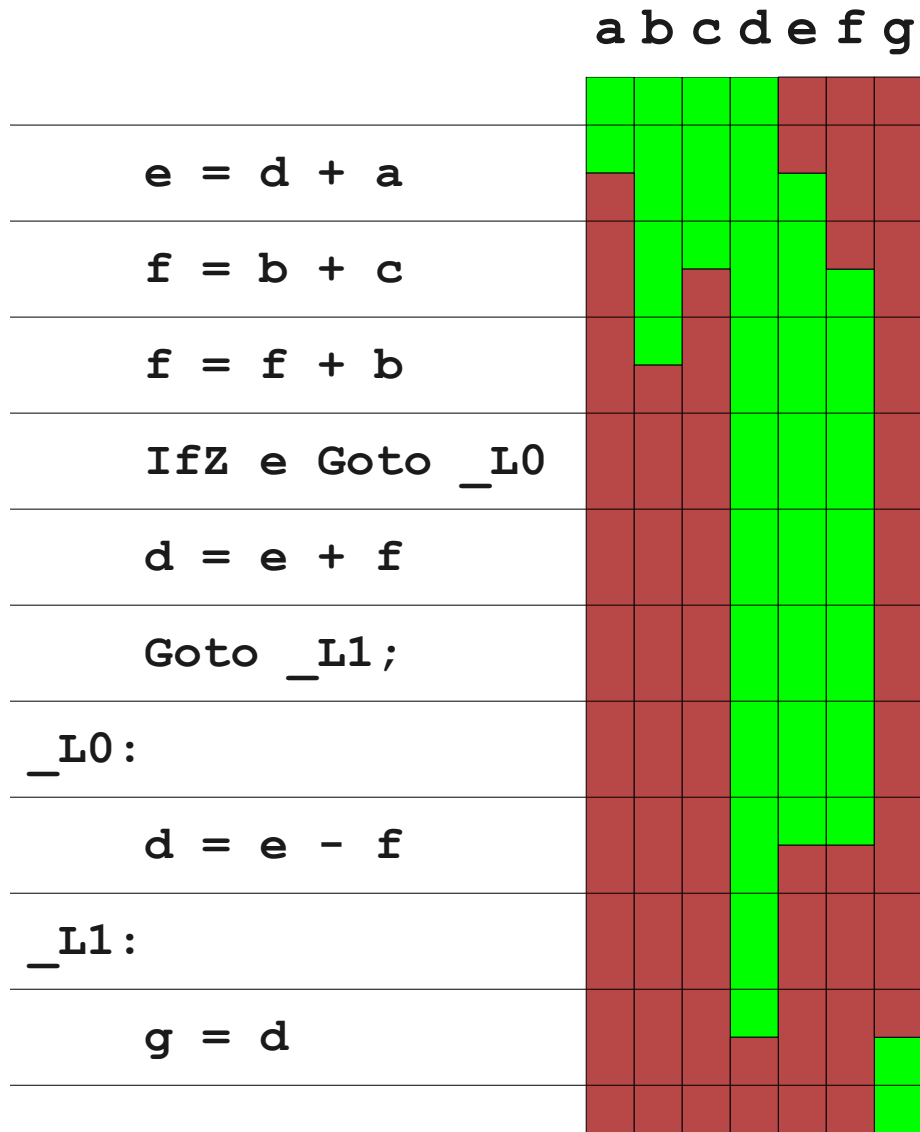
# Live Ranges and Live Intervals



# Live Ranges and Live Intervals



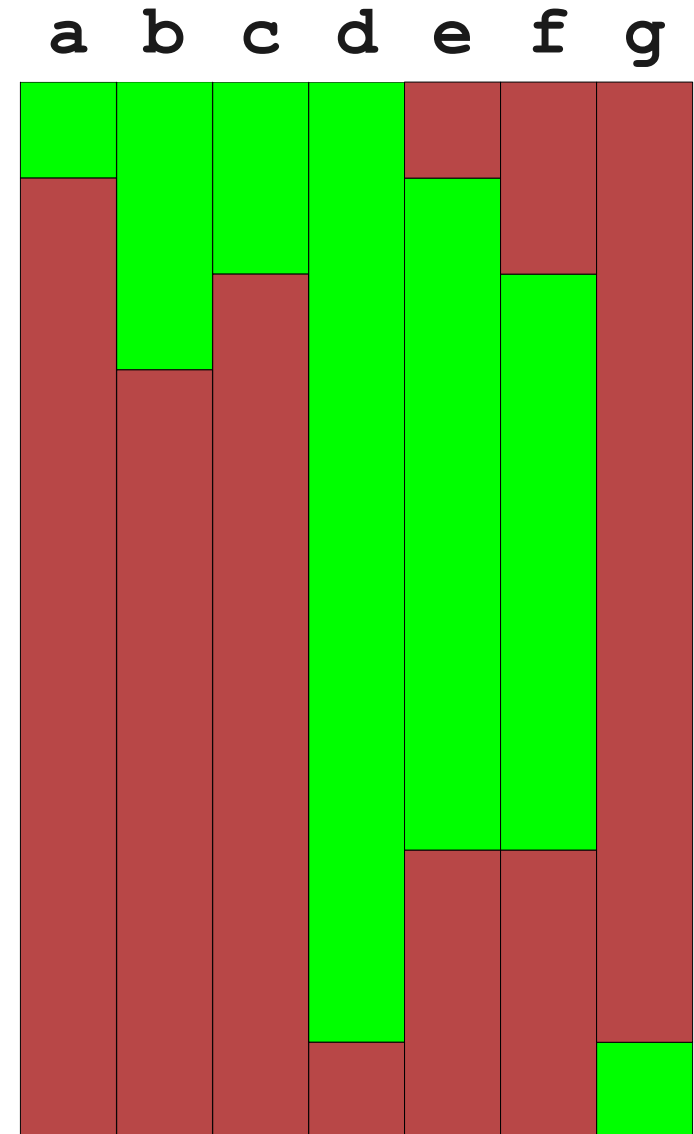
# Live Ranges and Live Intervals



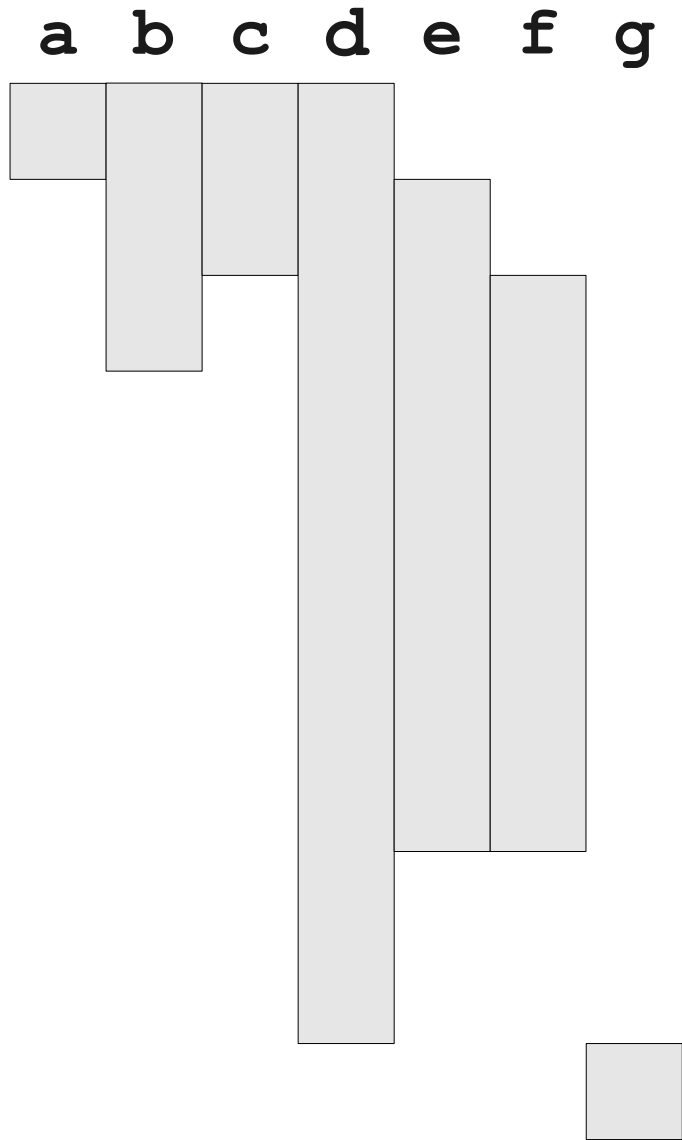


# Register Allocation with Live Intervals

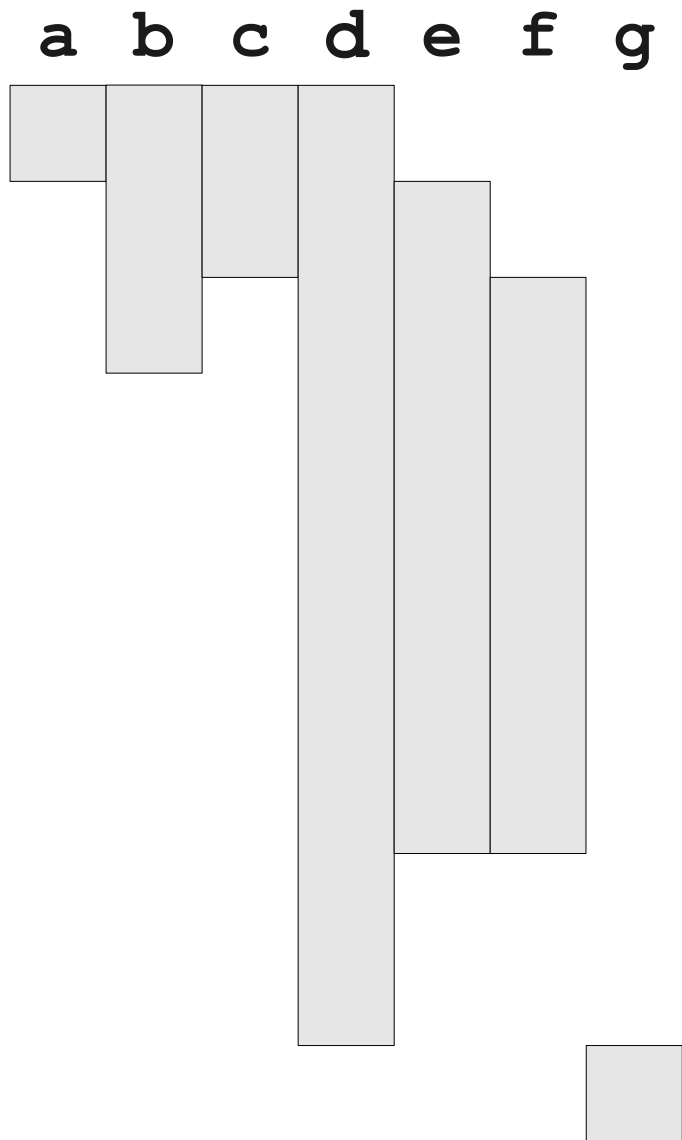
- Given the live intervals for all the variables in the program, we can allocate registers using a simple greedy algorithm.
- Idea: Track which registers are free at each point.
- When a live interval begins, give that variable a free register.
- When a live interval ends, the register is once again free.
- We can't always fit everything into a register; we'll see what do to in a minute.



# Register Allocation with Live Intervals



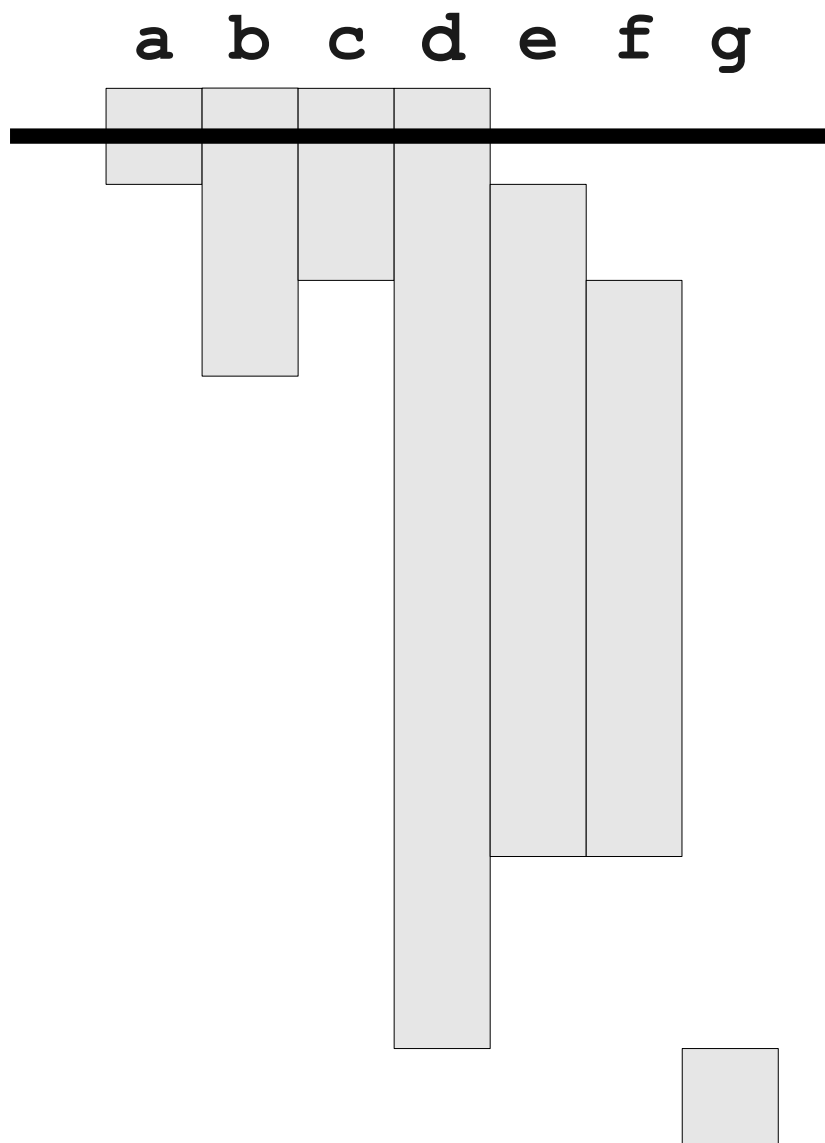
# Register Allocation with Live Intervals



**Free Registers**



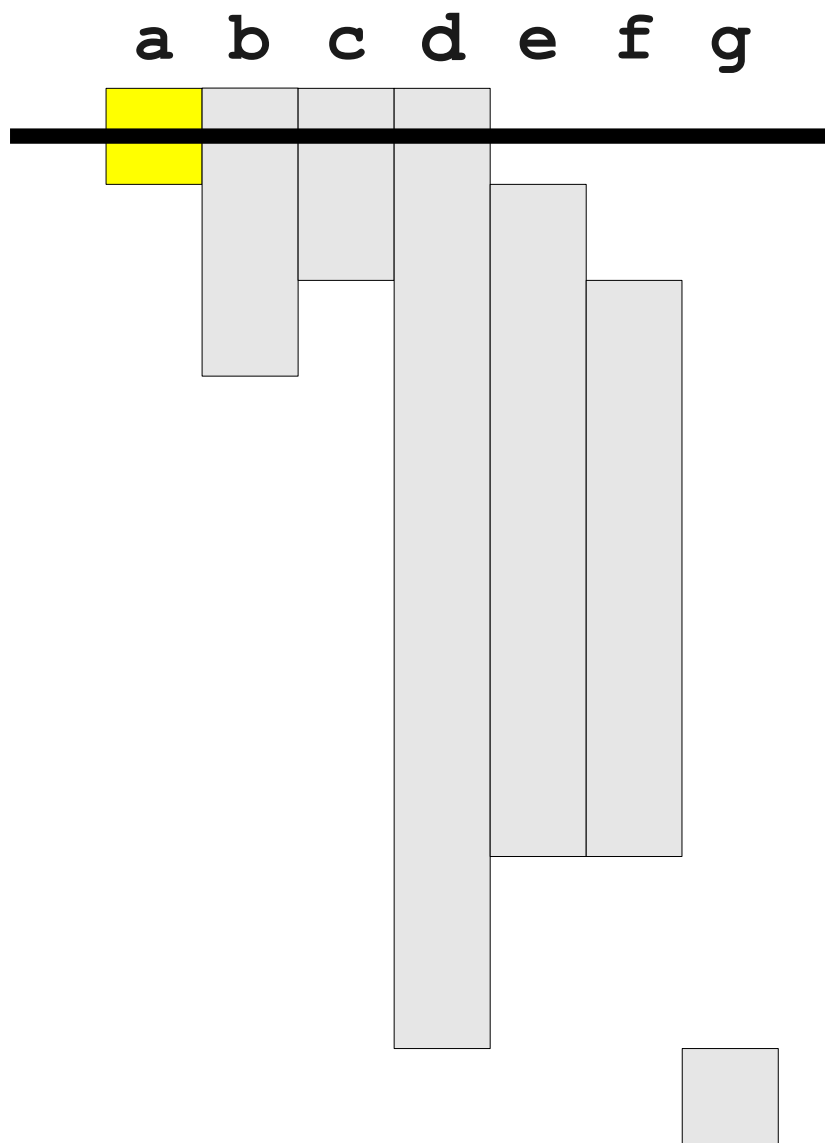
# Register Allocation with Live Intervals



**Free Registers**



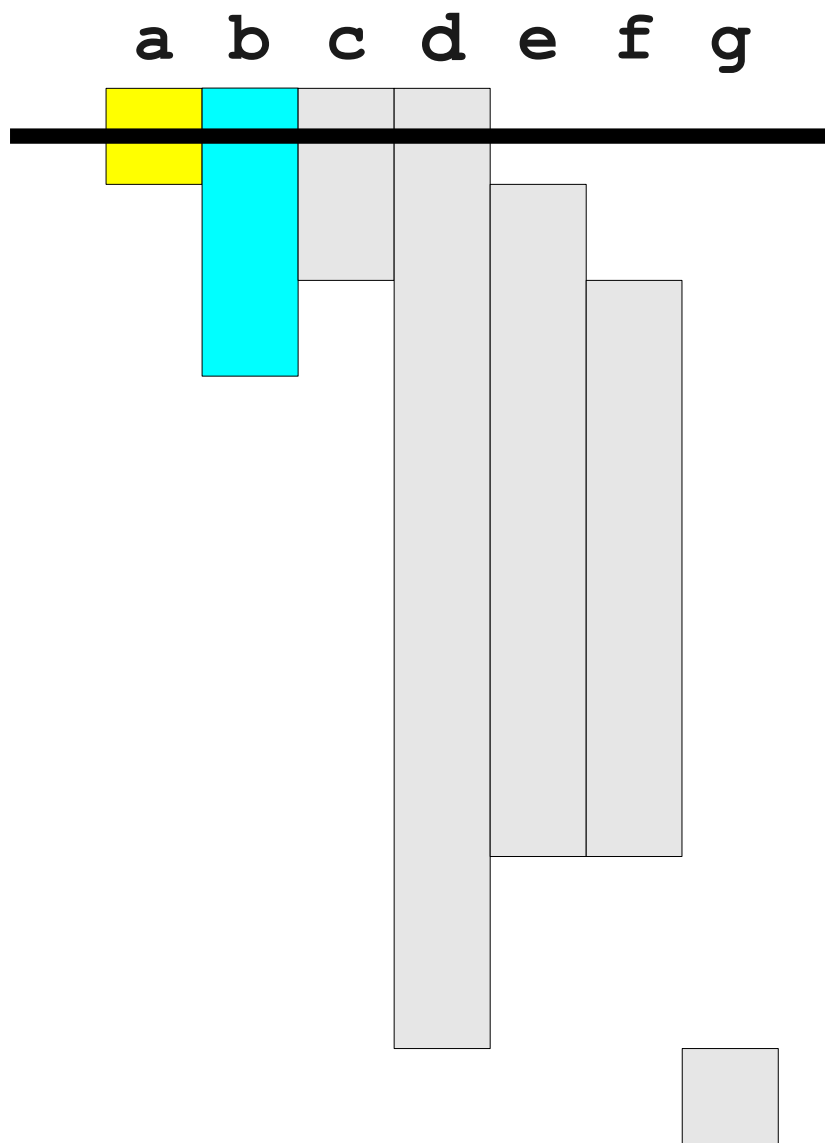
# Register Allocation with Live Intervals



## Free Registers



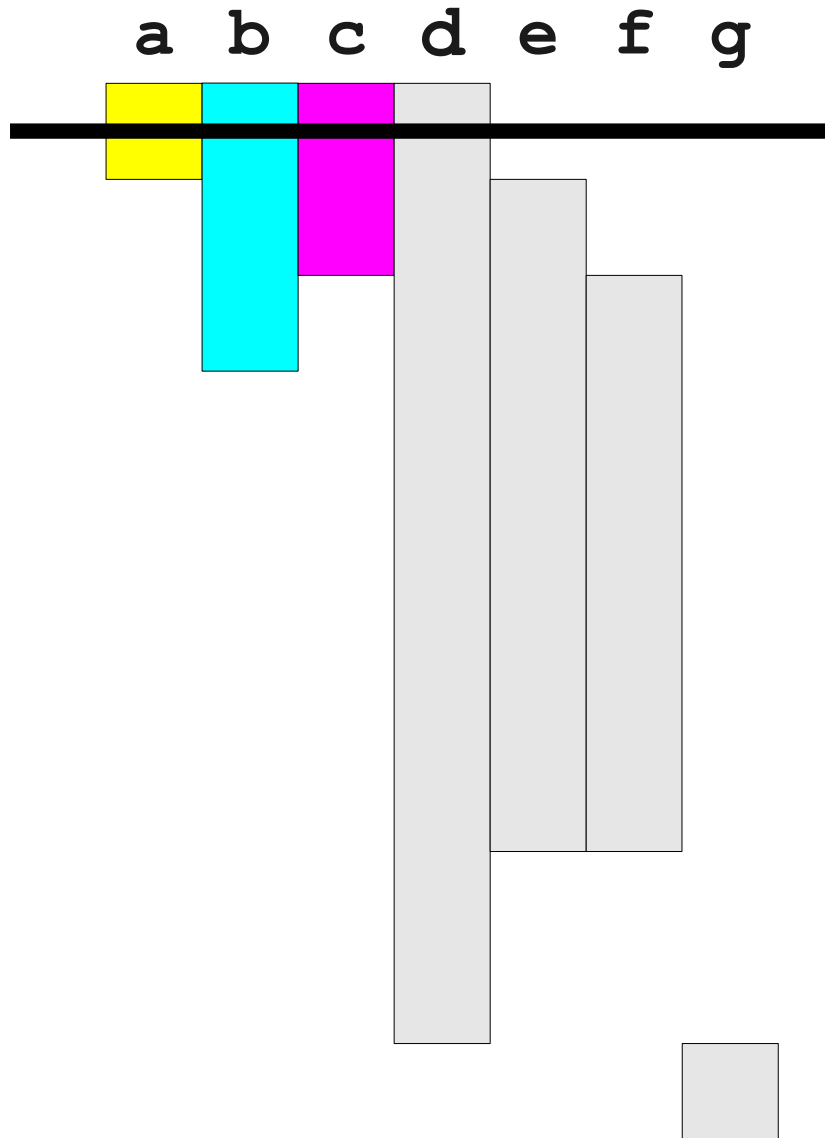
# Register Allocation with Live Intervals



## Free Registers



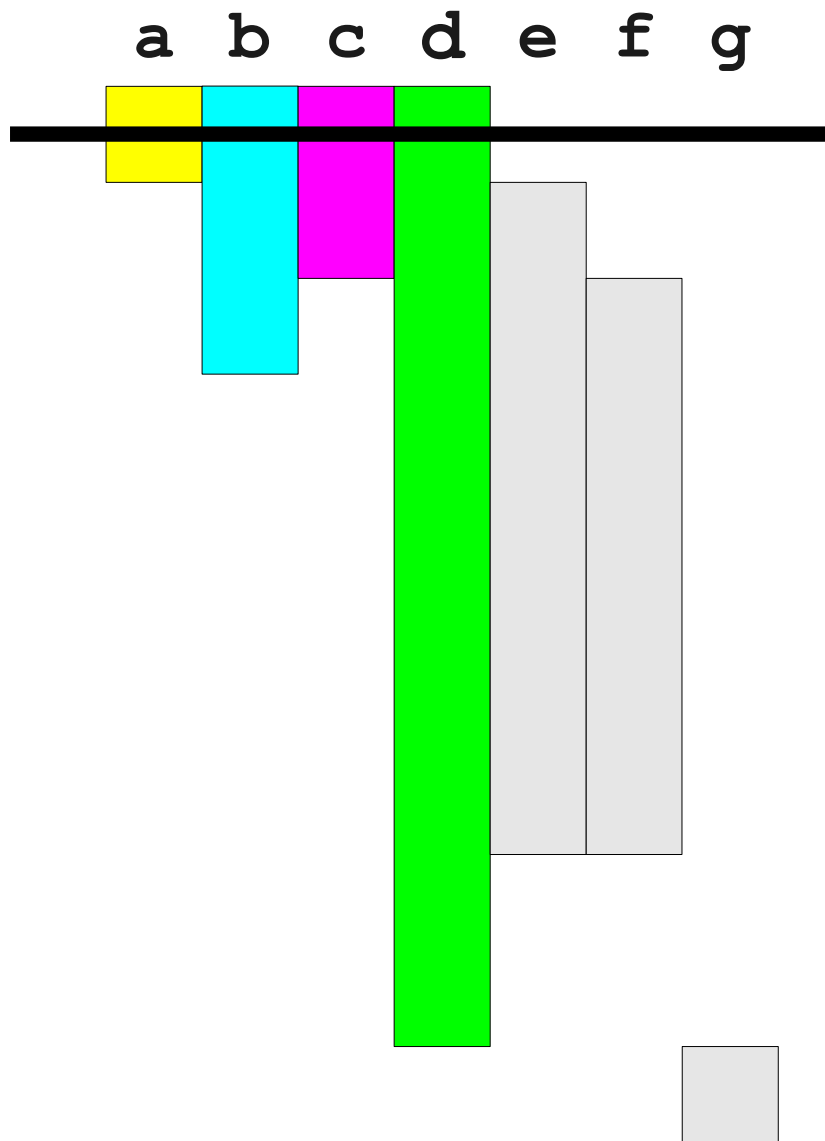
# Register Allocation with Live Intervals



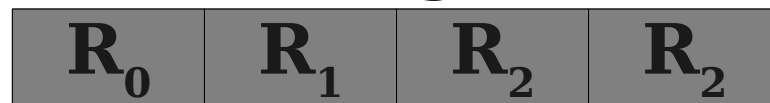
## Free Registers



# Register Allocation with Live Intervals

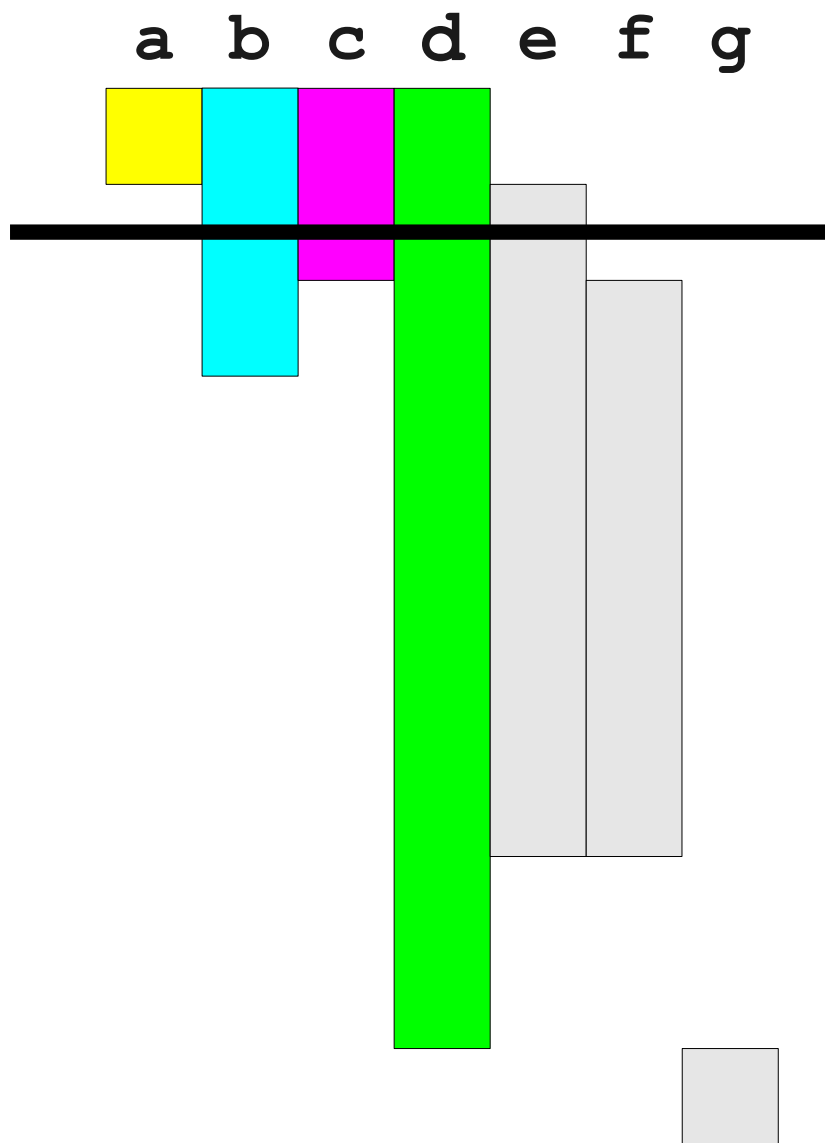


## Free Registers





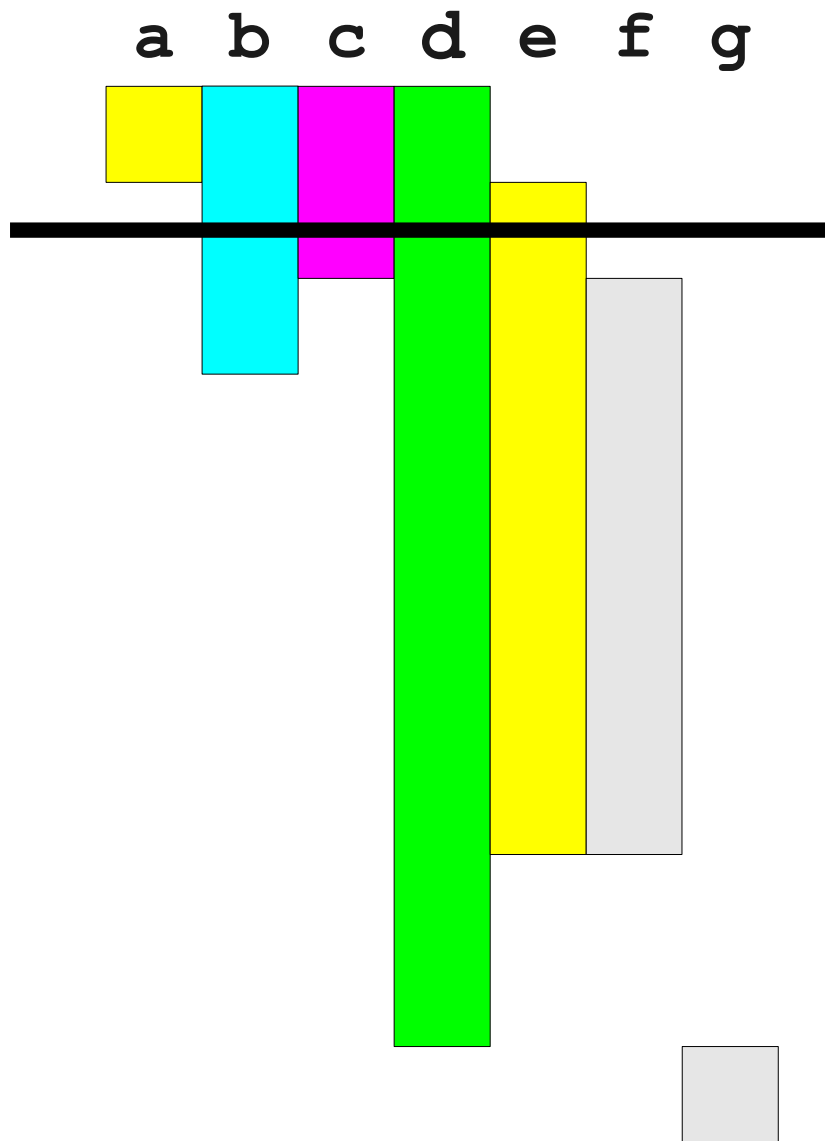
# Register Allocation with Live Intervals



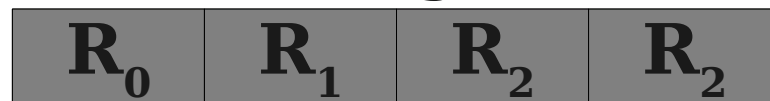
## Free Registers



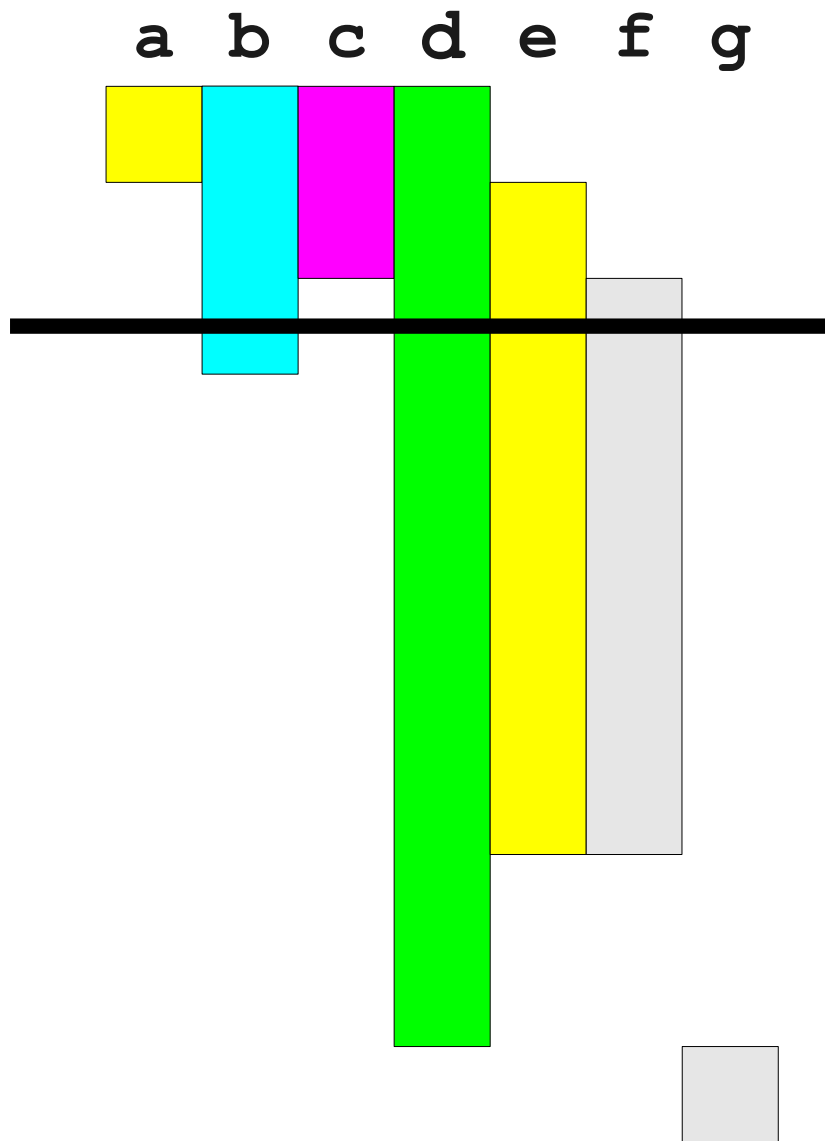
# Register Allocation with Live Intervals



## Free Registers



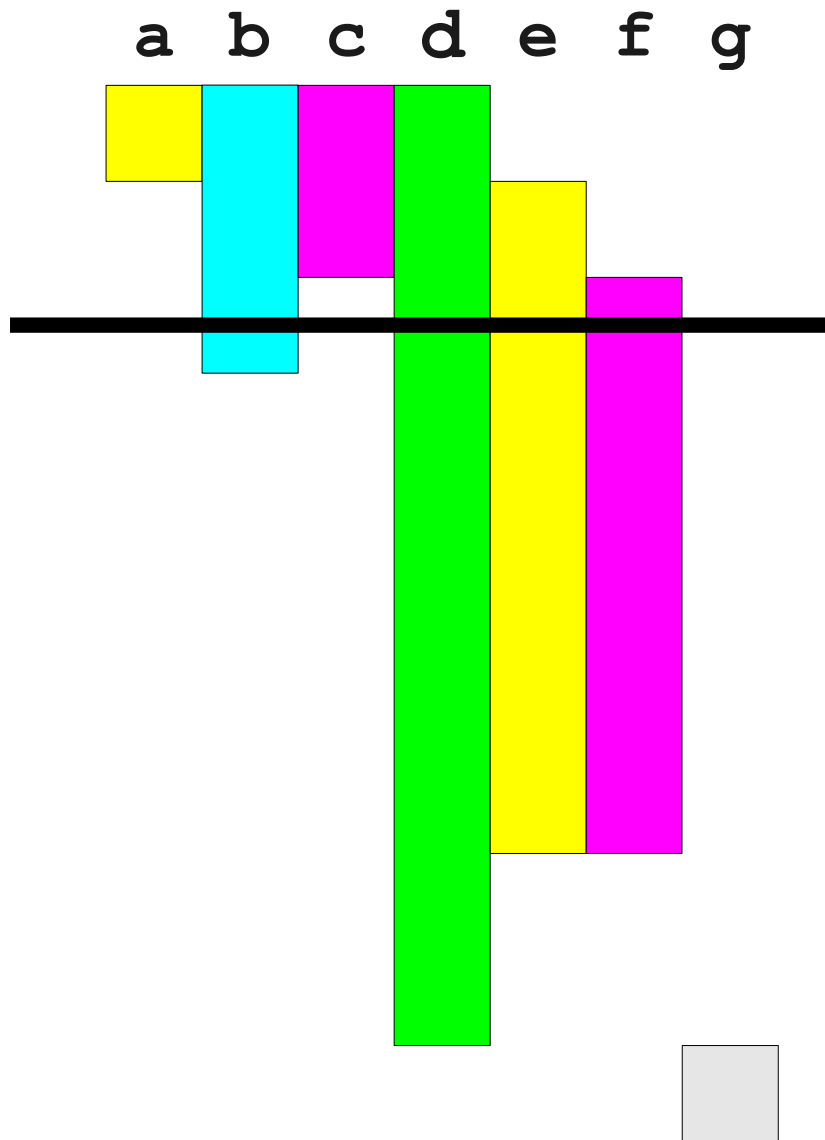
# Register Allocation with Live Intervals



## Free Registers



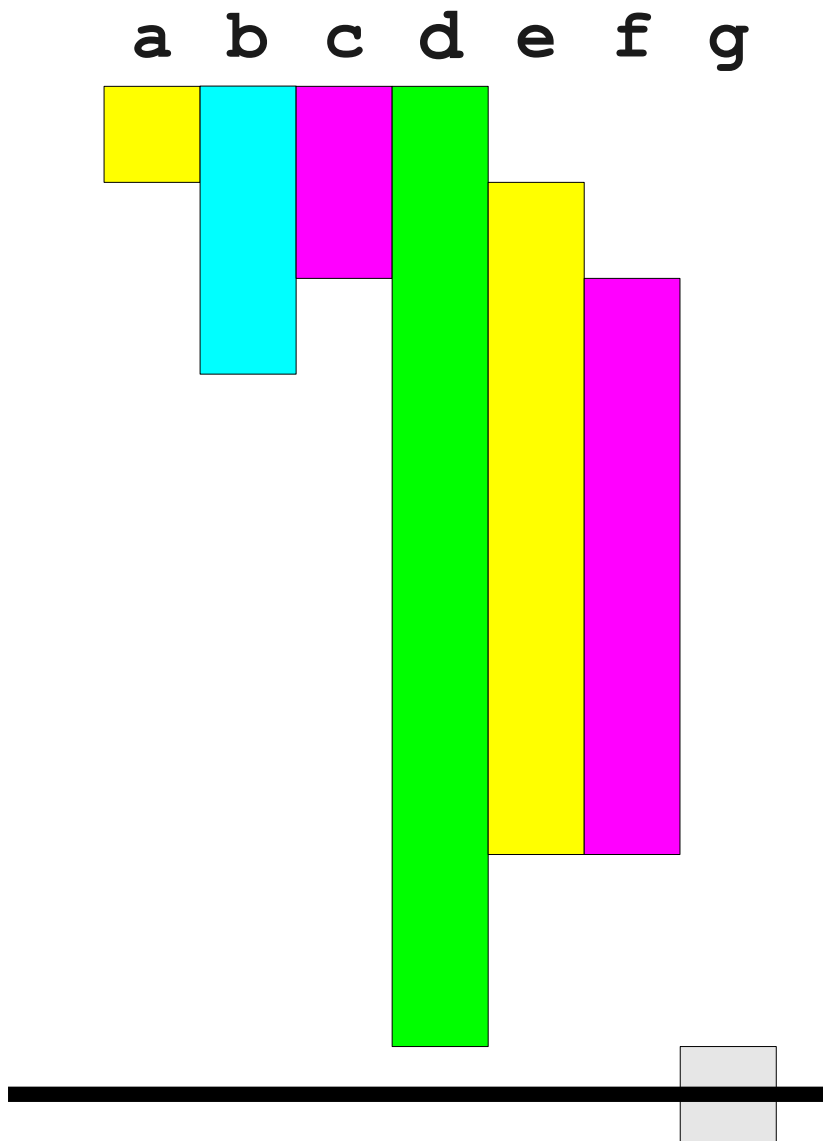
# Register Allocation with Live Intervals



## Free Registers



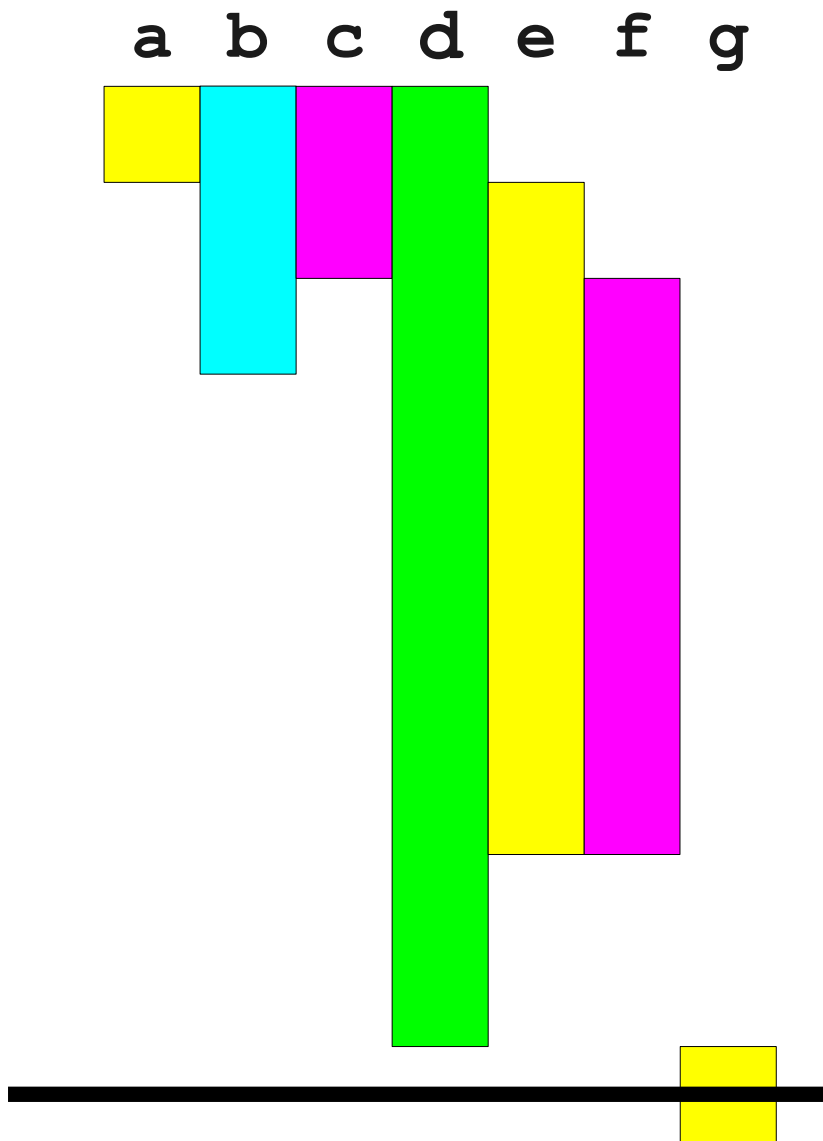
# Register Allocation with Live Intervals



## Free Registers



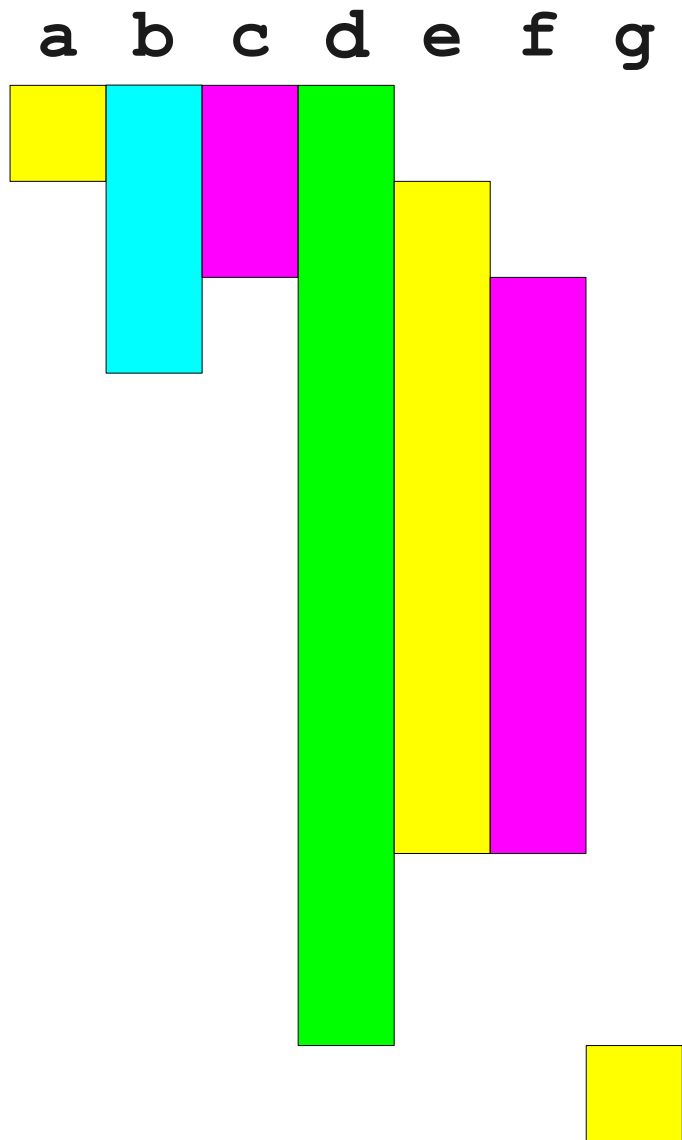
# Register Allocation with Live Intervals



## Free Registers



# Register Allocation with Live Intervals



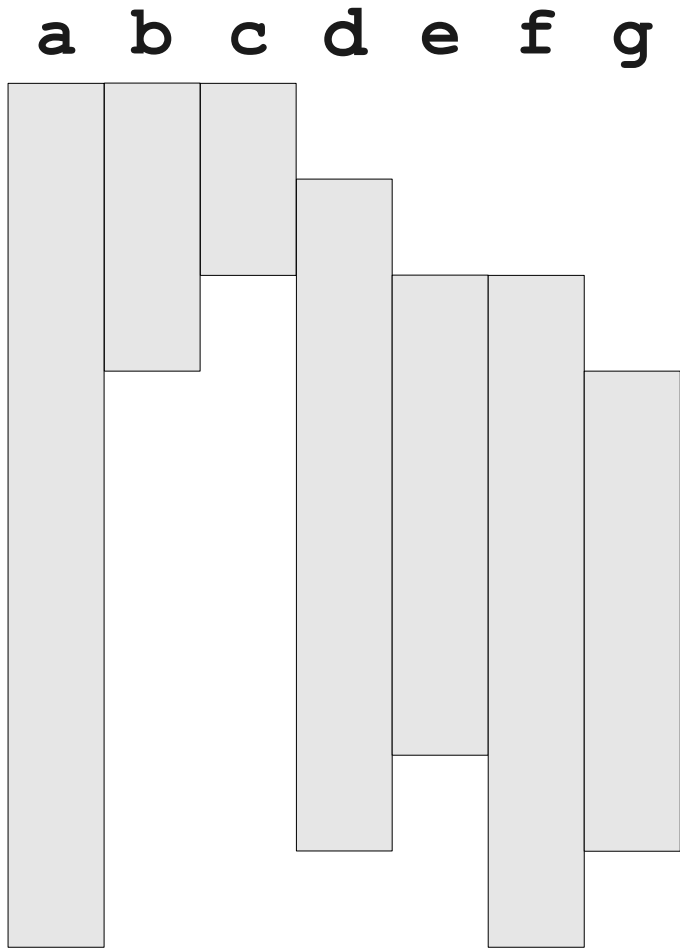
## Free Registers



# Another Example



# Another Example



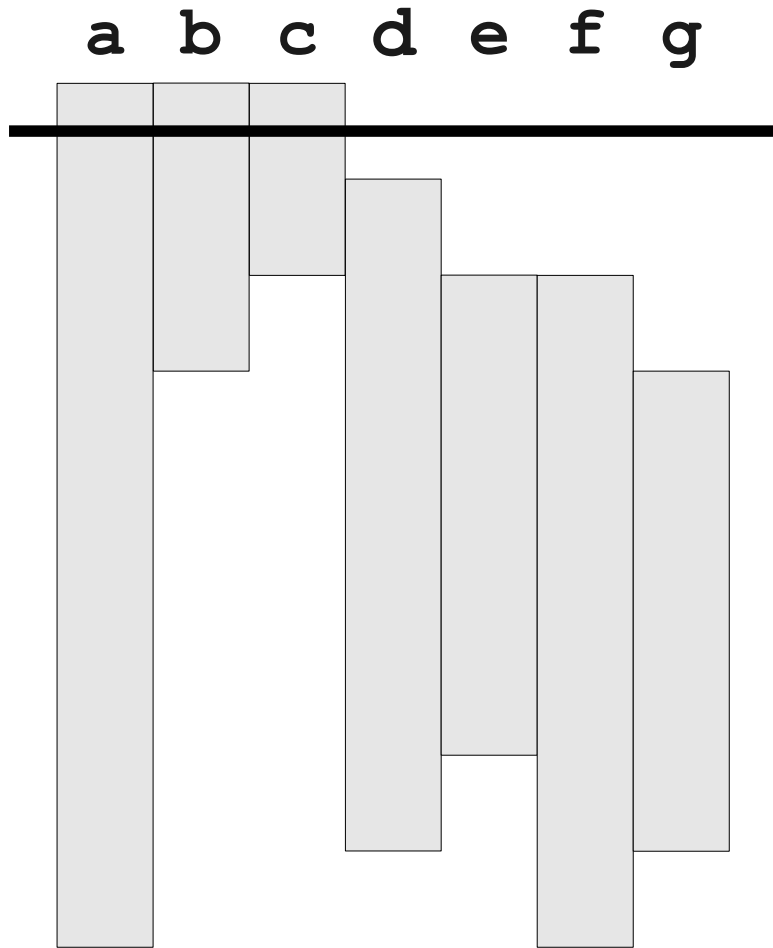
# Another Example



**Free Registers**



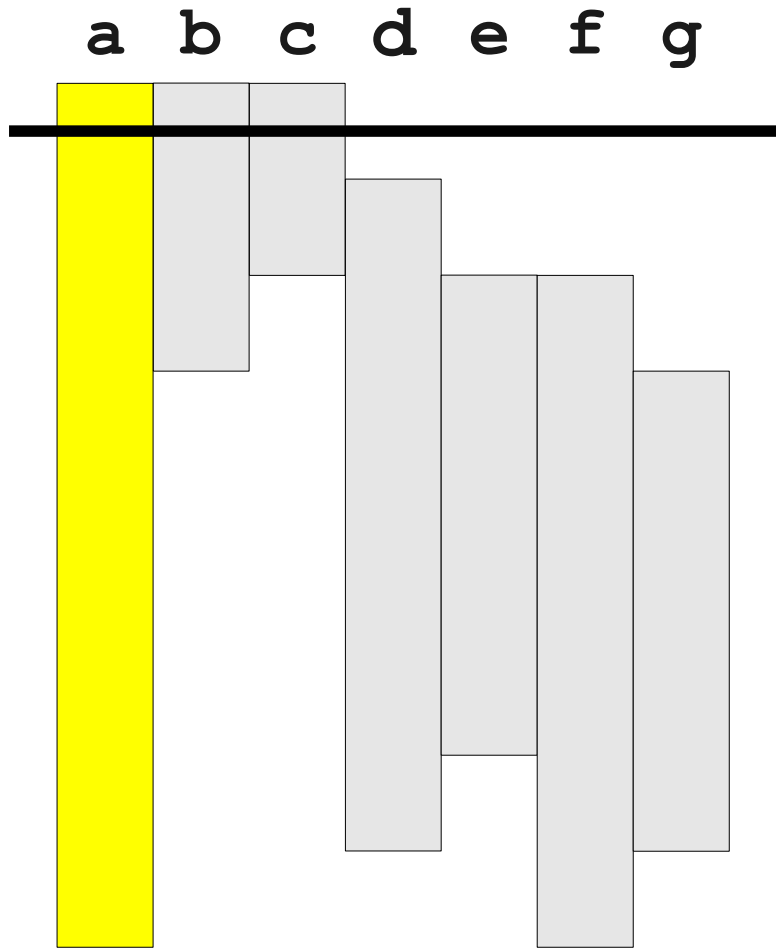
# Another Example



**Free Registers**



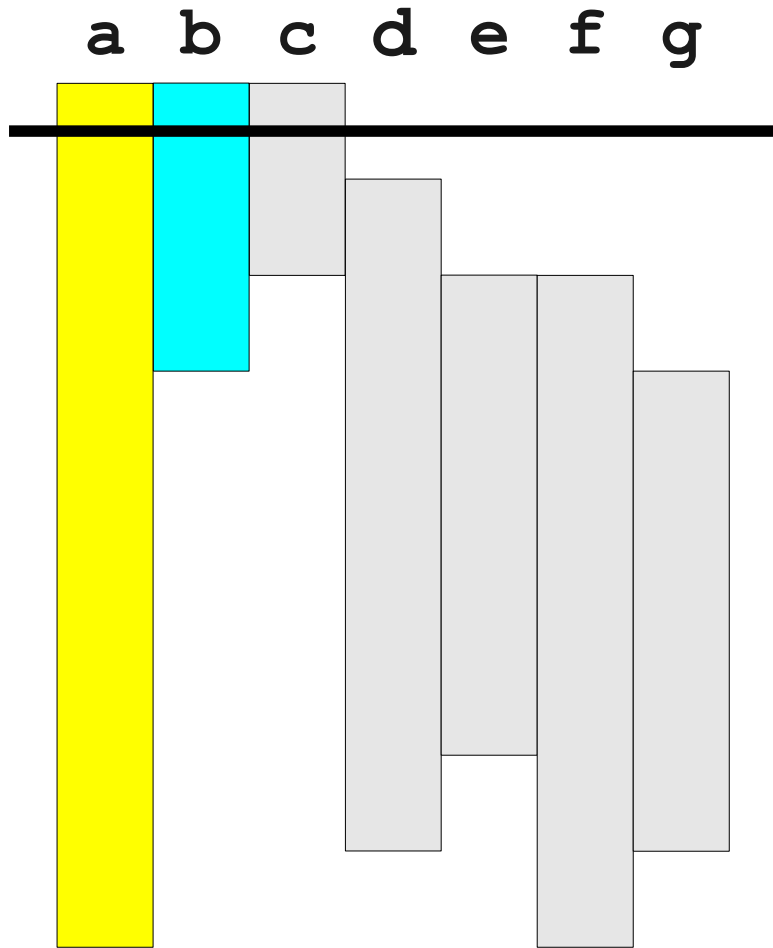
# Another Example



**Free Registers**



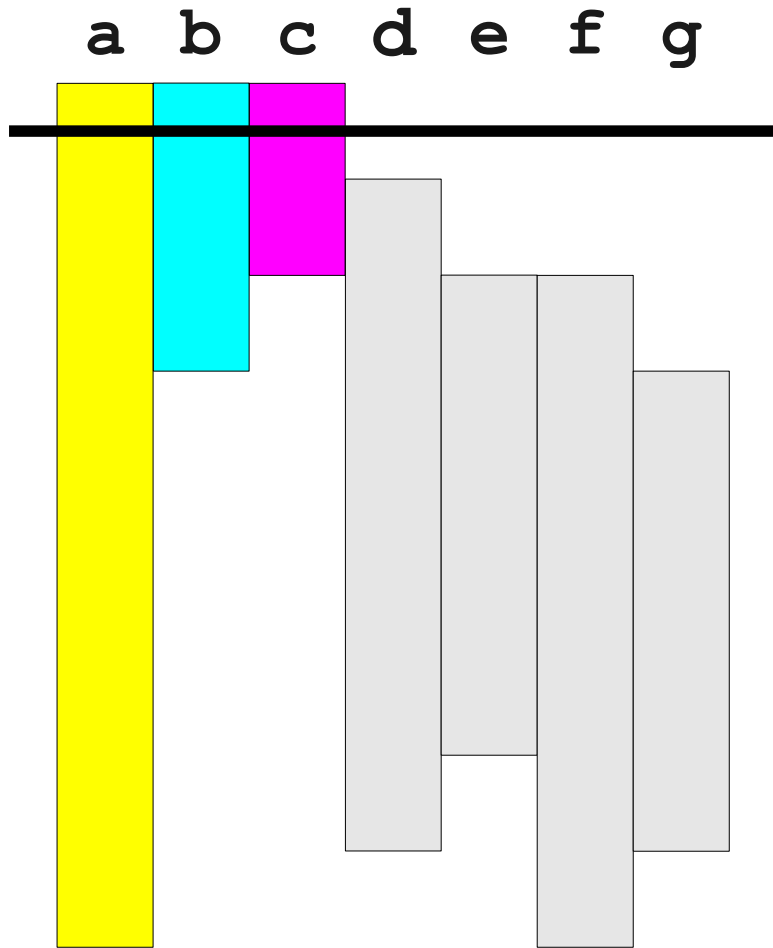
# Another Example



**Free Registers**



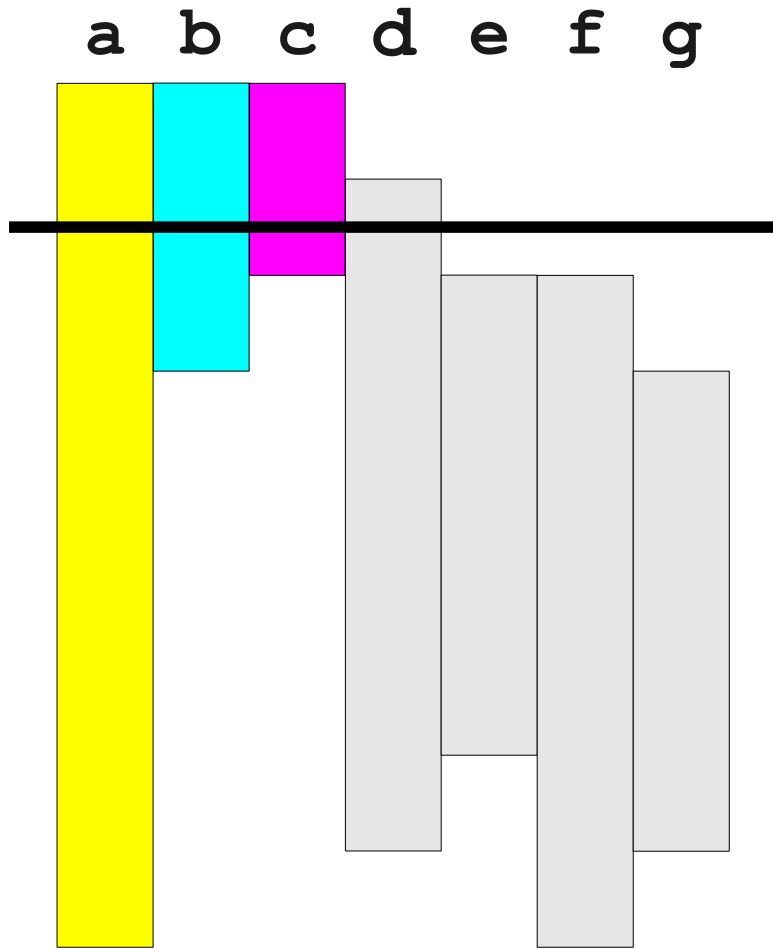
# Another Example



**Free Registers**



# Another Example



**Free Registers**



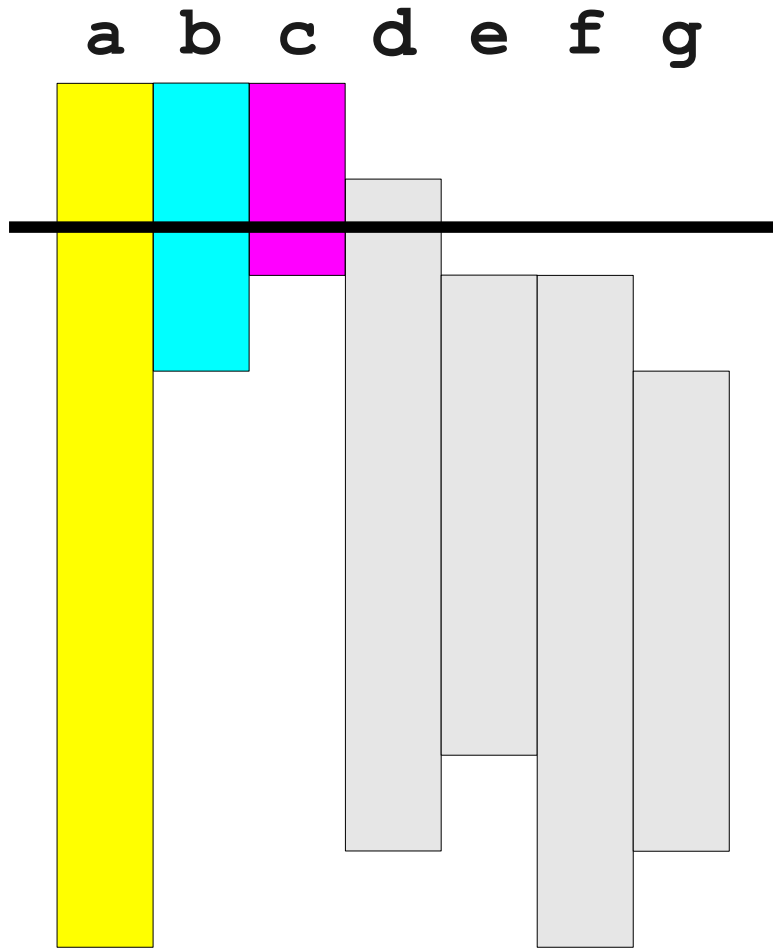
What do we do  
now?

# Register Spilling

- If a register cannot be found for a variable  $v$ , we may need to **spill** a variable.
- When a variable is spilled, it is stored in memory rather than a register.
- When we need a register for the spilled variable:
  - Evict some existing register to memory.
  - Load the variable into the register.
  - When done, write the register back to memory and reload the register with its original value.
- Spilling is slow, but sometimes necessary.



# Another Example

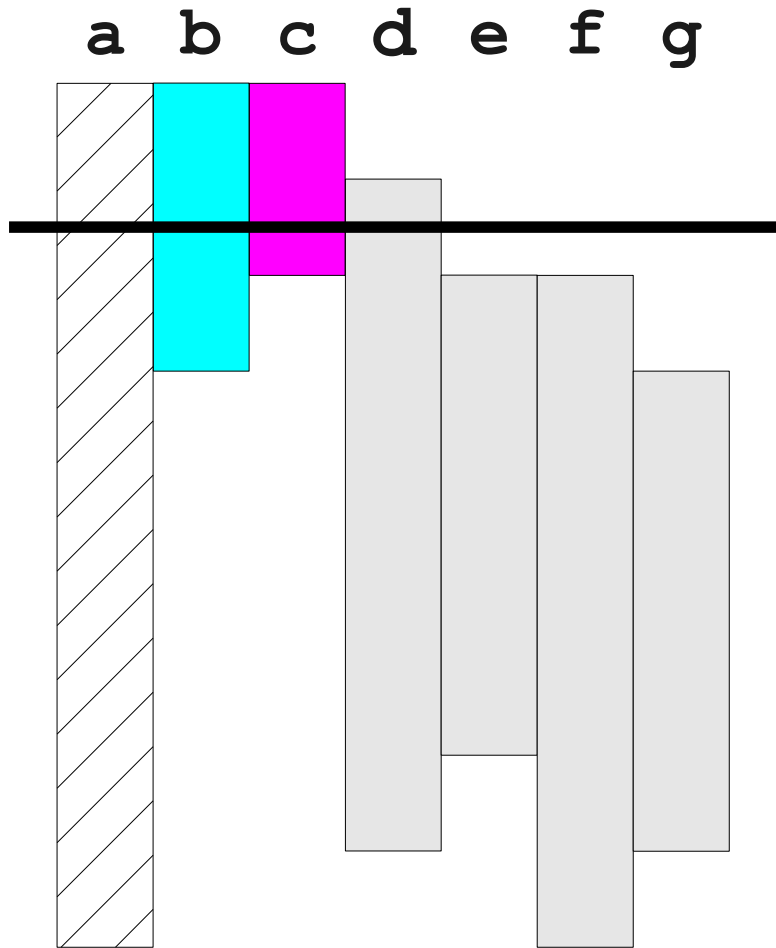


## Free Registers



What do we do  
now?

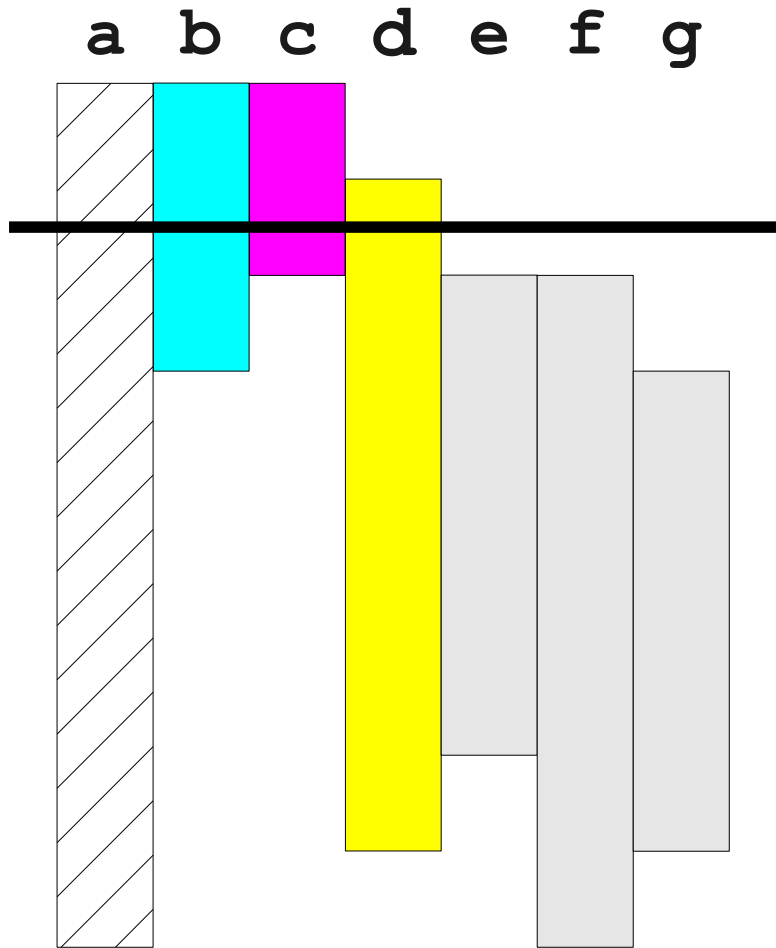
# Another Example



**Free Registers**



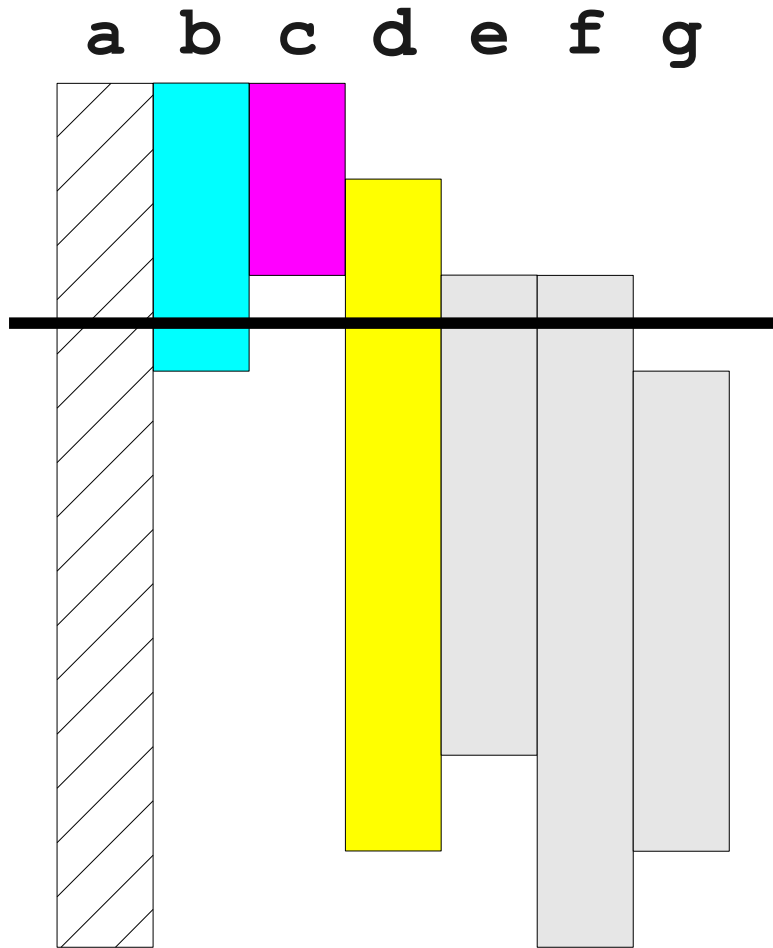
# Another Example



**Free Registers**



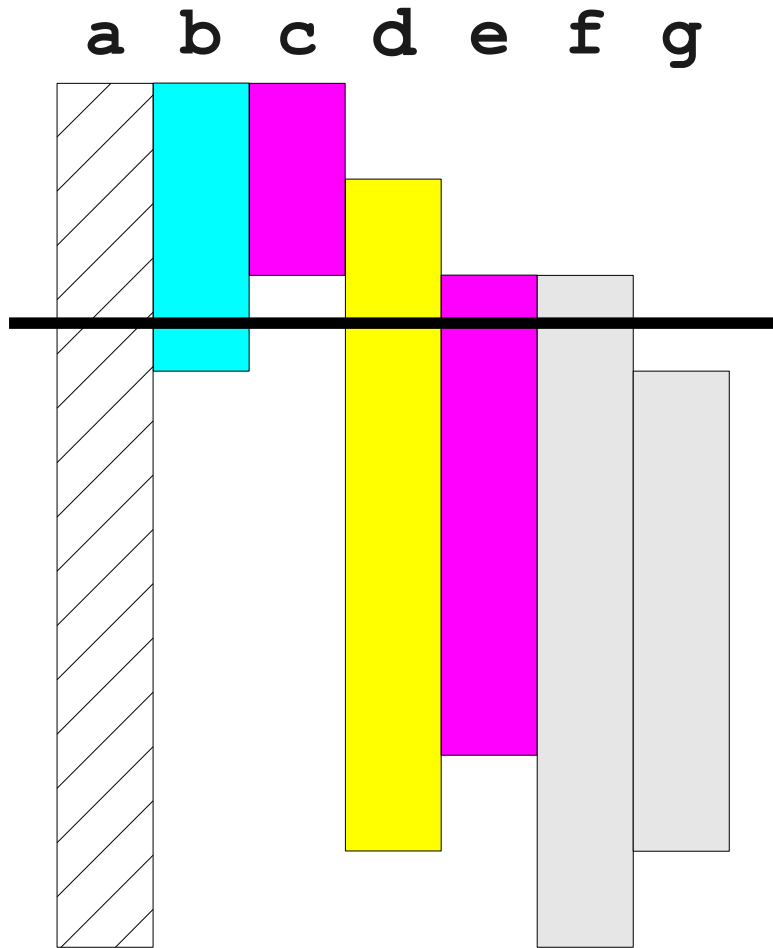
# Another Example



**Free Registers**



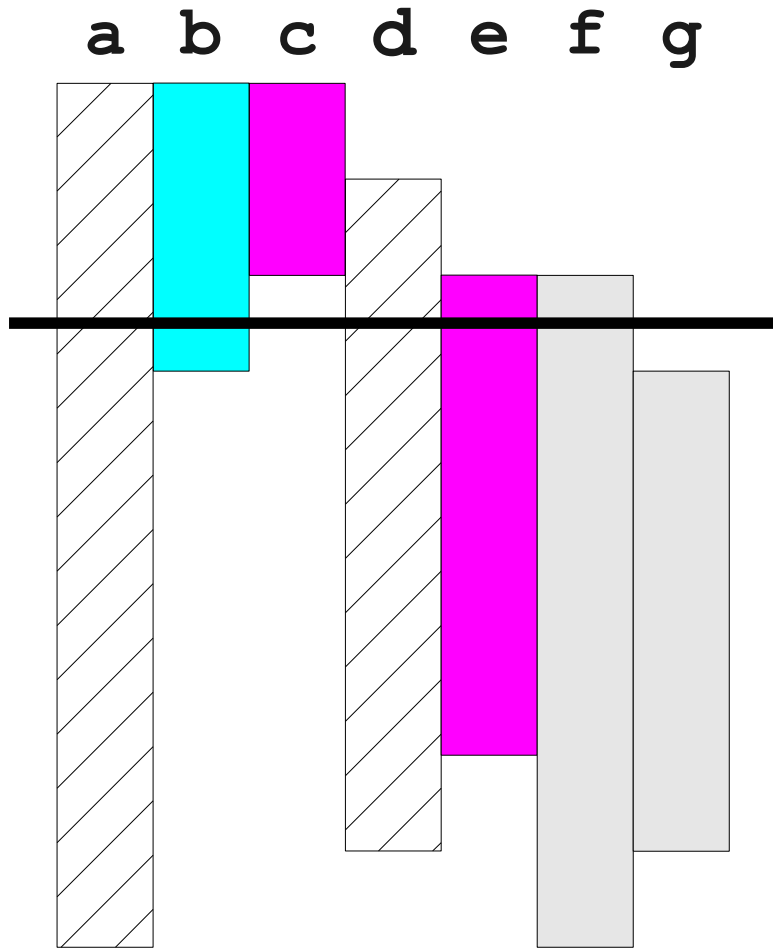
# Another Example



**Free Registers**



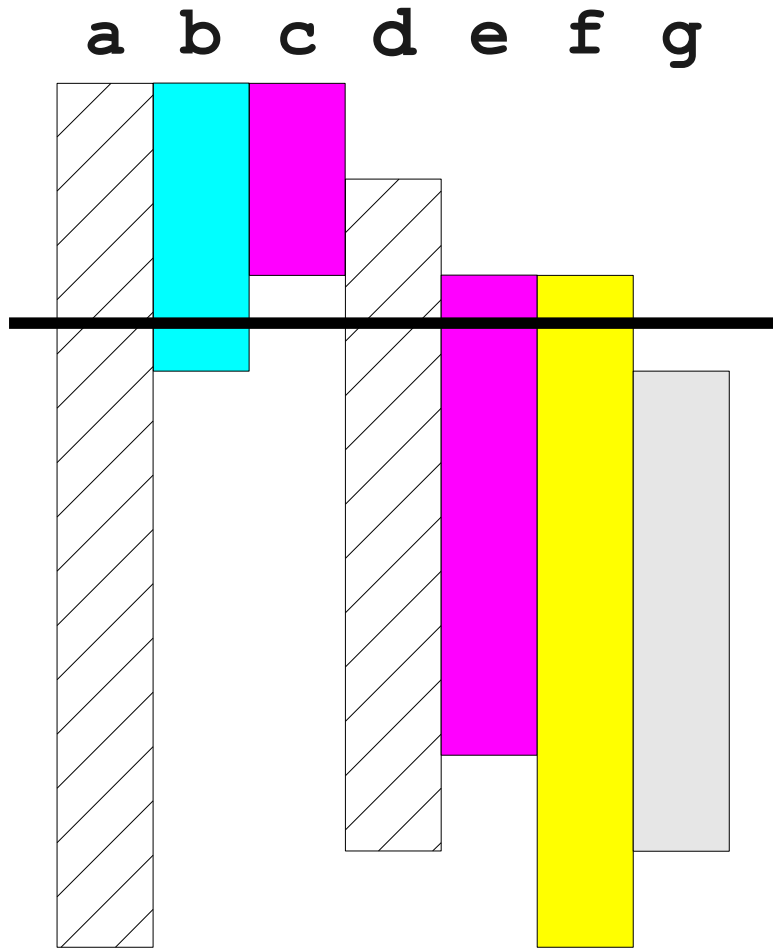
# Another Example



**Free Registers**



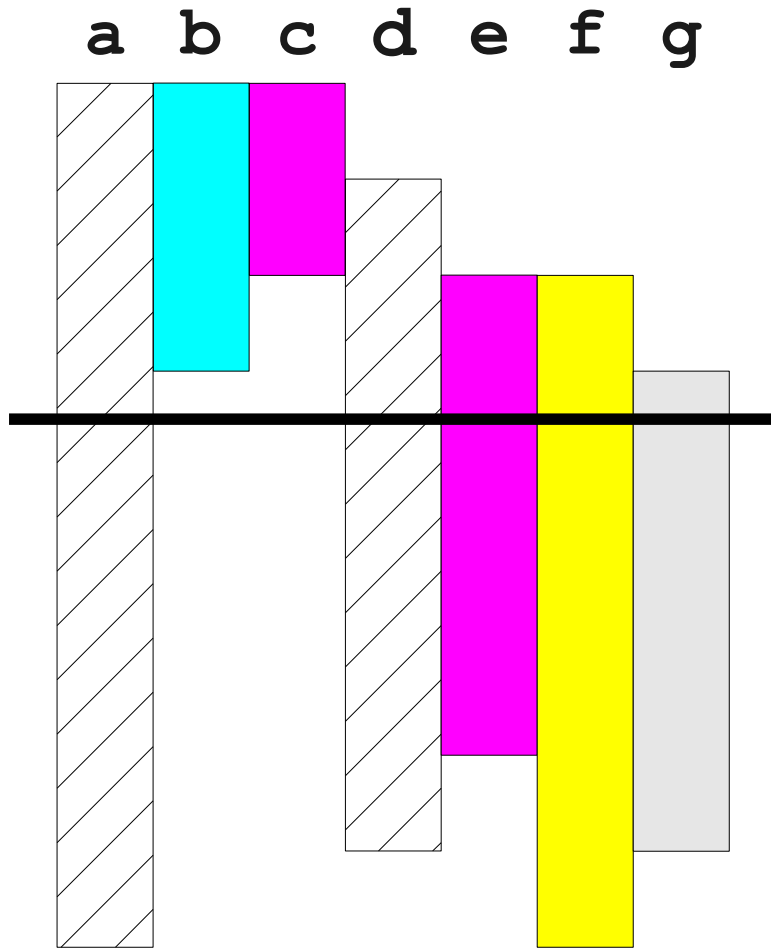
# Another Example



**Free Registers**



# Another Example

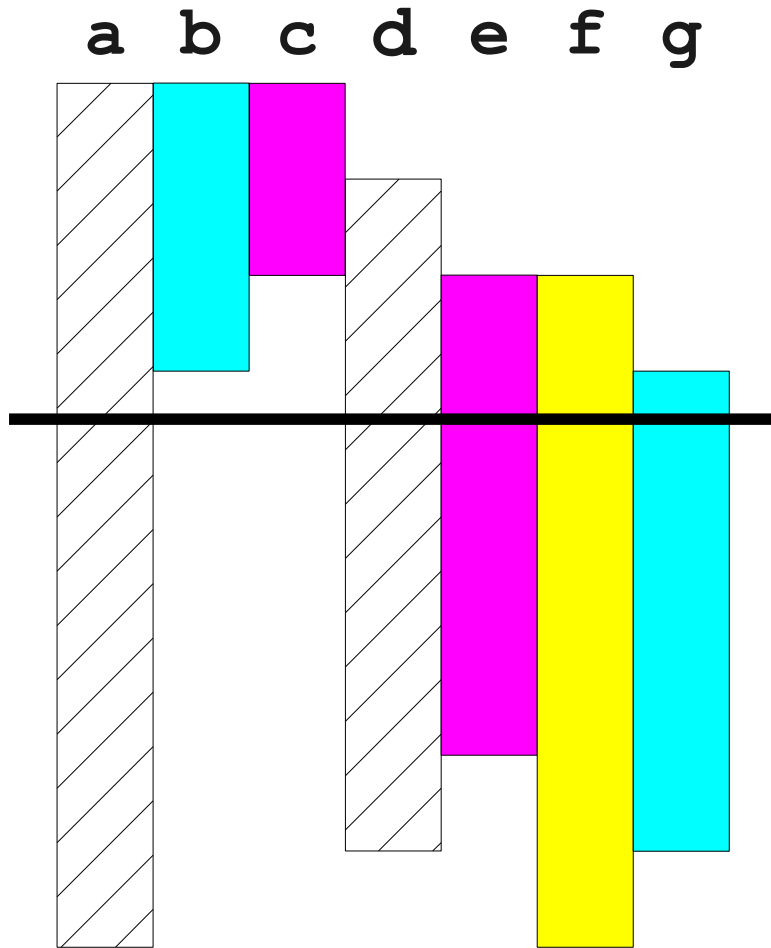


**Free Registers**





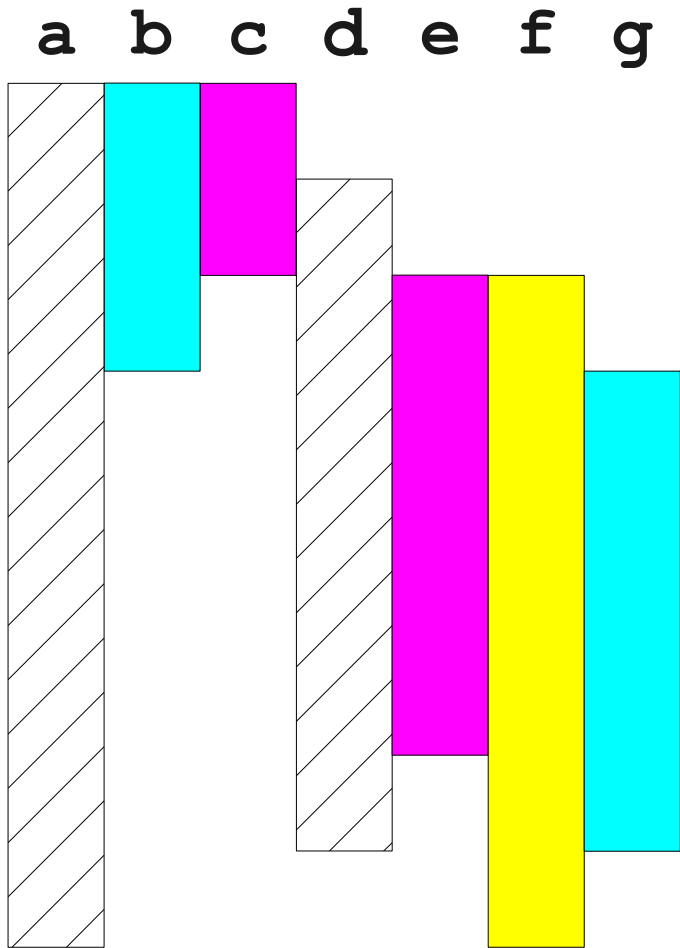
# Another Example



**Free Registers**



# Another Example



**Free Registers**



# Linear Scan Register Allocation

- This algorithm is called **linear scan register allocation** and is a comparatively new algorithm.
- Advantages:
  - Very efficient (after computing live intervals, runs in linear time)
  - Produces good code in many instances.
  - Allocation step works in one pass; can generate code during iteration.
  - Often used in JIT compilers like Java HotSpot.
- Disadvantages:
  - Imprecise due to use of live **intervals** rather than live **ranges**.
  - Other techniques known to be superior in many cases.

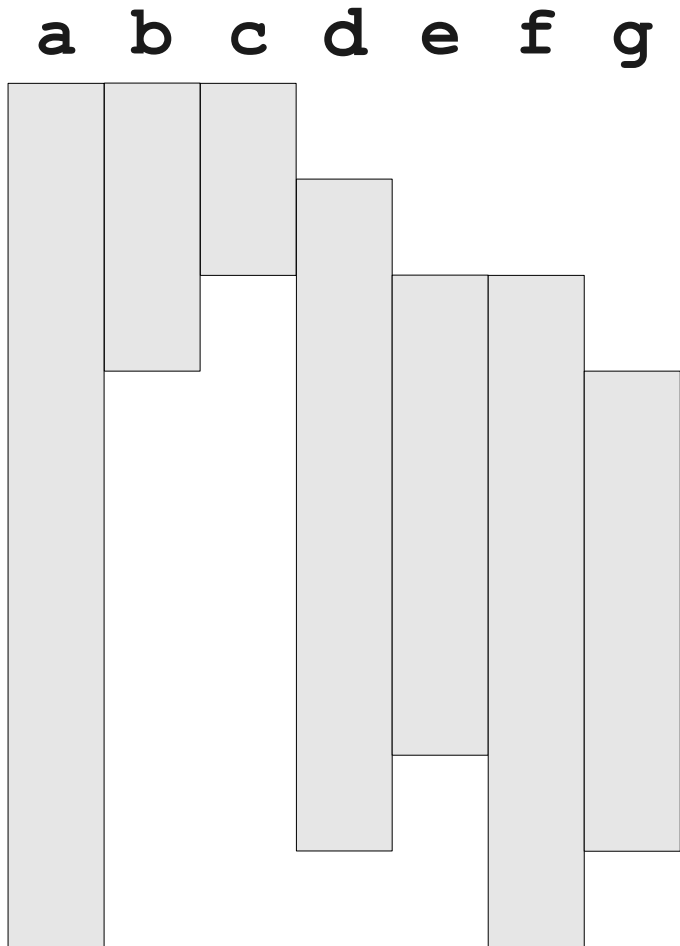
# Correctness Proof Sketch

- No register holds two live variables at once:
  - Live intervals are conservative approximations of live ranges.
  - No two variables with overlapping live ranges placed in the same register.
- At each program point, every variable is in the same location:
  - All variables assigned a unique location.

# Second-Chance Bin Packing

- A more aggressive version of linear-scan.
- Uses live **ranges** instead of live **intervals**.
- If a variable must be spilled, don't spill all uses of it.
  - A later live range might still fit into a register.
- Requires a final data-flow analysis to confirm variables are assigned consistent locations.
- See “Quality and Speed in Linear-scan Register Allocation” by Traub, Holloway, and Smith.

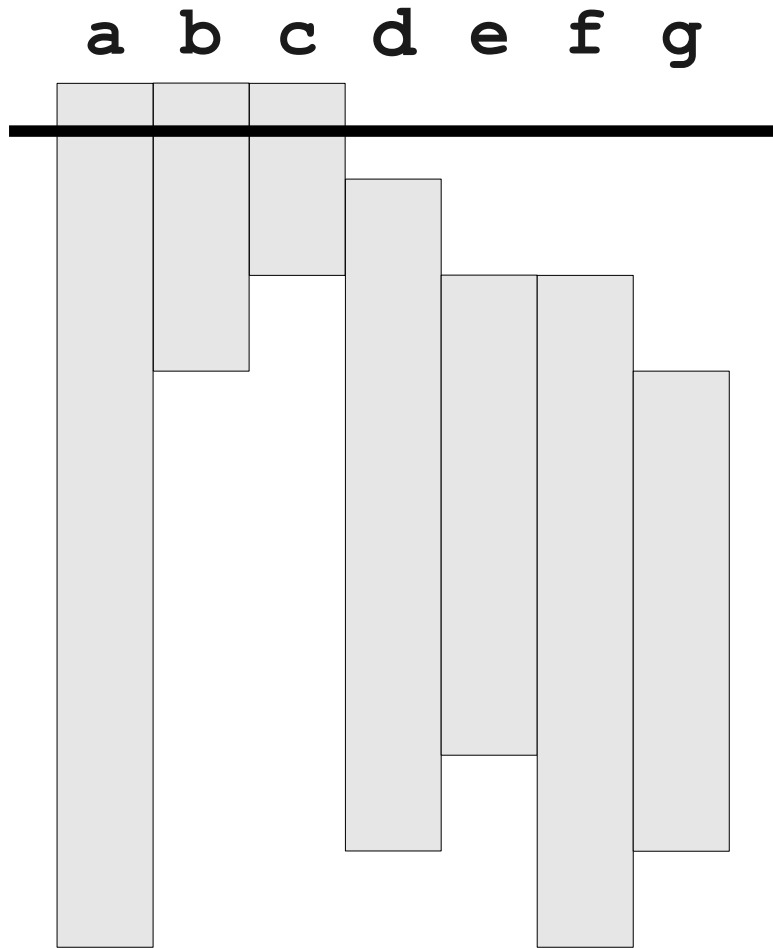
# Second-Chance Bin Packing



**Free Registers**



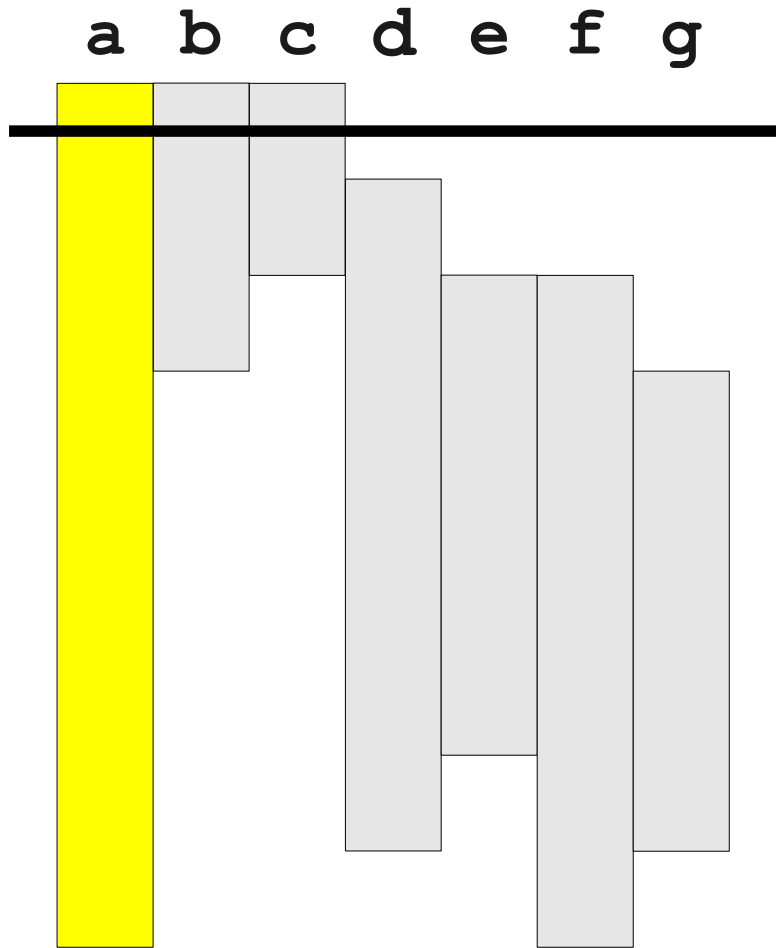
# Second-Chance Bin Packing



**Free Registers**



# Second-Chance Bin Packing

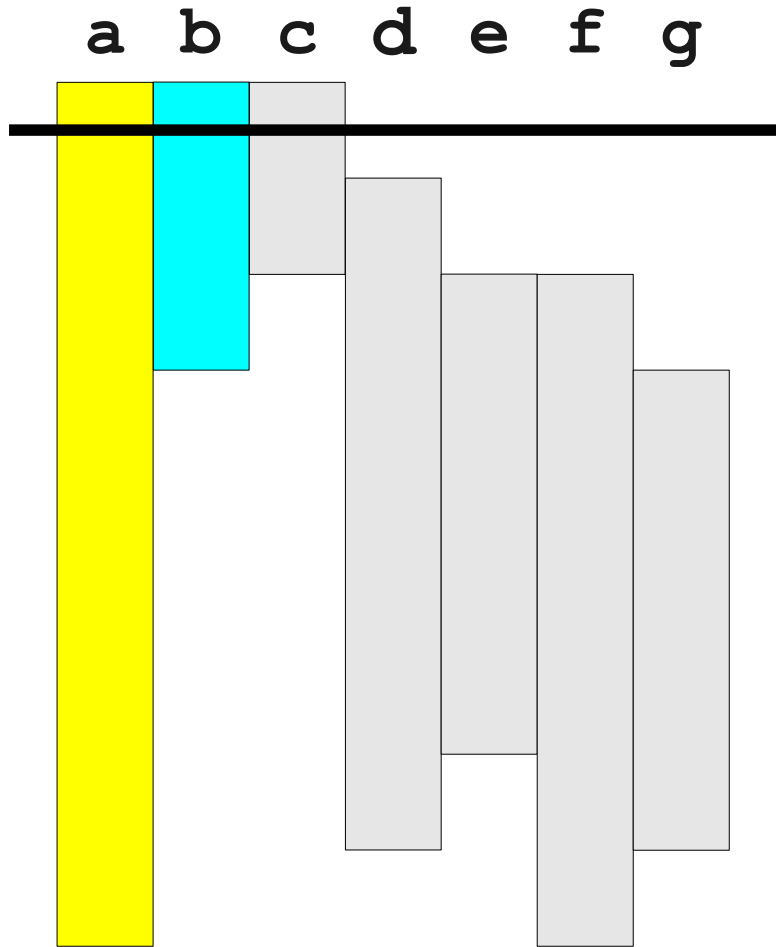


**Free Registers**





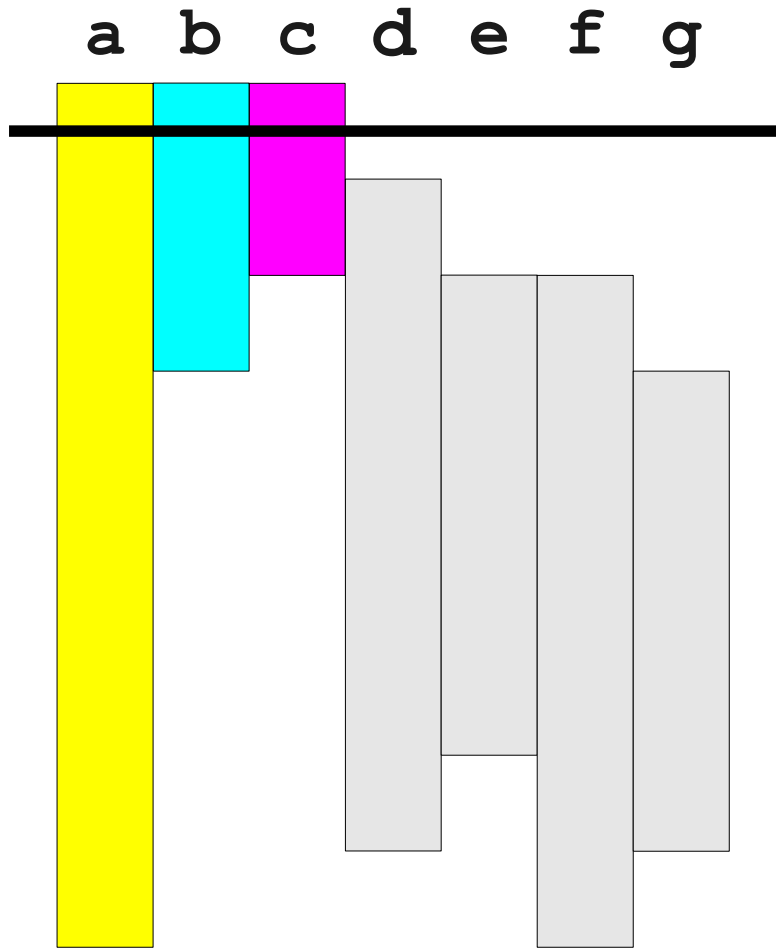
# Second-Chance Bin Packing



**Free Registers**



# Second-Chance Bin Packing

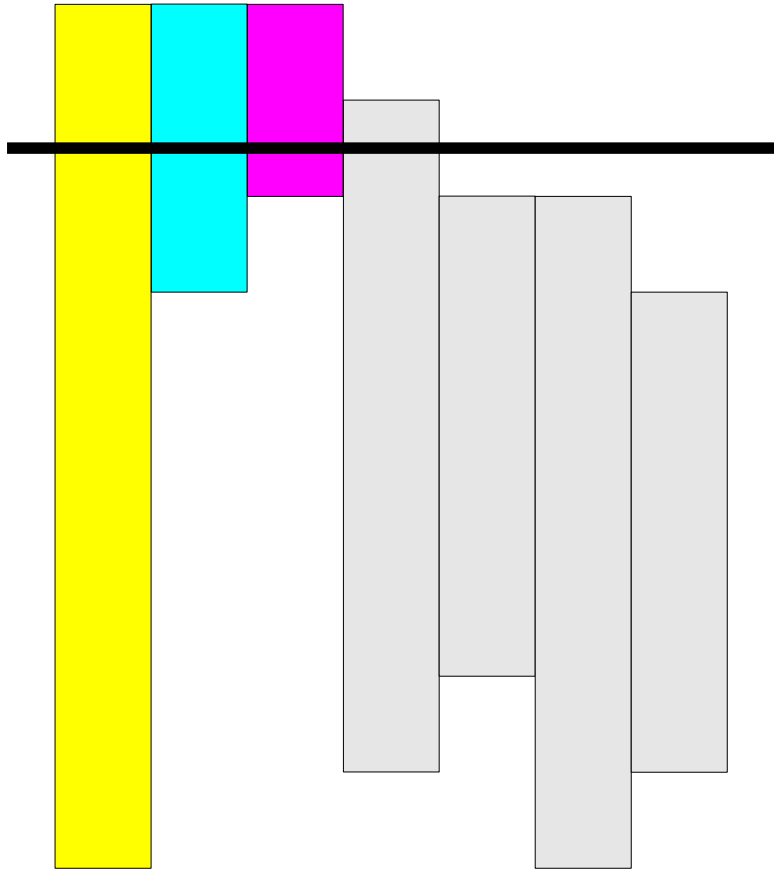


**Free Registers**



# Second-Chance Bin Packing

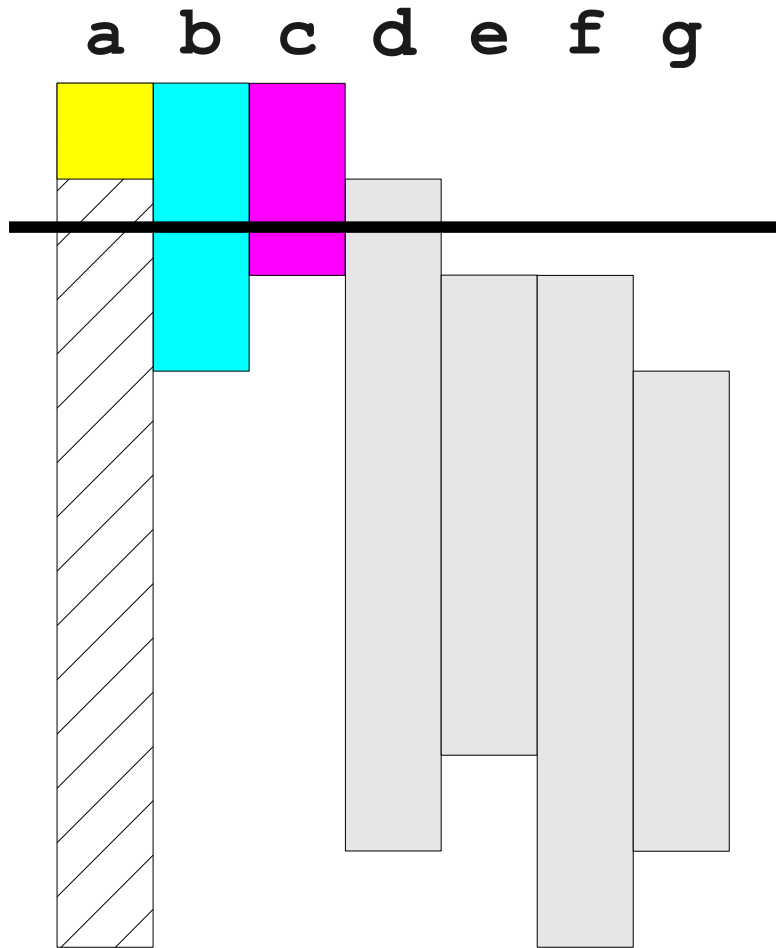
a b c d e f g



**Free Registers**



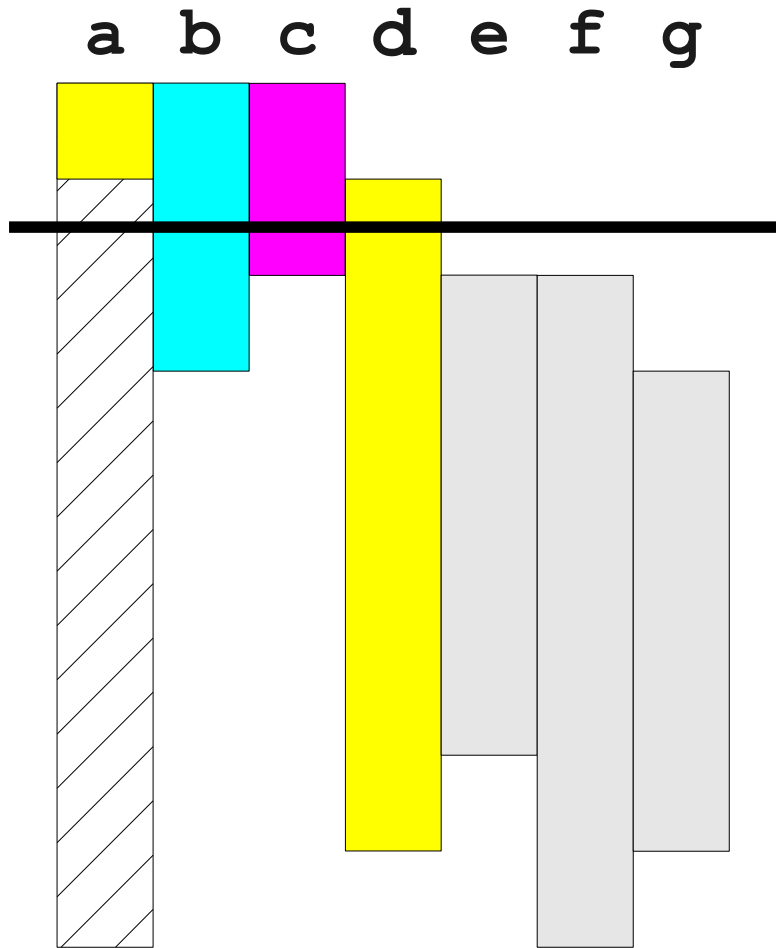
# Second-Chance Bin Packing



**Free Registers**



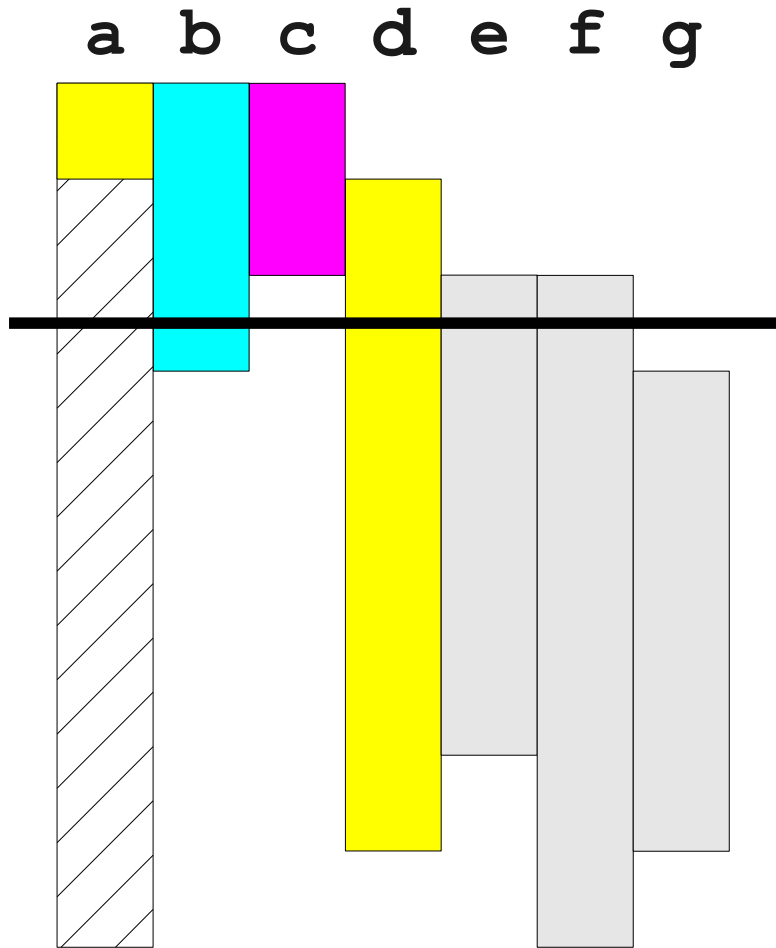
# Second-Chance Bin Packing



**Free Registers**



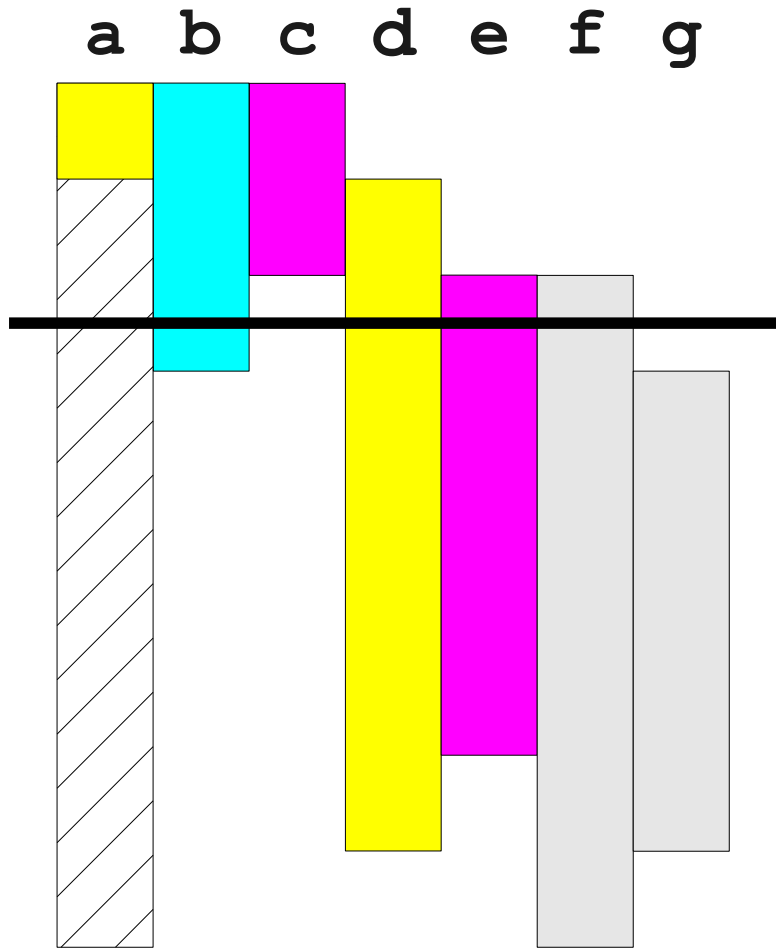
# Second-Chance Bin Packing



**Free Registers**



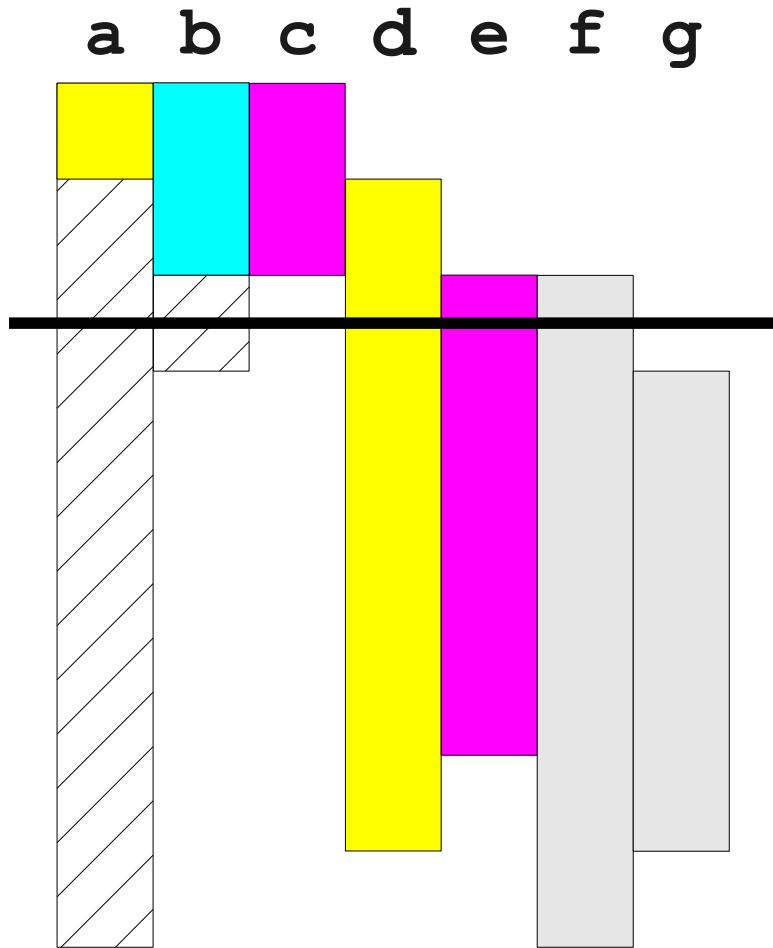
# Second-Chance Bin Packing



**Free Registers**



# Second-Chance Bin Packing

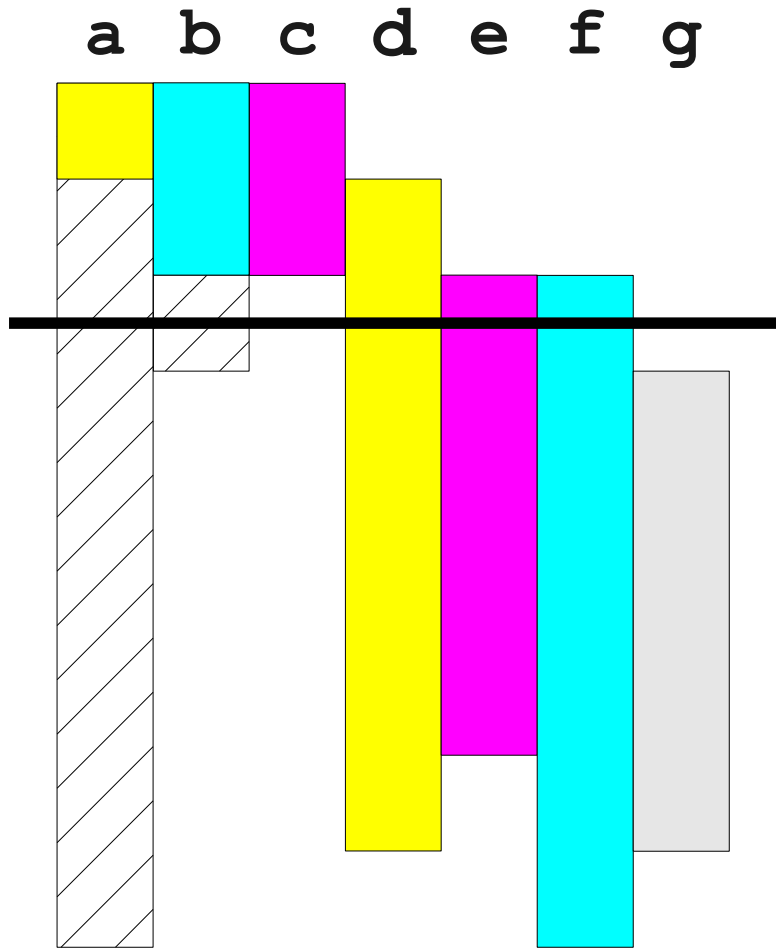


**Free Registers**





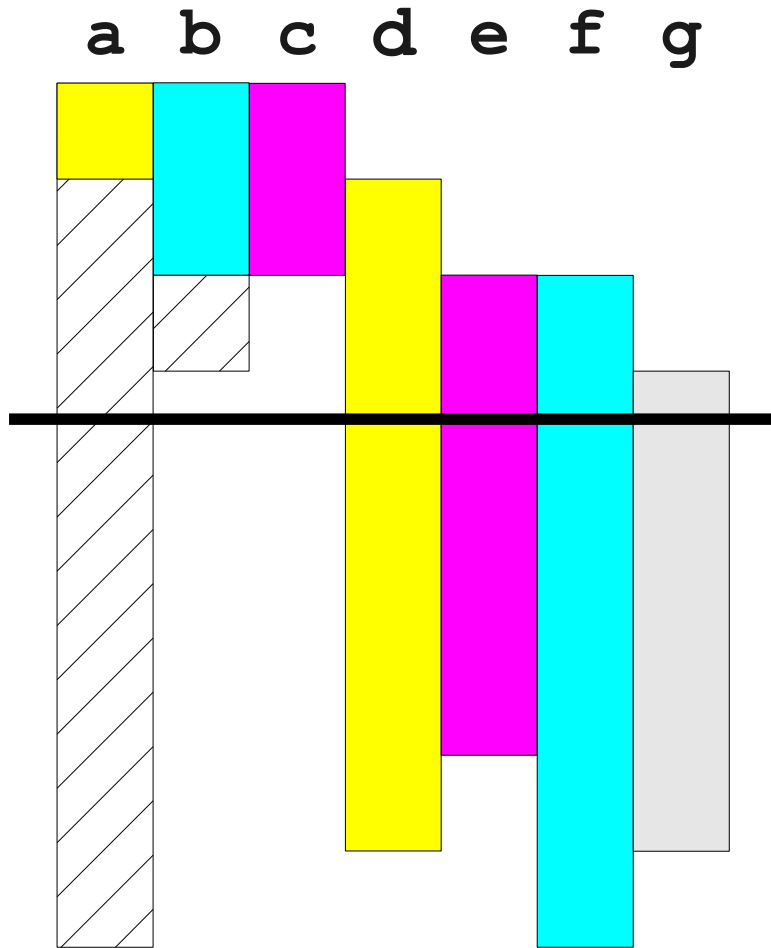
# Second-Chance Bin Packing



**Free Registers**



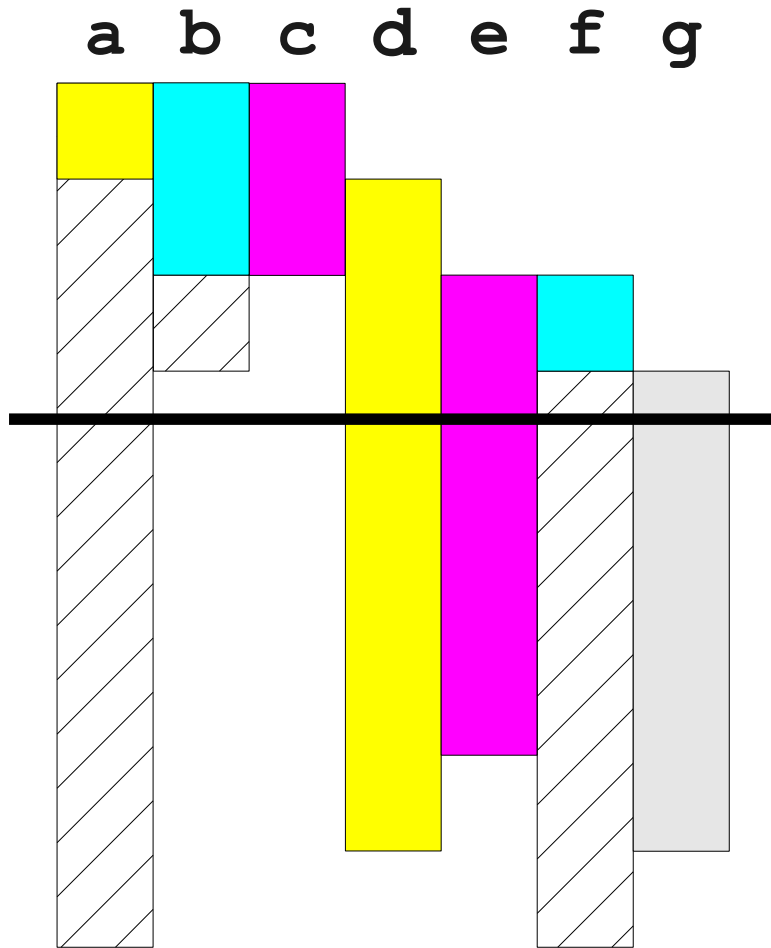
# Second-Chance Bin Packing



**Free Registers**



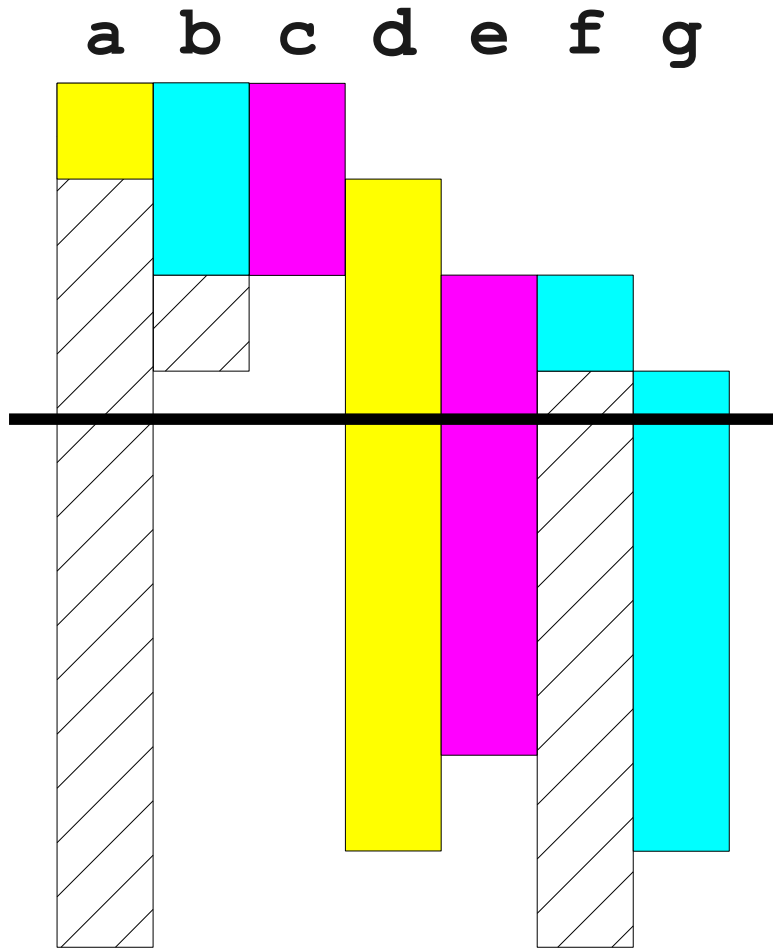
# Second-Chance Bin Packing



**Free Registers**



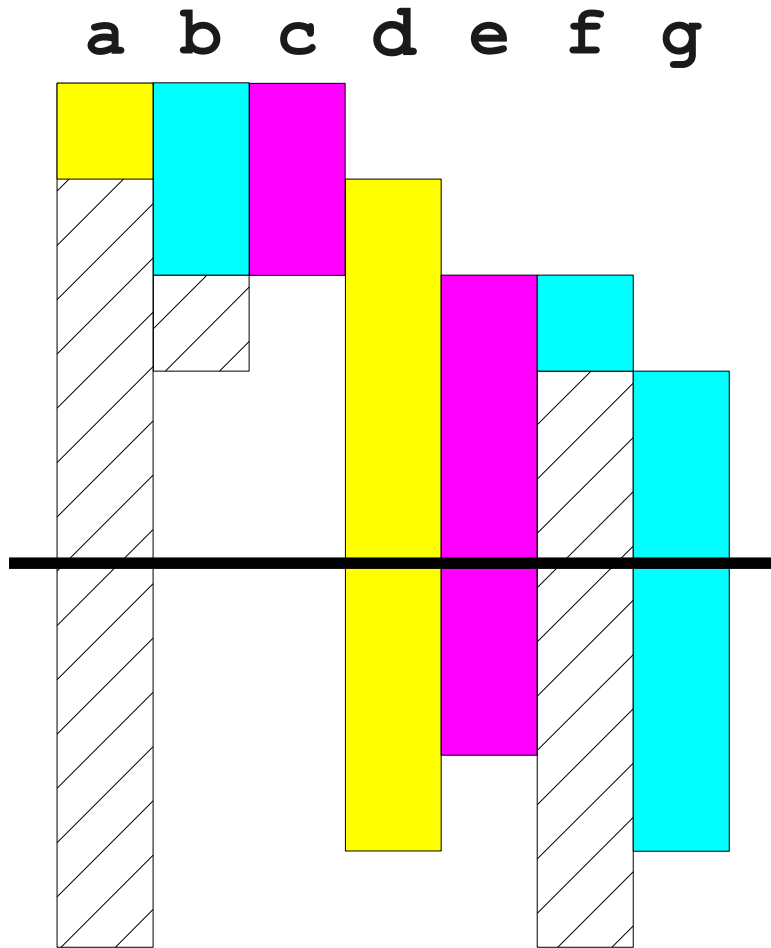
# Second-Chance Bin Packing



**Free Registers**



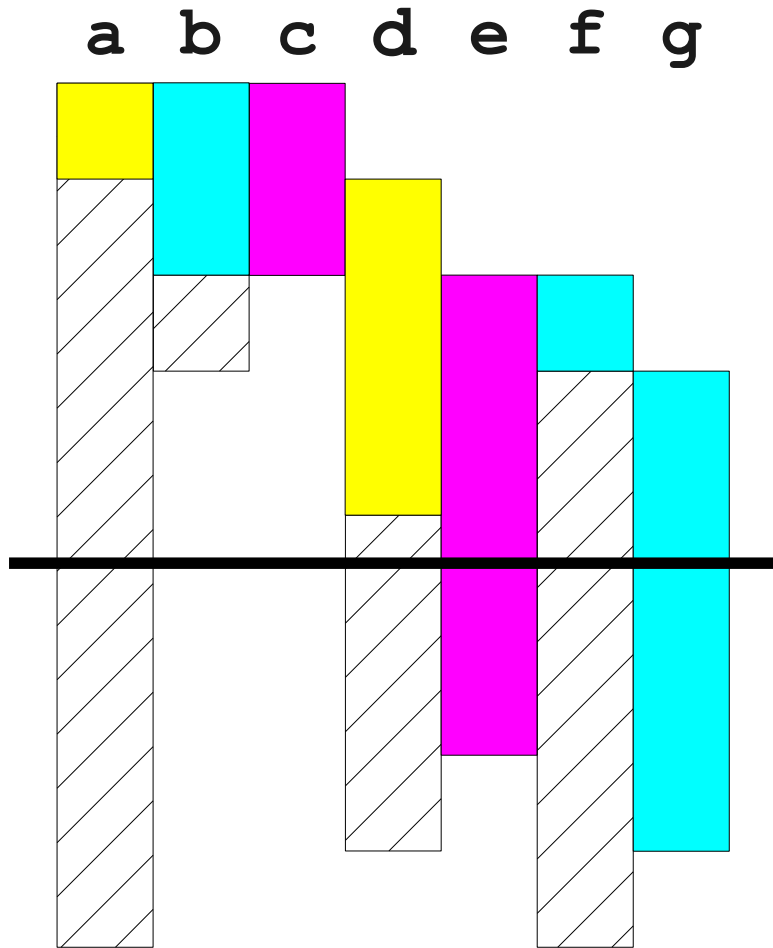
# Second-Chance Bin Packing



**Free Registers**



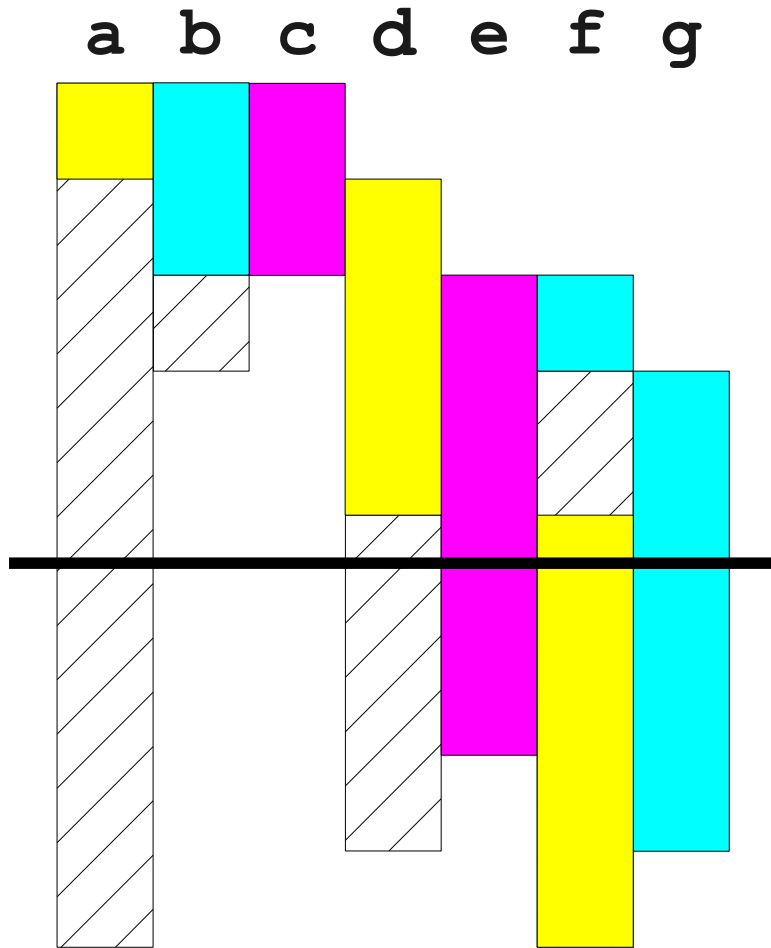
# Second-Chance Bin Packing



**Free Registers**



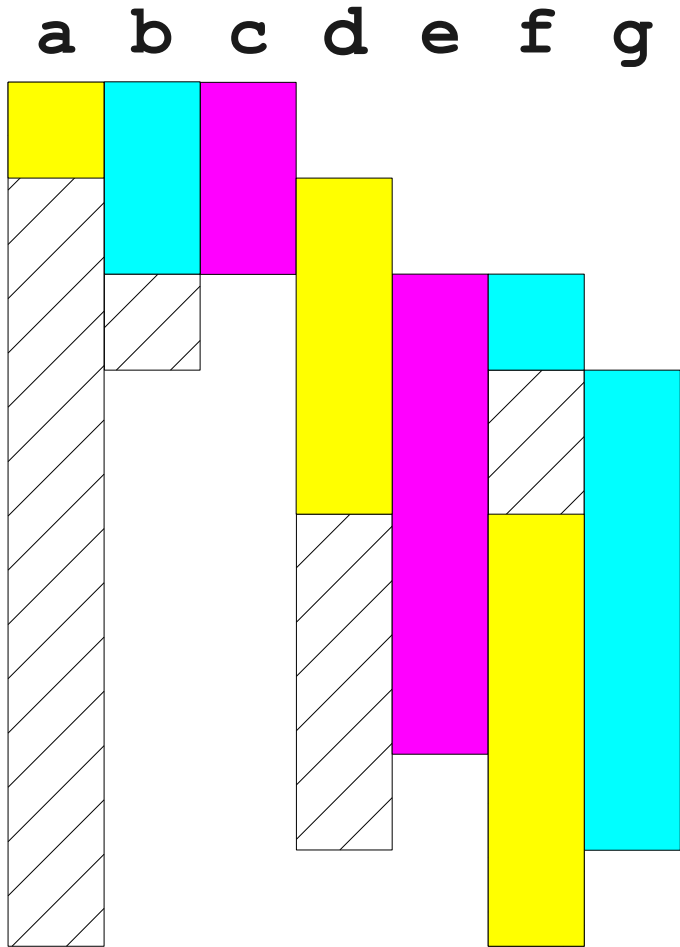
# Second-Chance Bin Packing



**Free Registers**



# Second-Chance Bin Packing



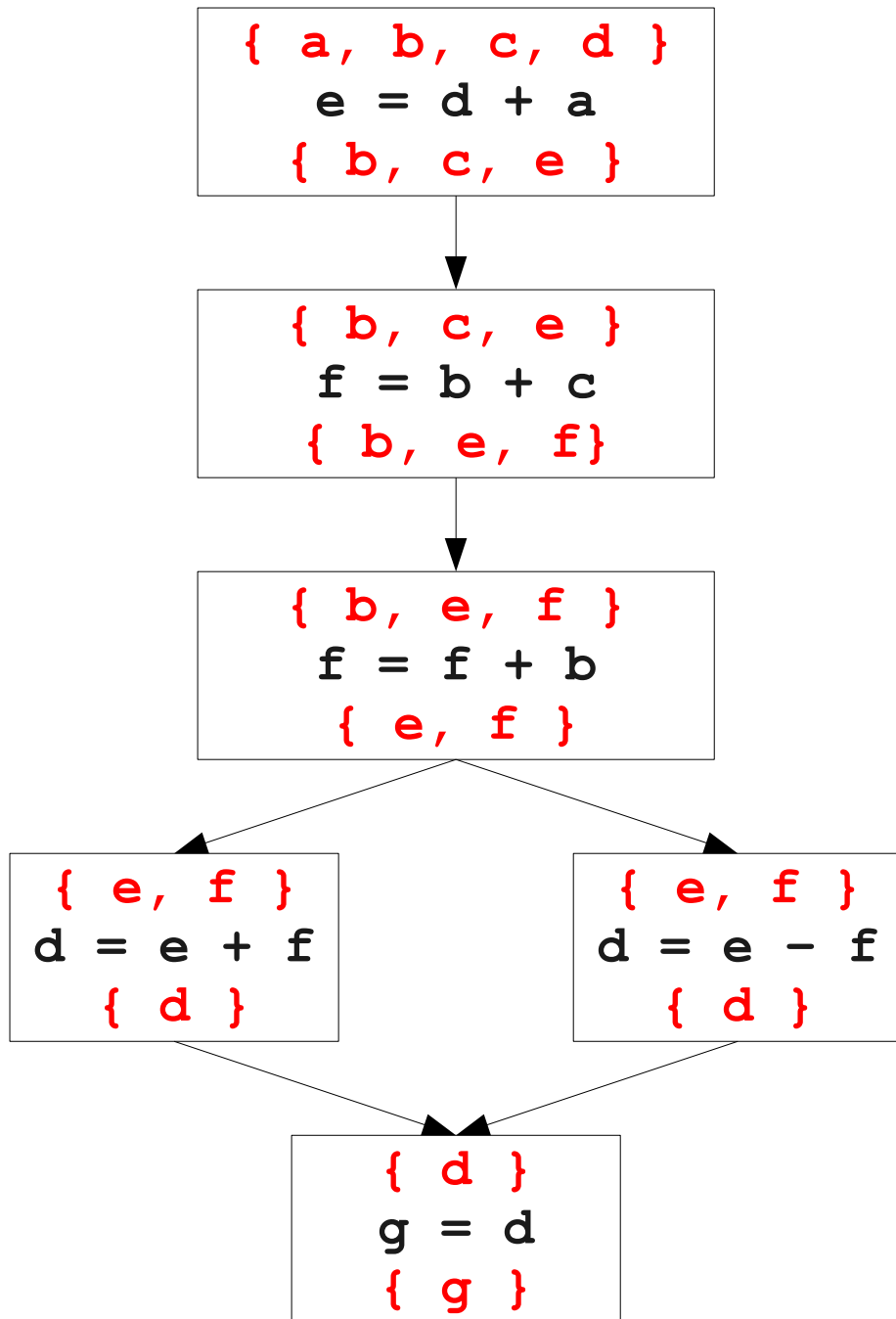
**Free Registers**



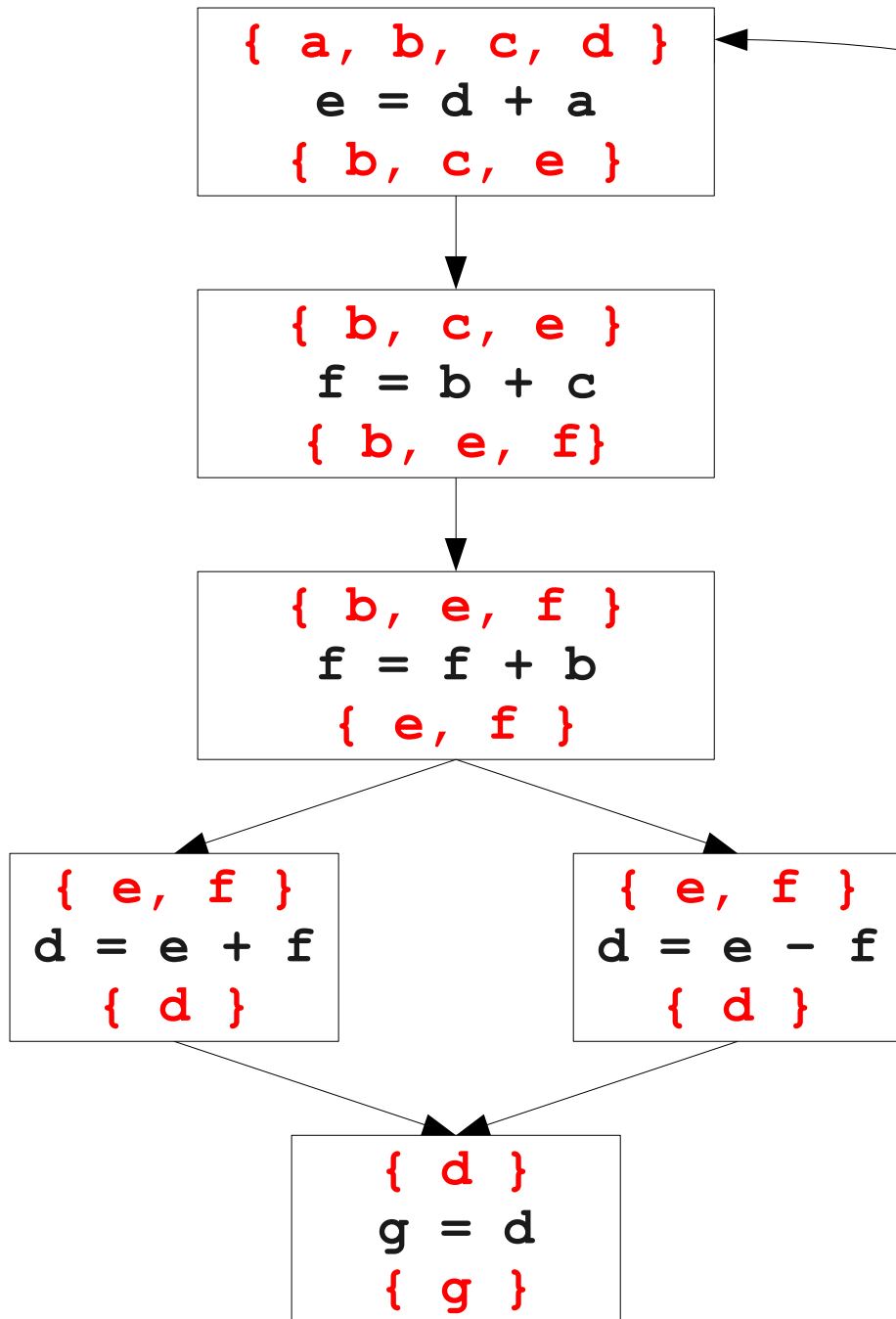


# An Entirely Different Approach

# An Entirely Different Approach

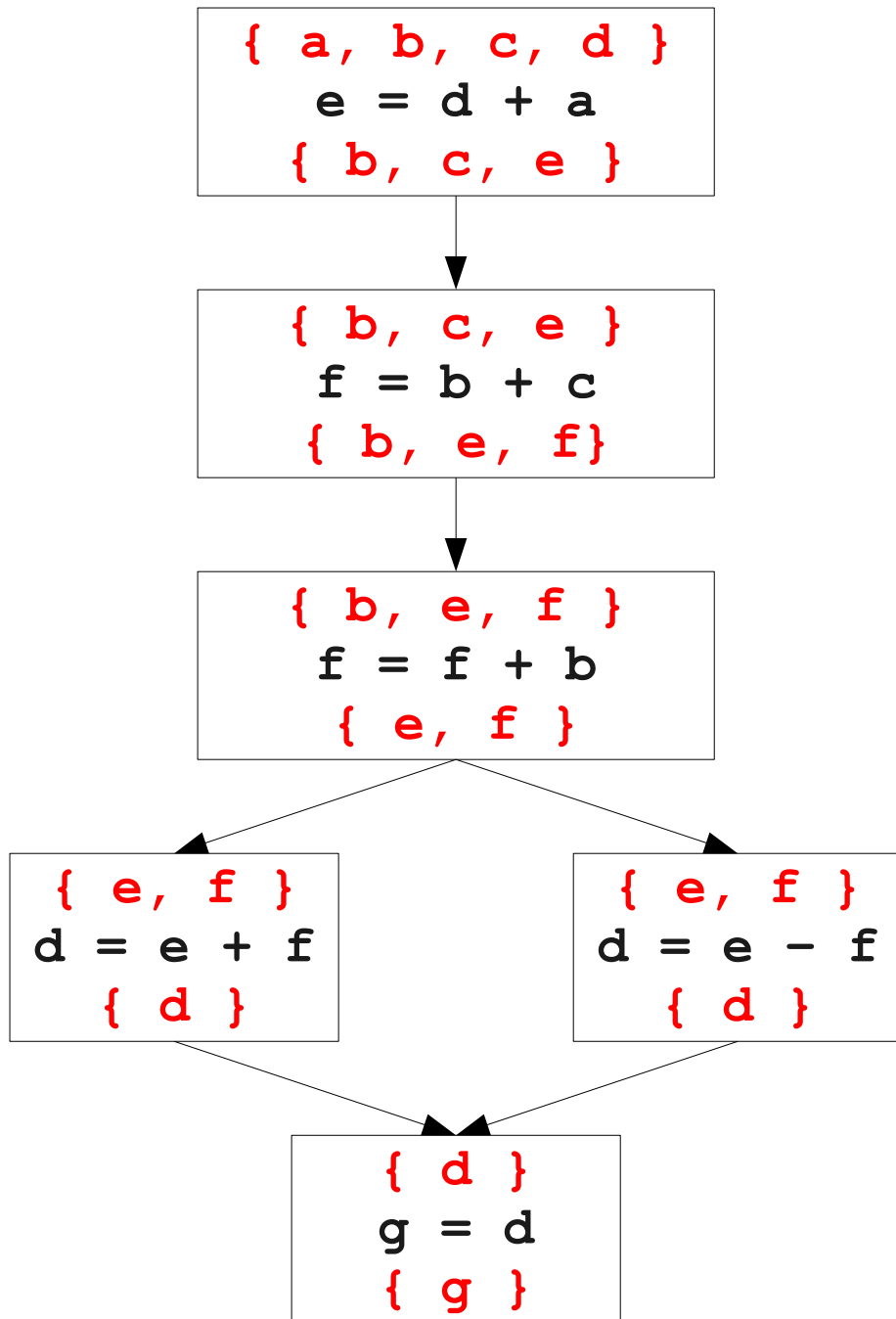


# An Entirely Different Approach

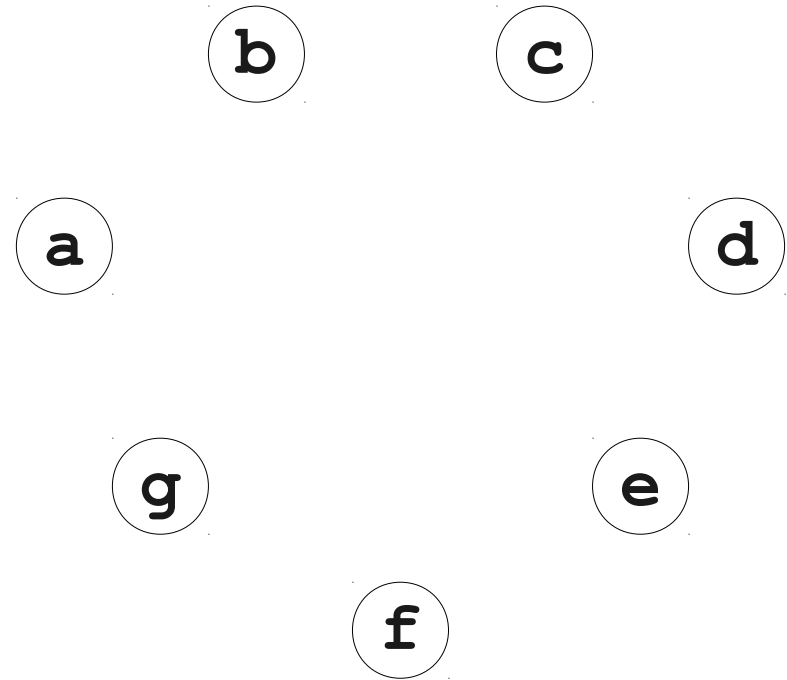
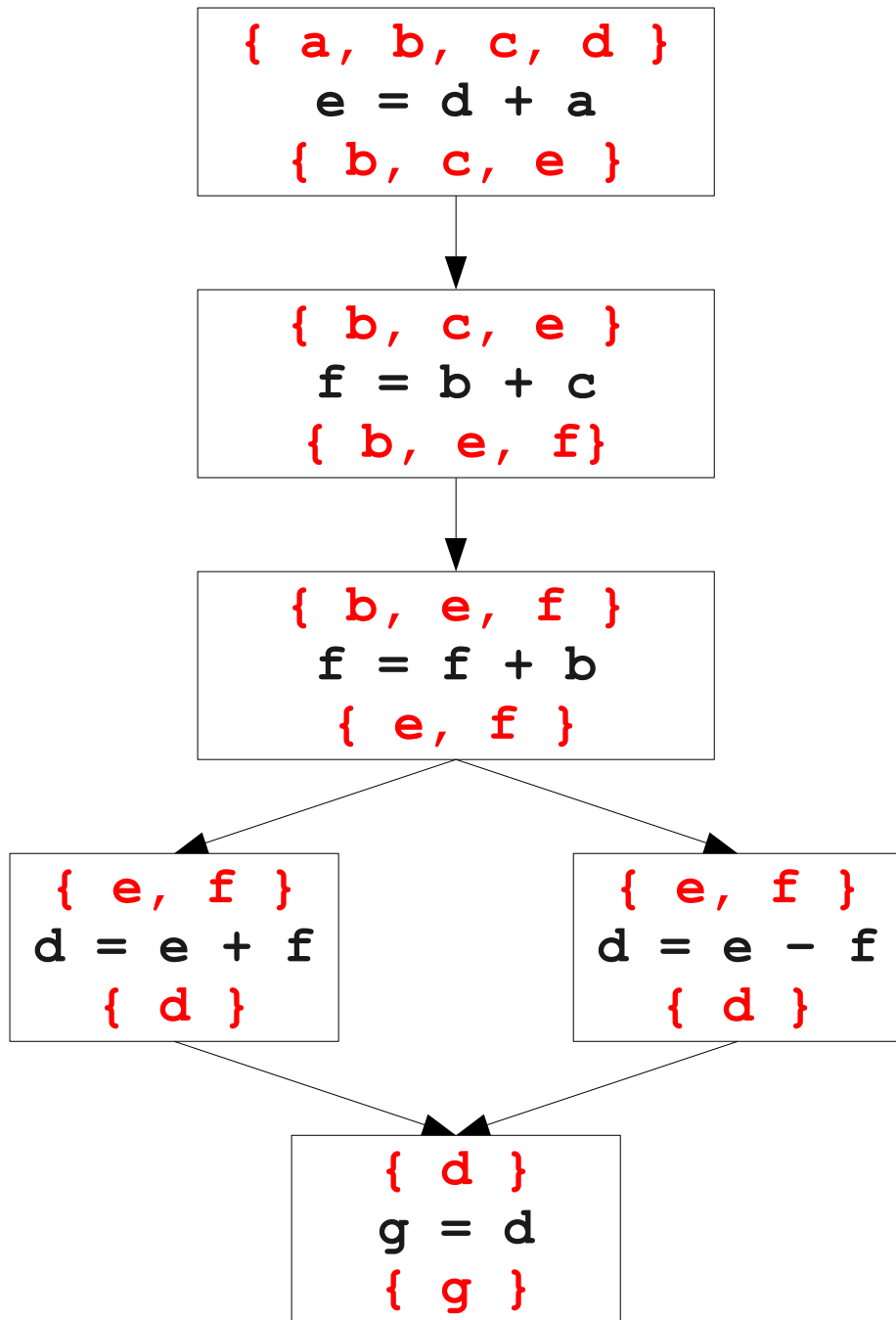


What can we infer from all these variables being live at this point?

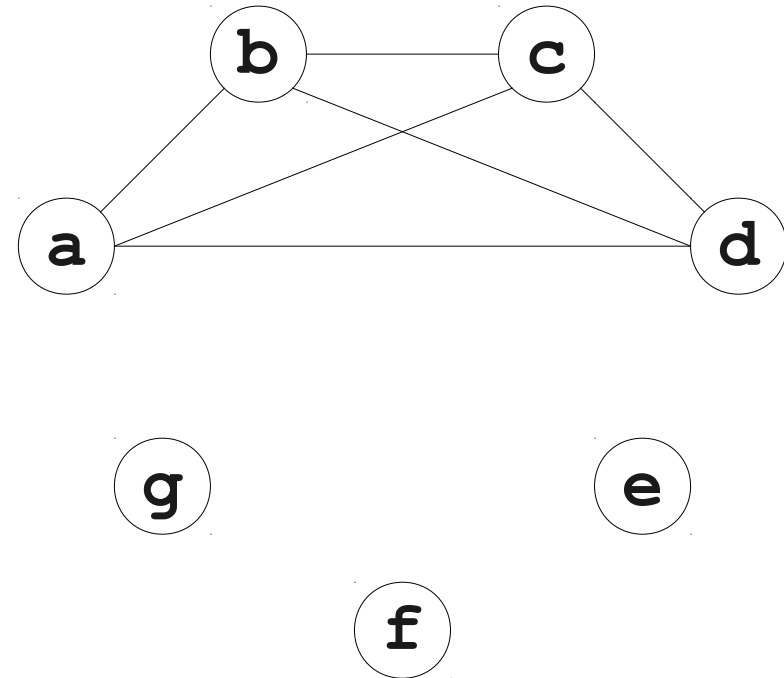
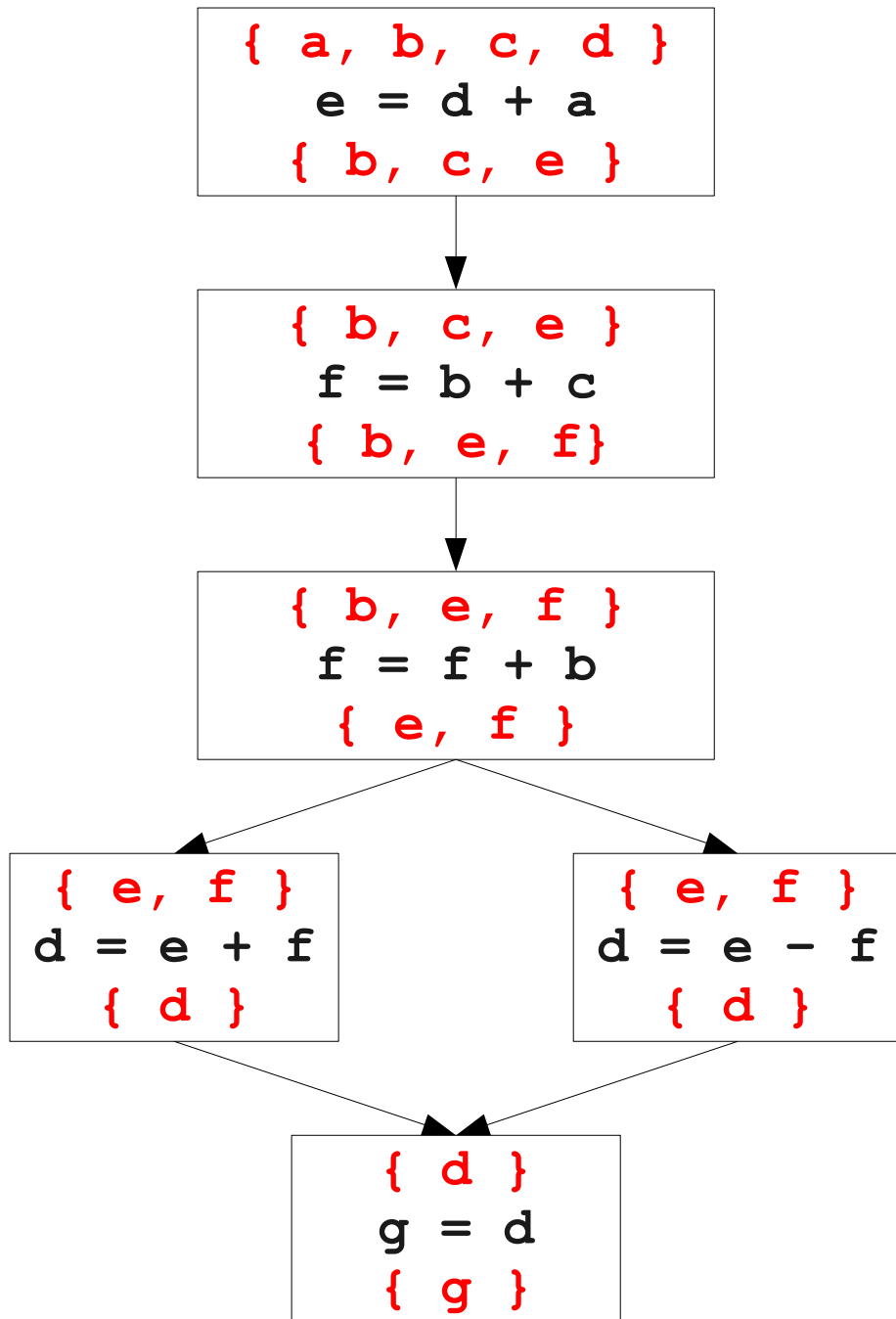
# An Entirely Different Approach



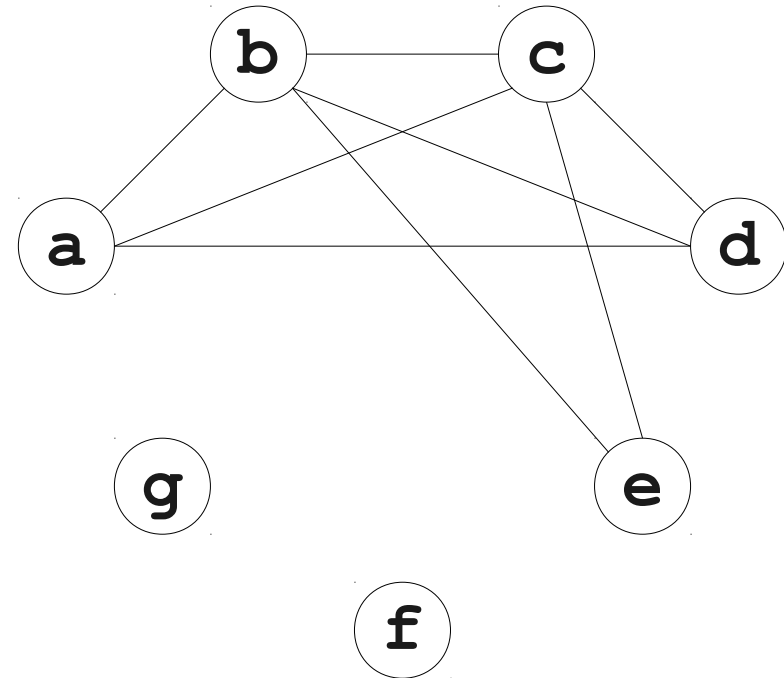
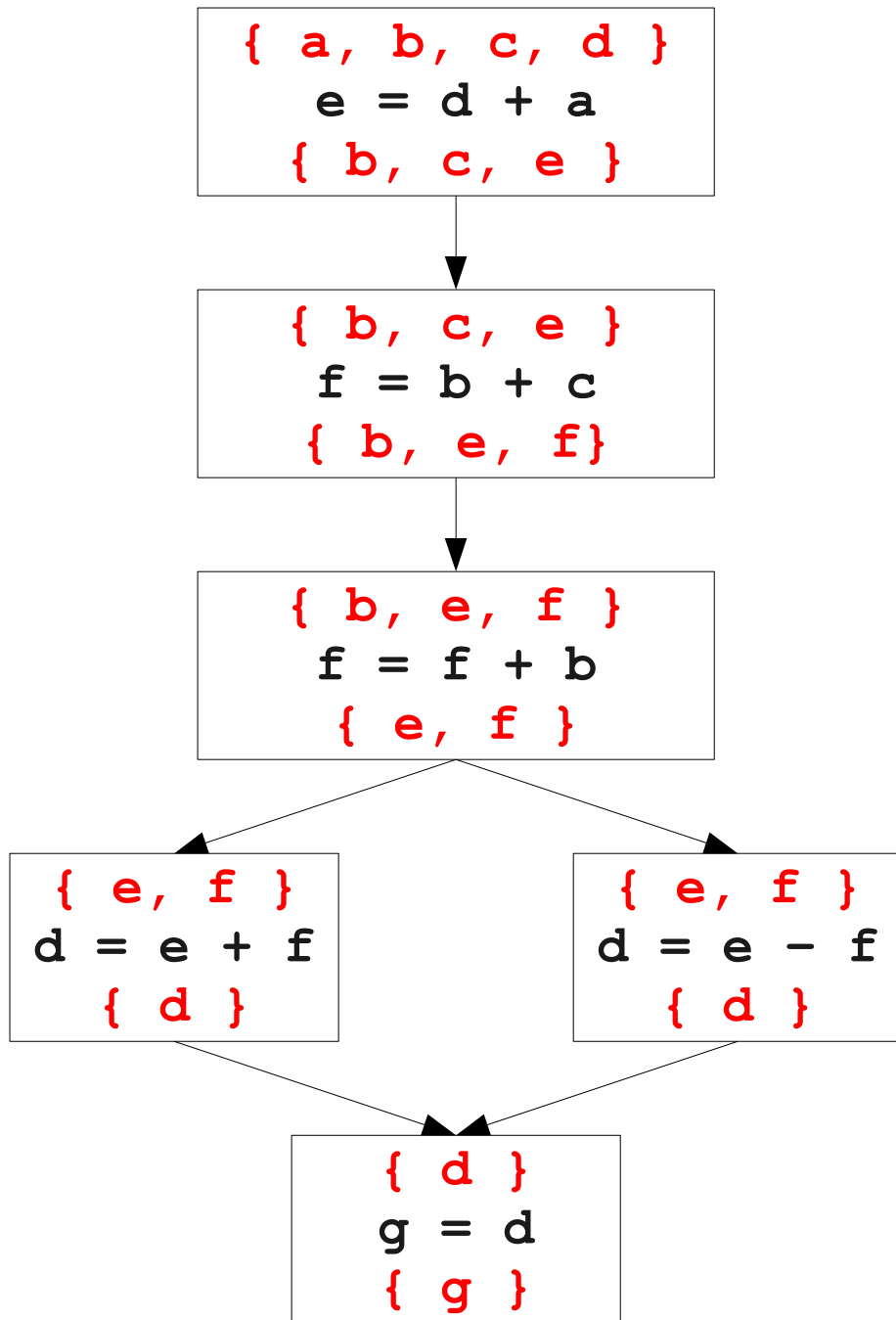
# An Entirely Different Approach



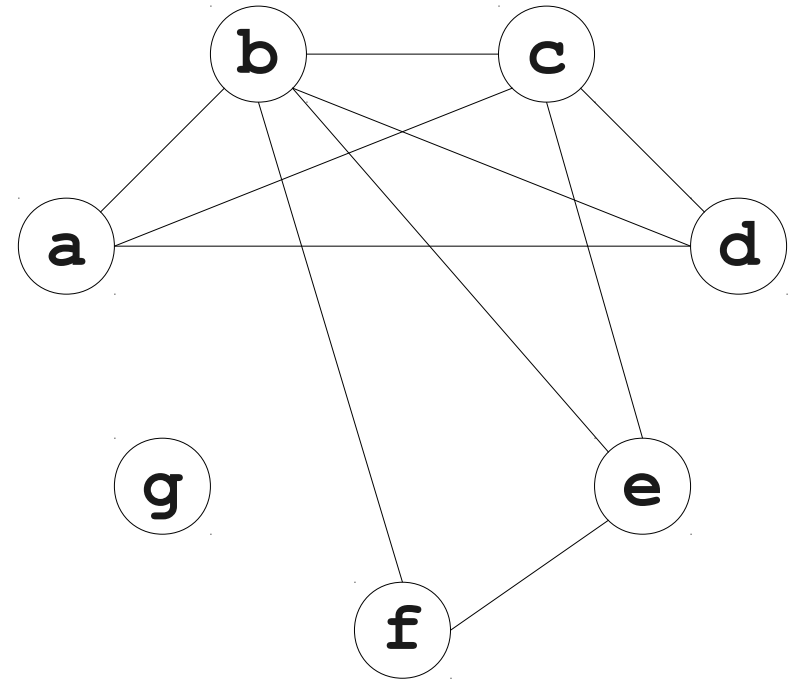
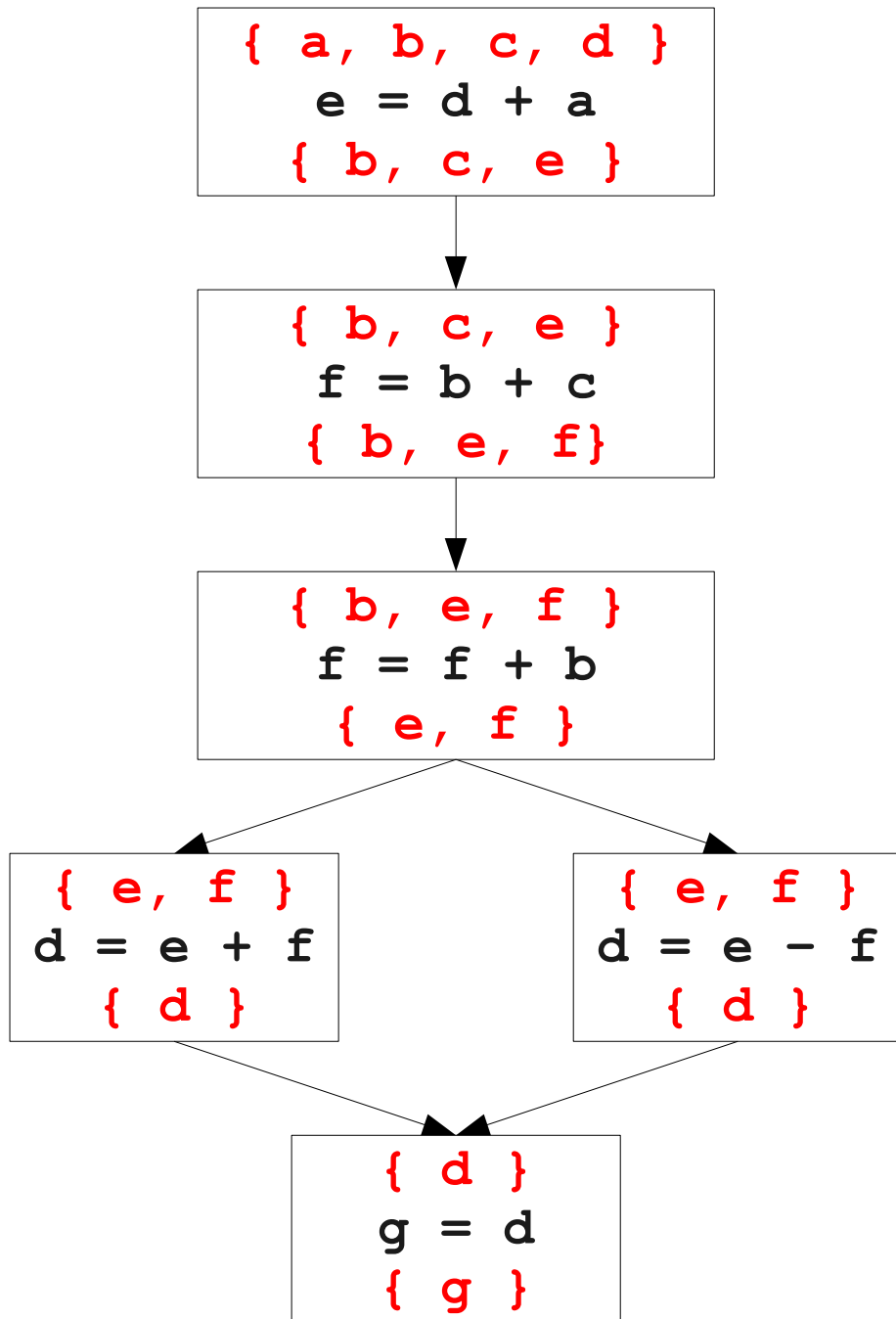
# An Entirely Different Approach



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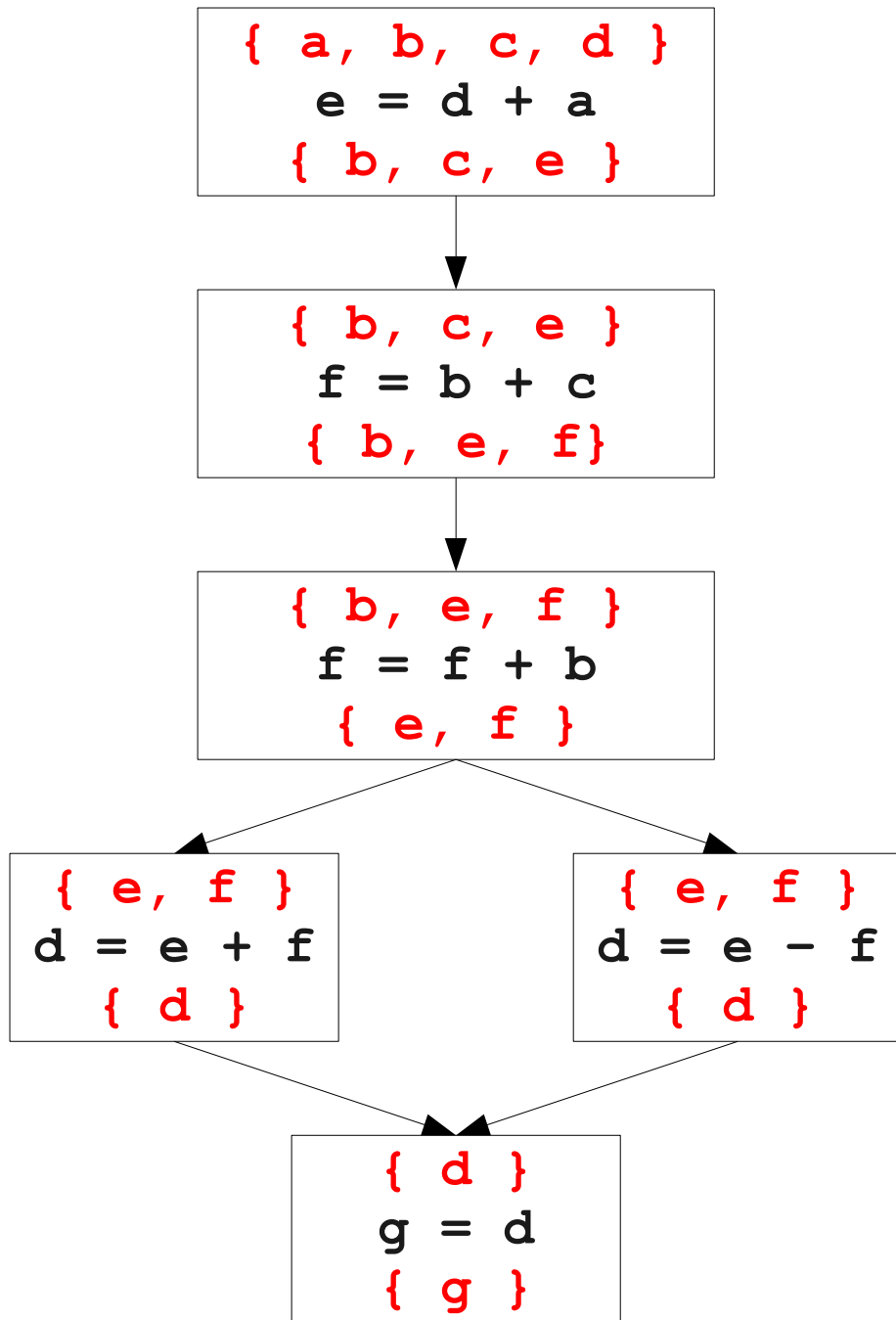


# An Entirely Different Approach

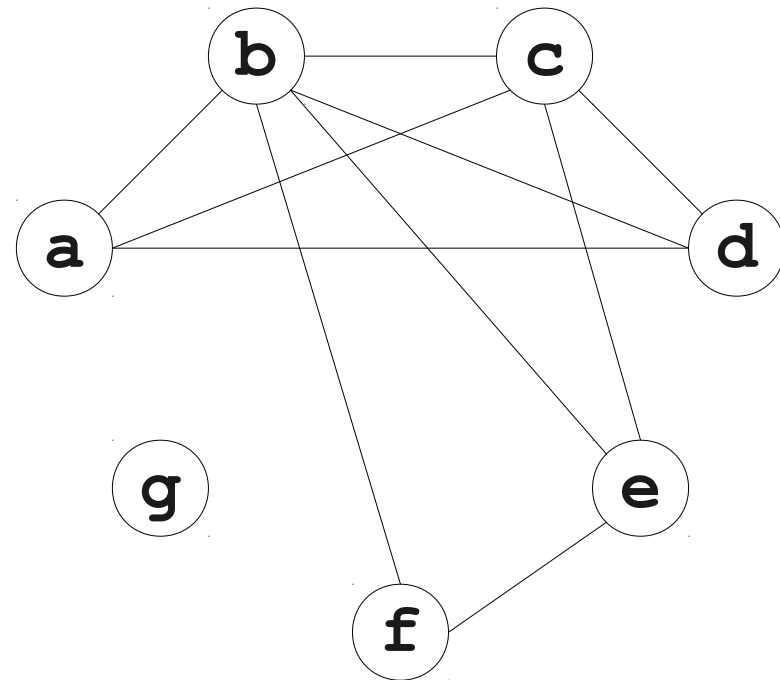
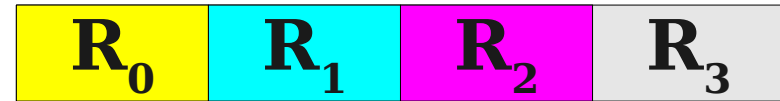




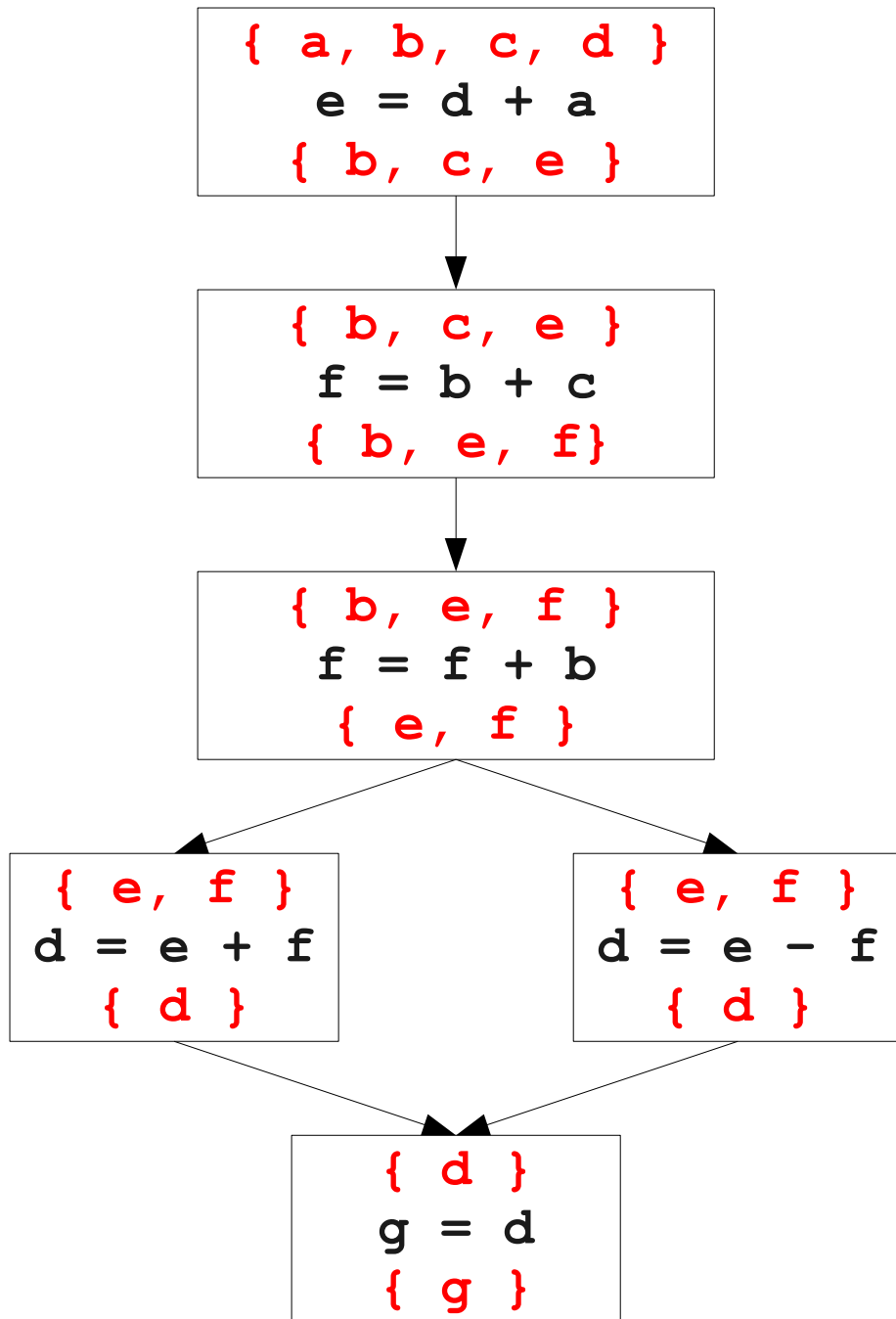
# An Entirely Different Approach



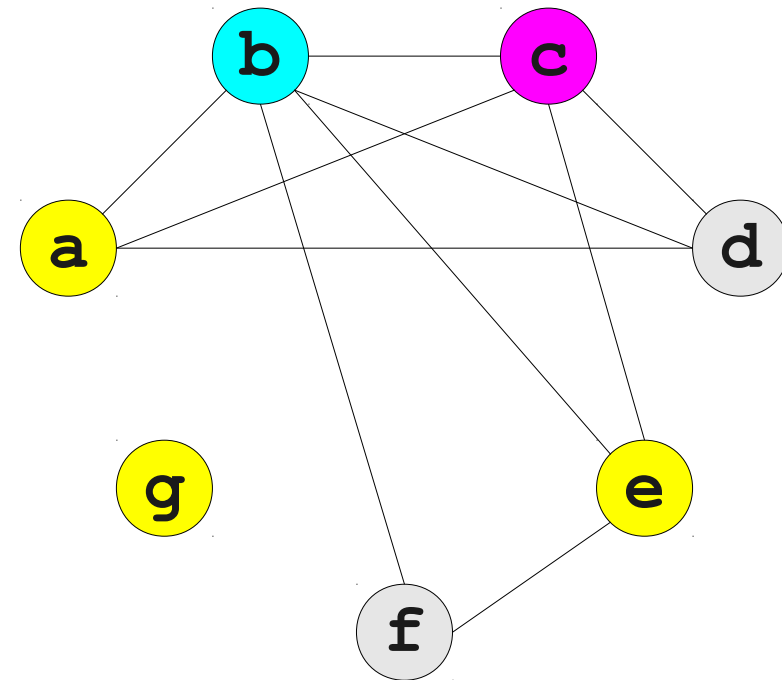
## Registers



# An Entirely Different Approach



## Registers



# The Register Interference Graph

- The **register interference graph** (RIG) of a control-flow graph is an undirected graph where
  - Each node is a variable.
  - There is an edge between two variables that are live at the same program point.
- Perform register allocation by assigning each variable a different register from all of its neighbors.
- There's just one catch...

# The One Catch

- This problem is equivalent to **graph-coloring**, which is **NP-hard** if there are at least three registers.
- No good polynomial-time algorithms (or even good approximations!) are known for this problem.
- We have to be content with a heuristic that is good enough for RIGs that arise in practice.

The One Catch to The One Catch

# The One Catch to The One Catch

If you can figure out a way to assign registers to arbitrary RIGs, you've just proven  $\mathbf{P} = \mathbf{NP}$  and will get a **\$1,000,000 check** from the Clay Mathematics Institute.

# The One Catch to The One Catch

## **CHALLENGE ACCEPTED**



If you can figure out a way to assign registers to arbitrary RIGs, you've just proven  $\mathbf{P} = \mathbf{NP}$  and will get a **\$1,000,000 check** from the Clay Mathematics Institute.

# Battling **NP**-Hardness

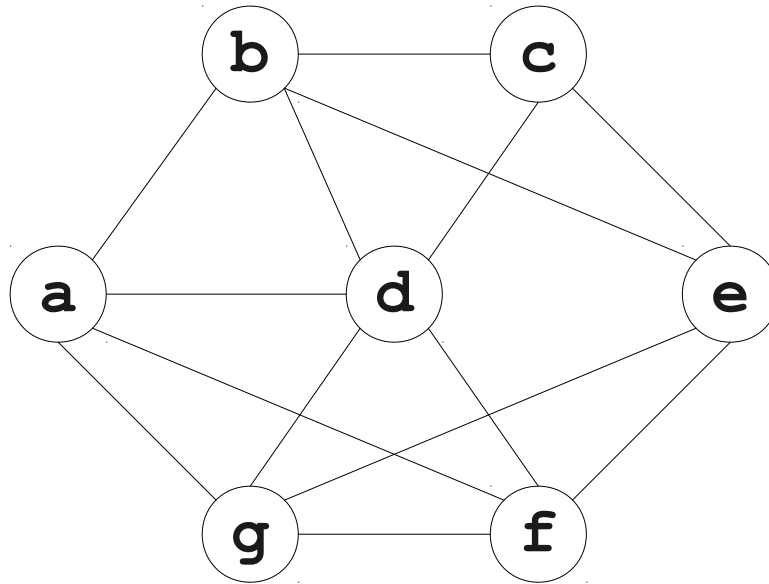


# Chaitin's Algorithm

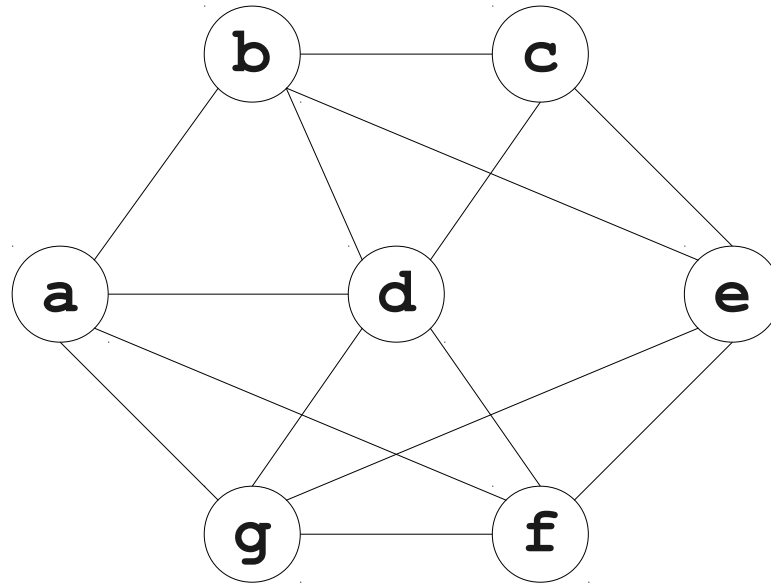
- Intuition:
  - Suppose we are trying to  $k$ -color a graph and find a node with fewer than  $k$  edges.
  - If we delete this node from the graph and color what remains, we can find a color for this node if we add it back in.
  - Reason: With fewer than  $k$  neighbors, some color must be left over.
- Algorithm:
  - Find a node with fewer than  $k$  outgoing edges.
  - Remove it from the graph.
  - Recursively color the rest of the graph.
  - Add the node back in.
  - Assign it a valid color.

# Chaitin's Algorithm

# Chaitin's Algorithm



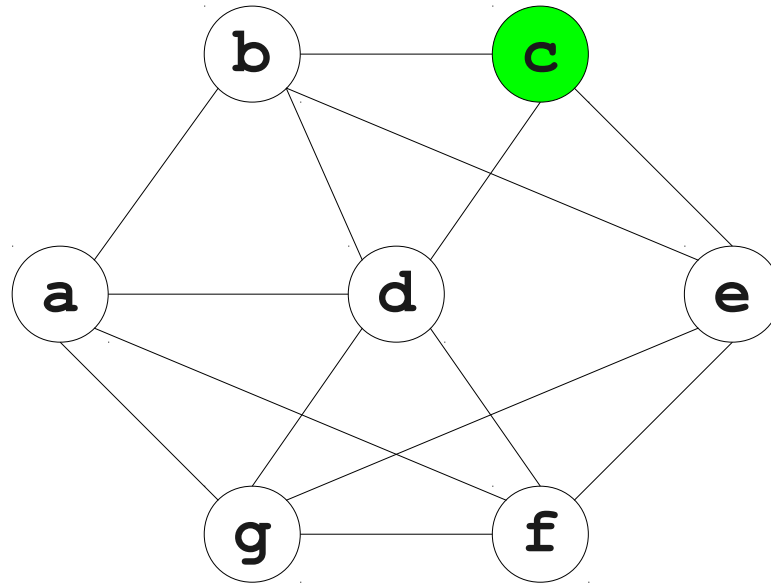
# Chaitin's Algorithm



## Registers



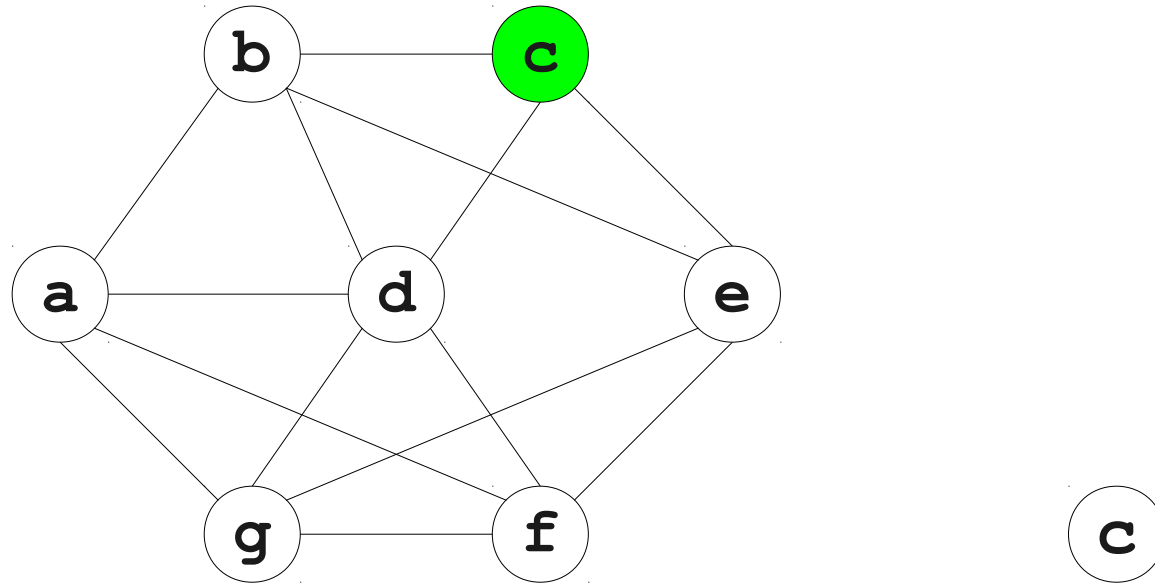
# Chaitin's Algorithm



## Registers



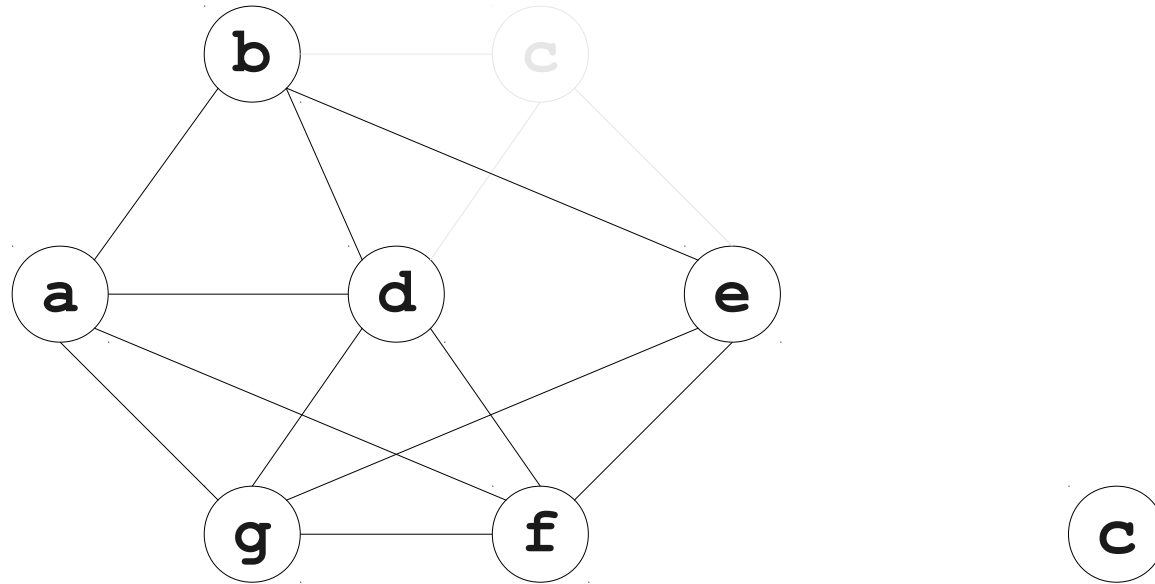
# Chaitin's Algorithm



**Registers**



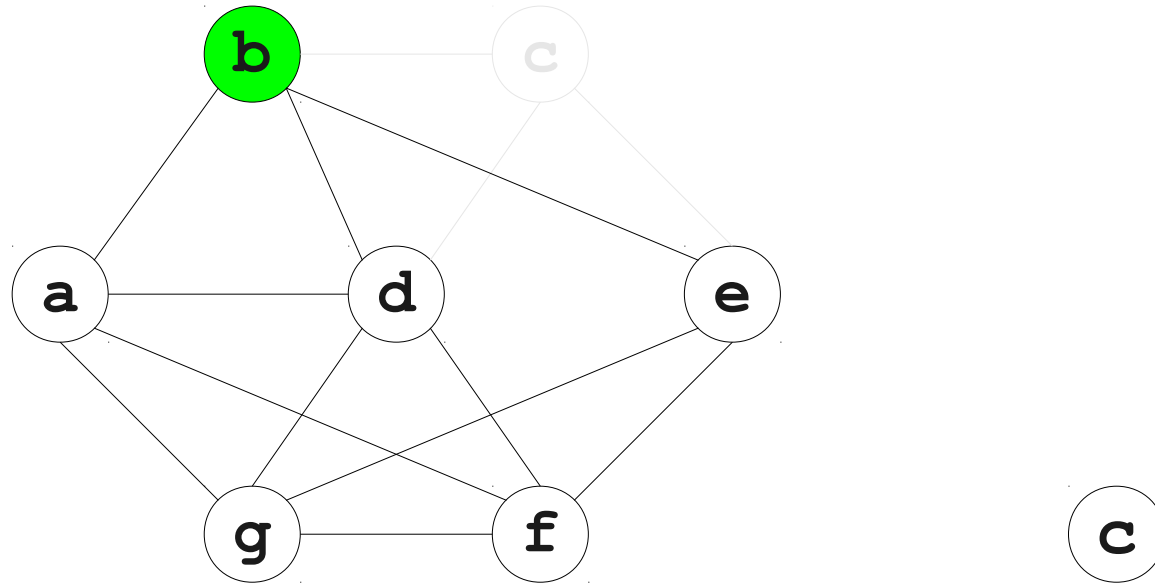
# Chaitin's Algorithm



## Registers



# Chaitin's Algorithm

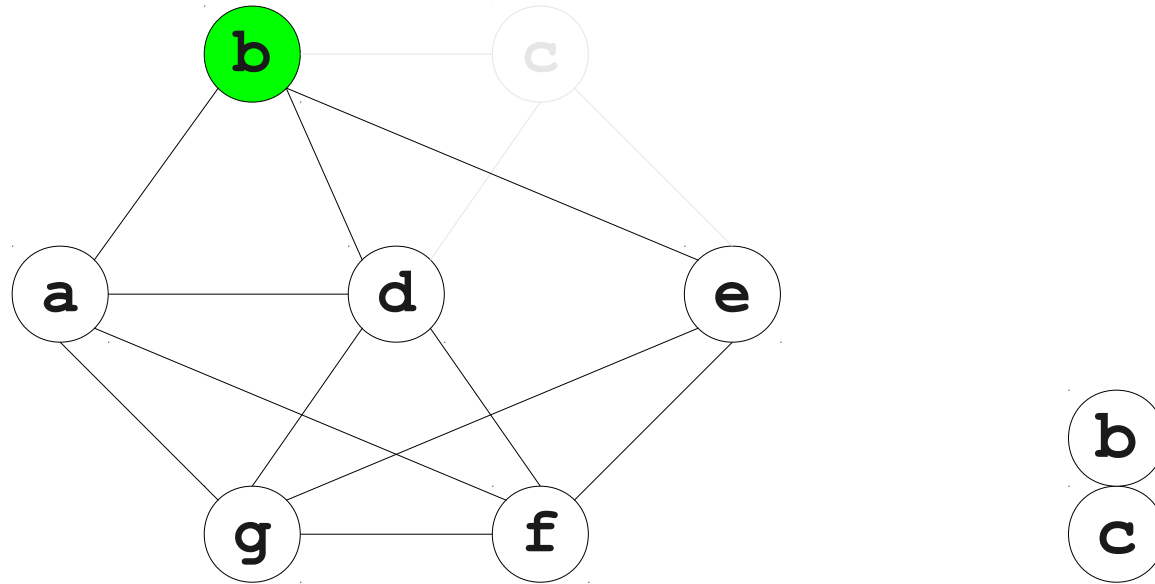


## Registers





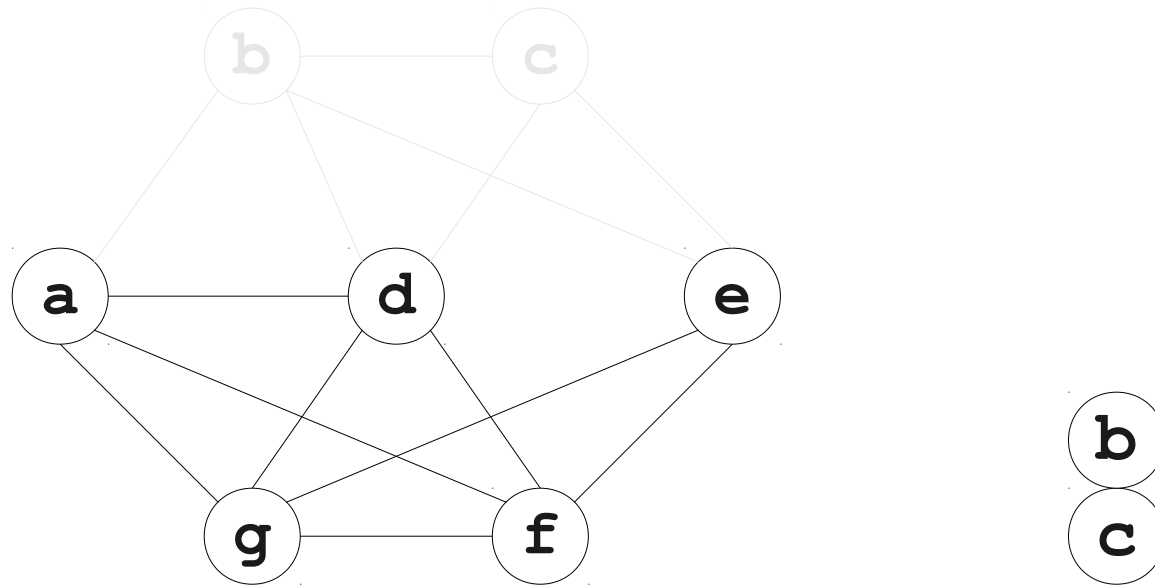
# Chaitin's Algorithm



## Registers



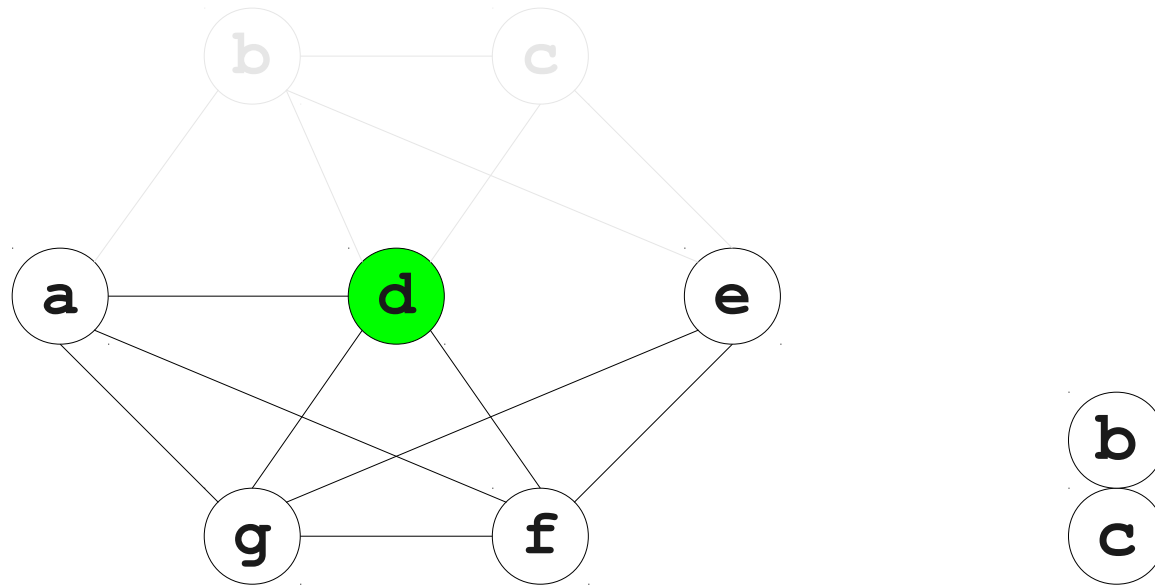
# Chaitin's Algorithm



**Registers**



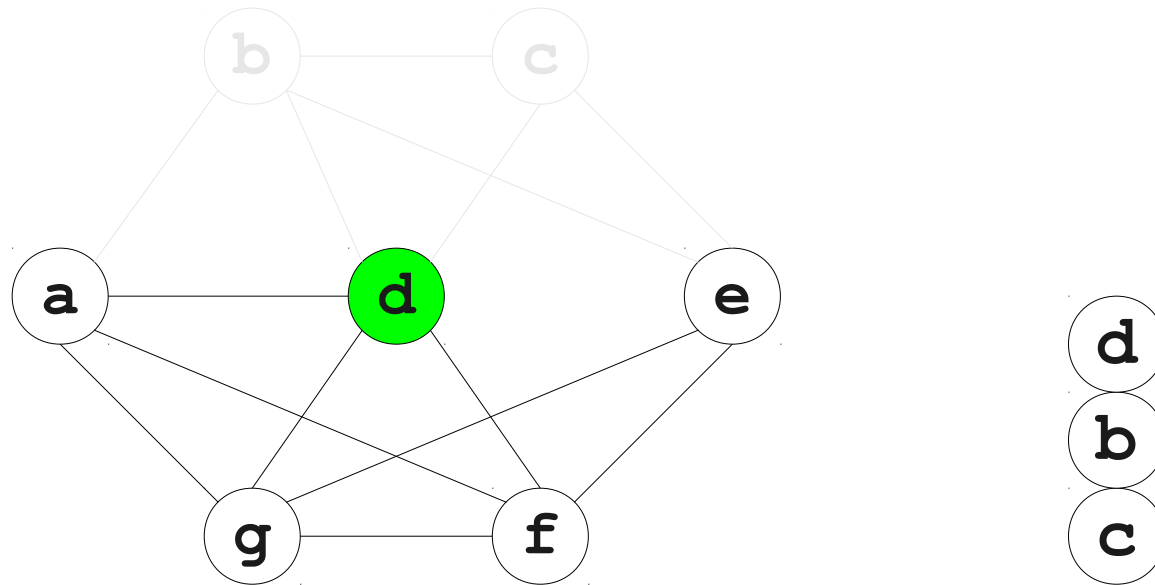
# Chaitin's Algorithm



**Registers**



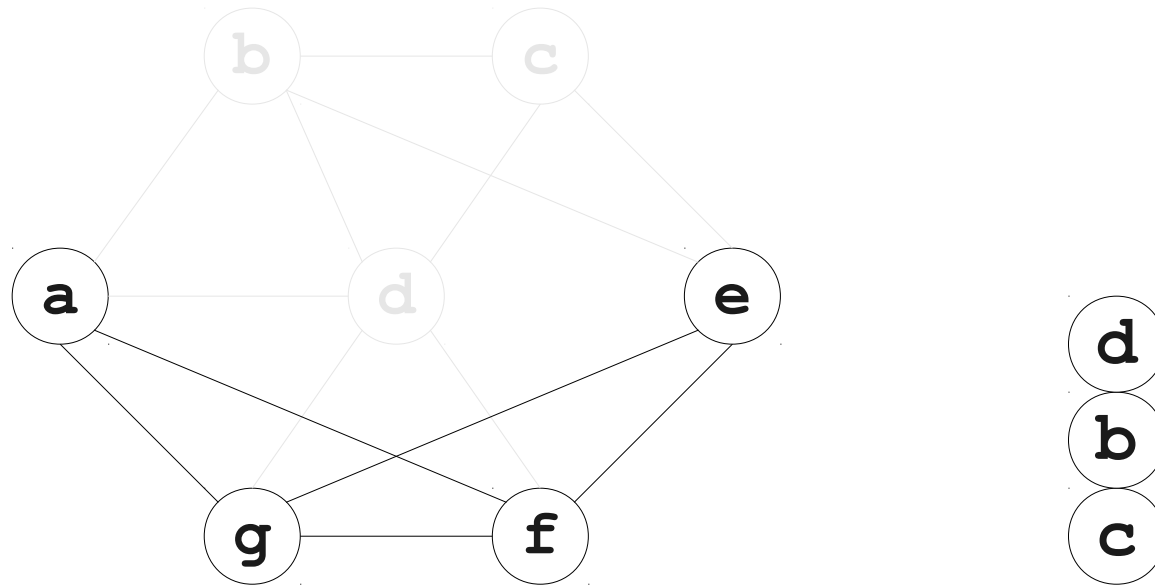
# Chaitin's Algorithm



**Registers**



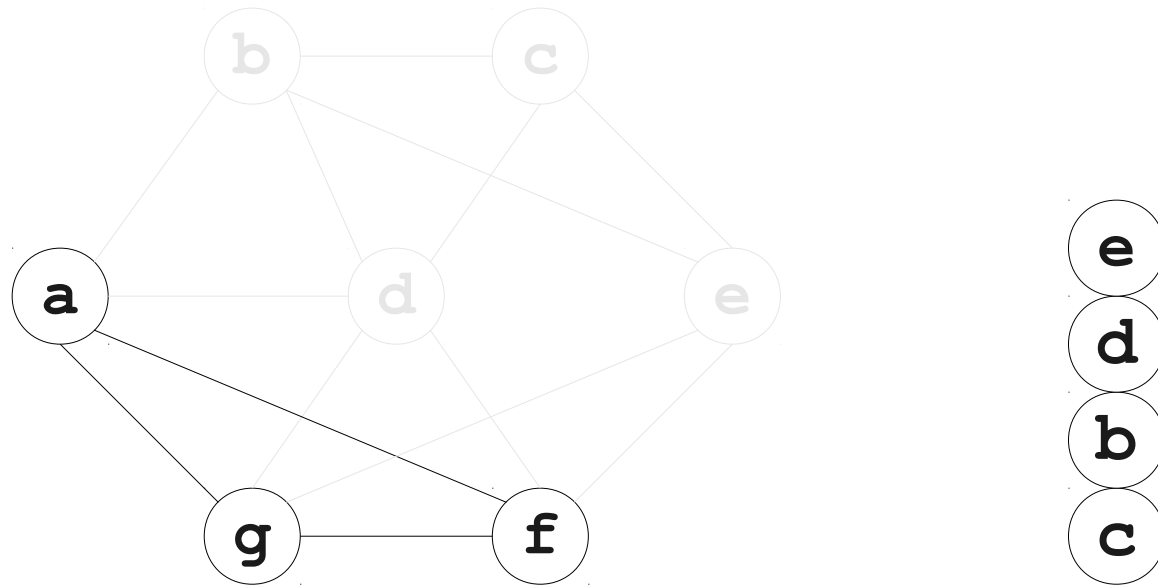
# Chaitin's Algorithm



## Registers



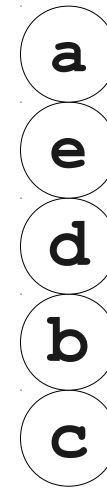
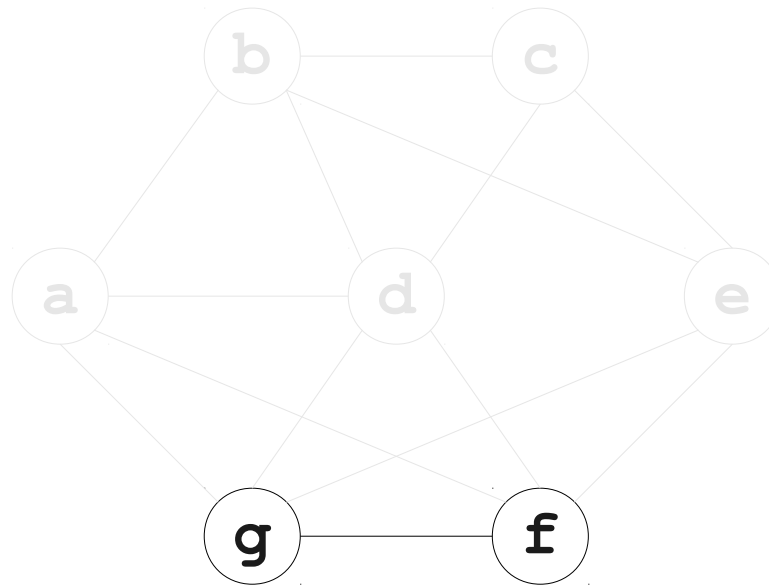
# Chaitin's Algorithm



## Registers



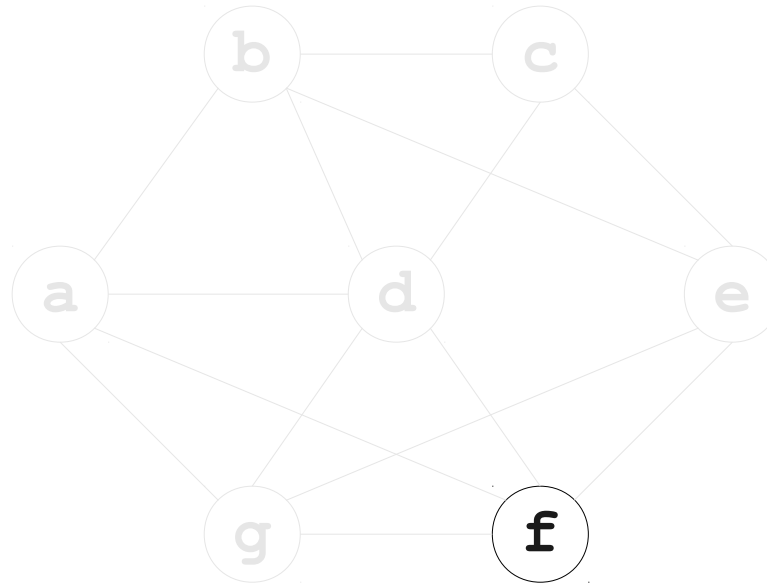
# Chaitin's Algorithm



## Registers



# Chaitin's Algorithm

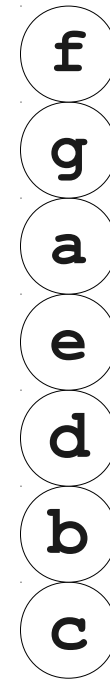


## Registers





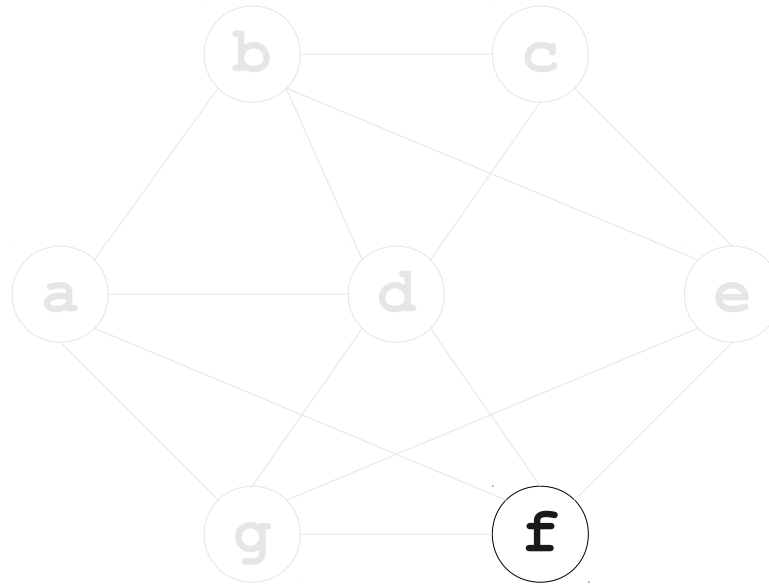
# Chaitin's Algorithm



## Registers



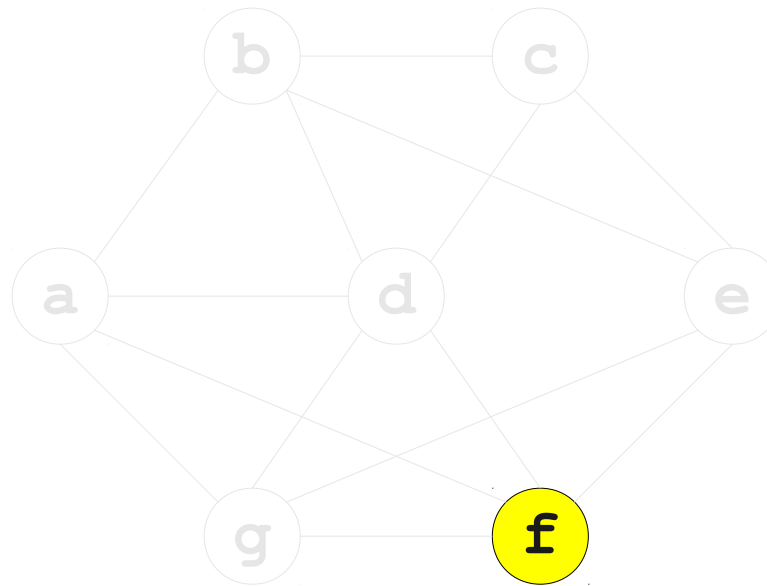
# Chaitin's Algorithm



## Registers



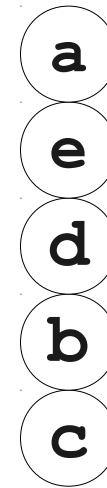
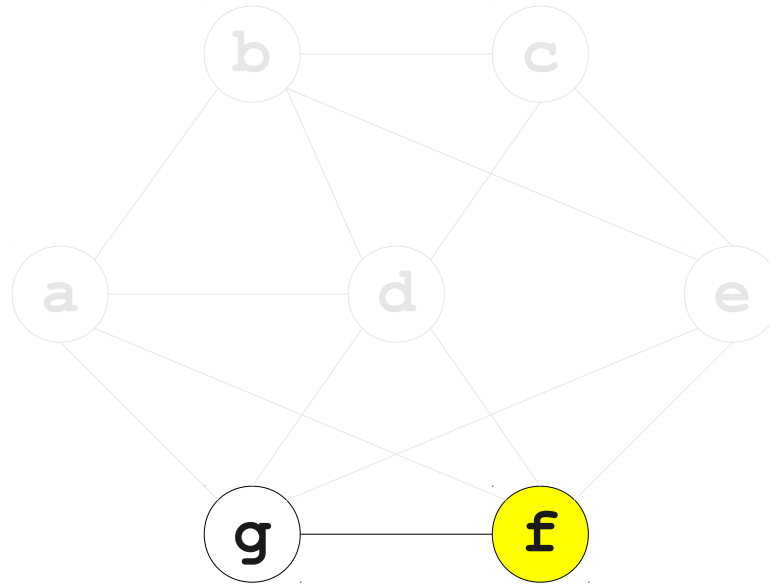
# Chaitin's Algorithm



## Registers



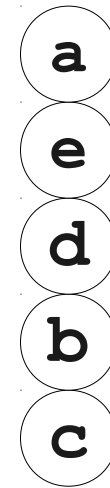
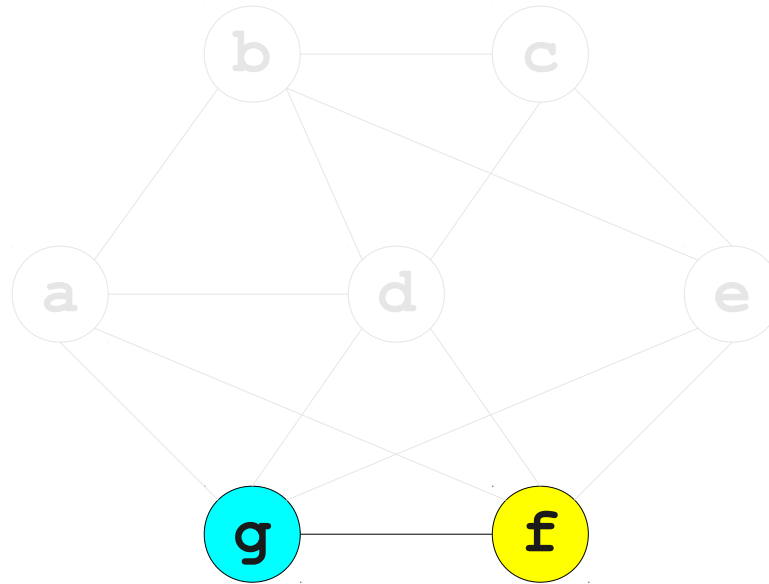
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## Registers



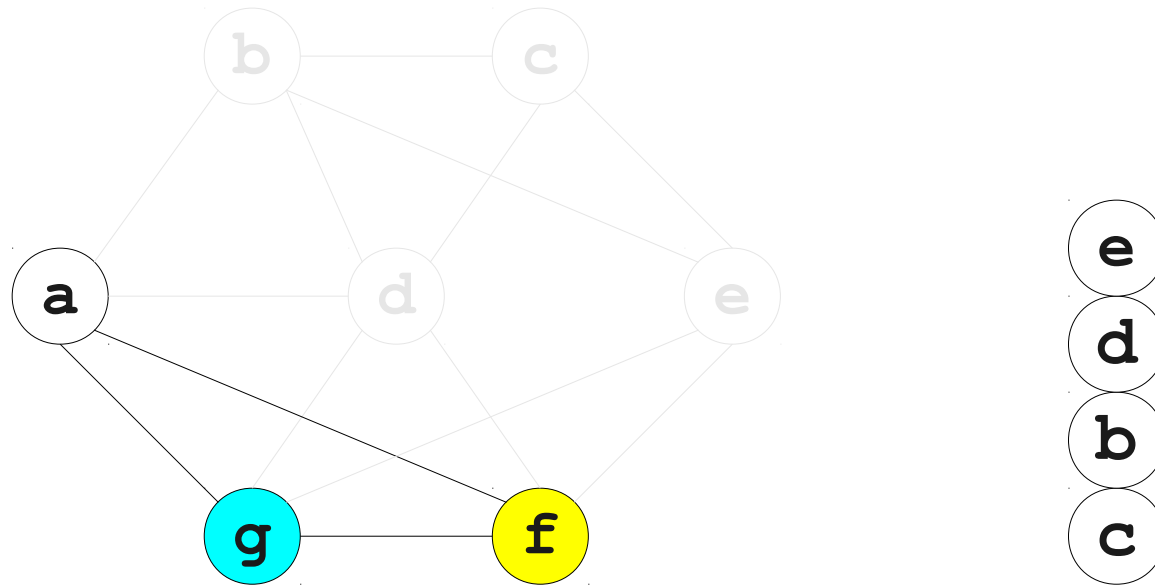
# Chaitin's Algorithm



## Registers



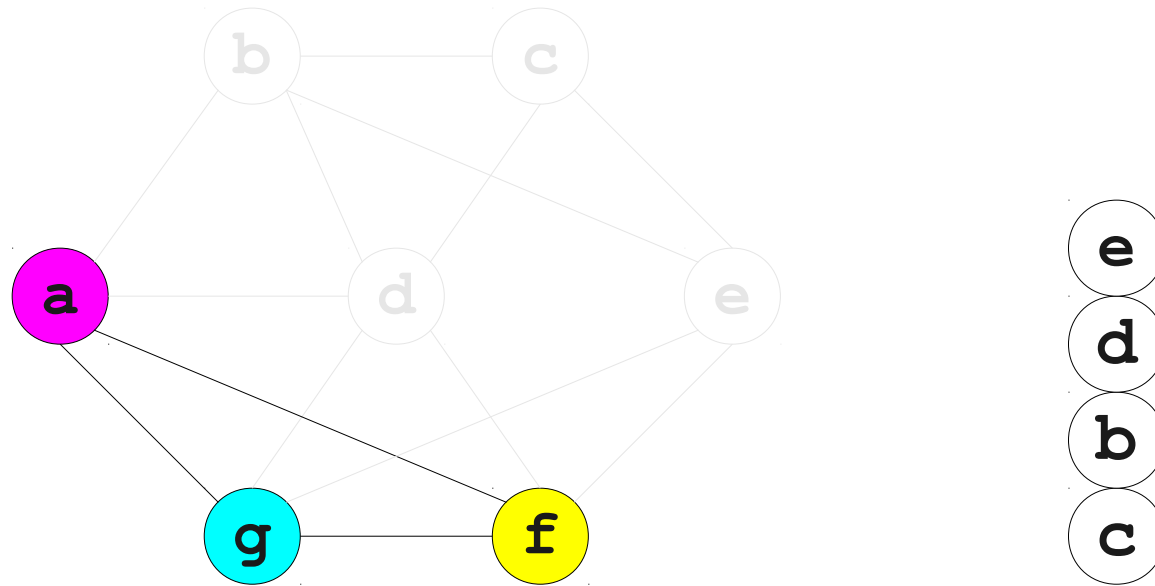
# Chaitin's Algorithm



## Registers



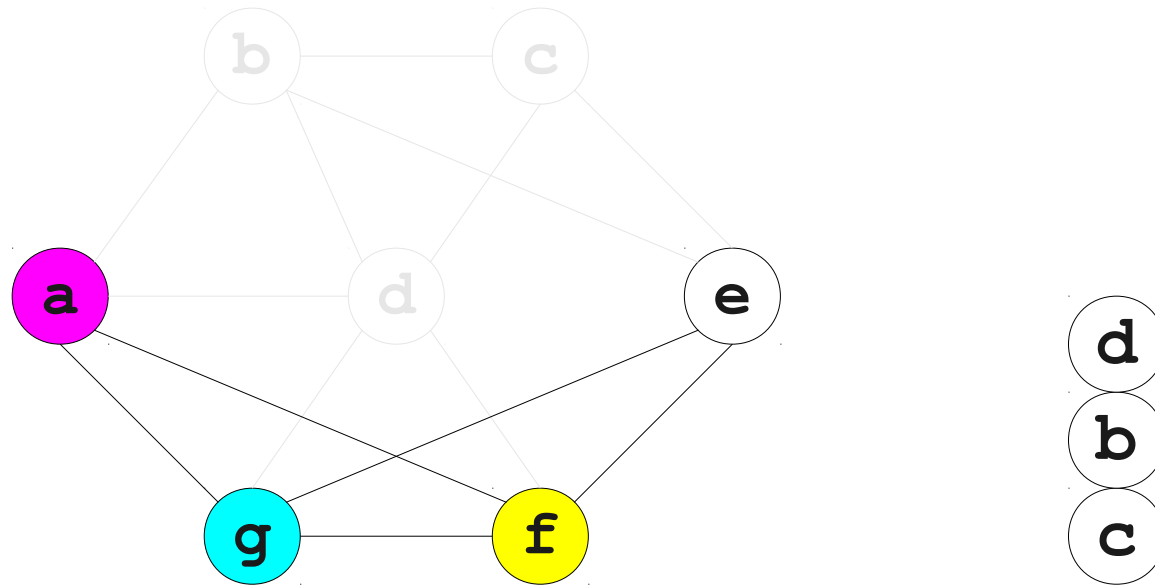
# Chaitin's Algorithm



**Registers**



# Chaitin's Algorithm

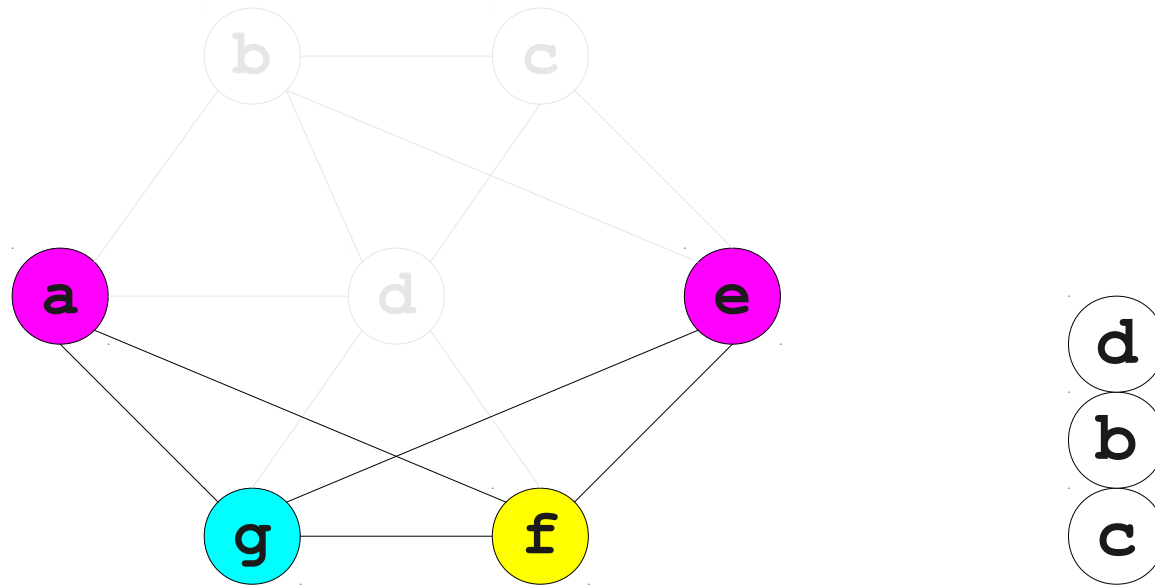


**Registers**





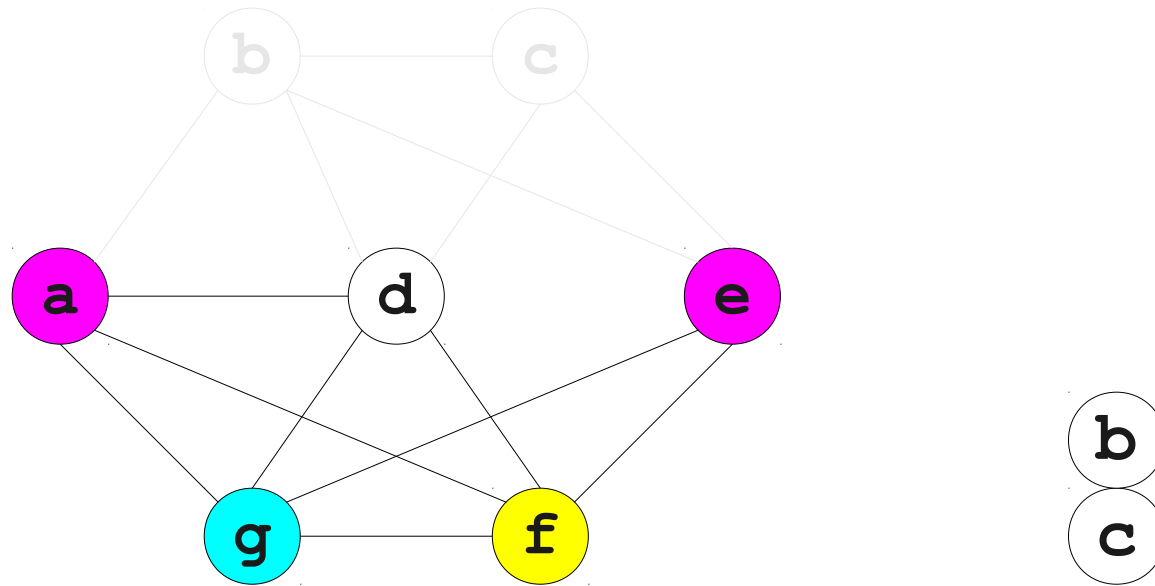
# Chaitin's Algorithm



**Registers**



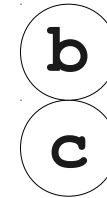
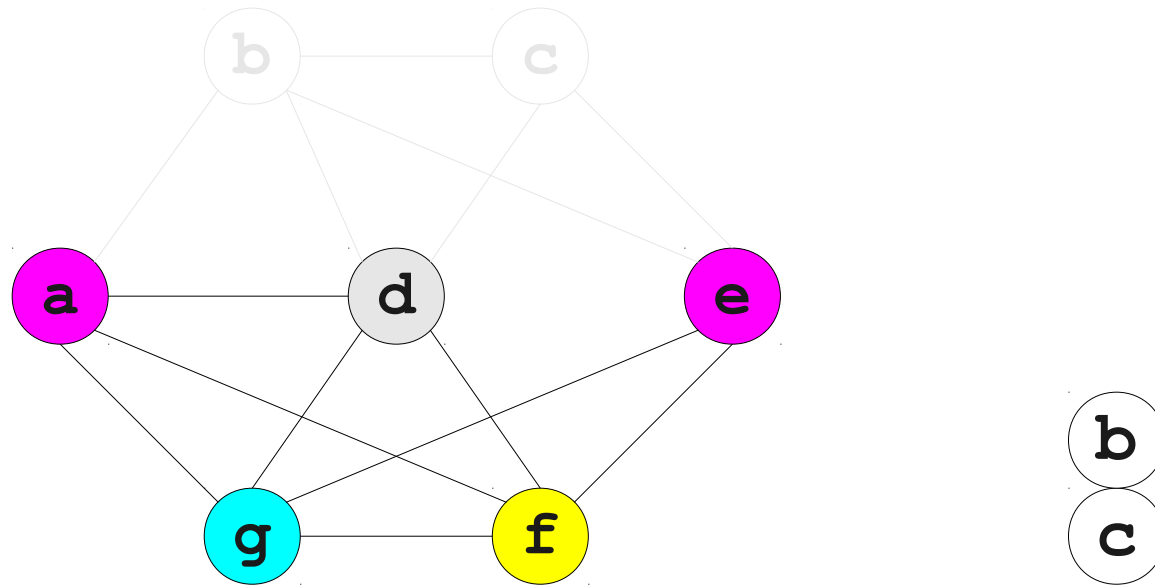
# Chaitin's Algorithm



**Registers**



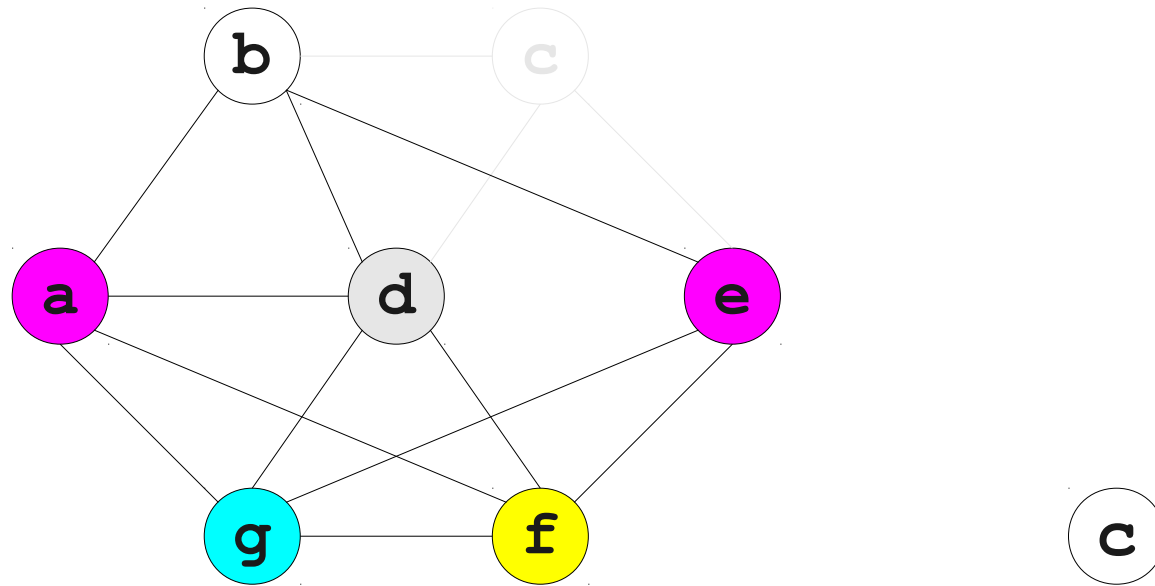
# Chaitin's Algorithm



**Registers**



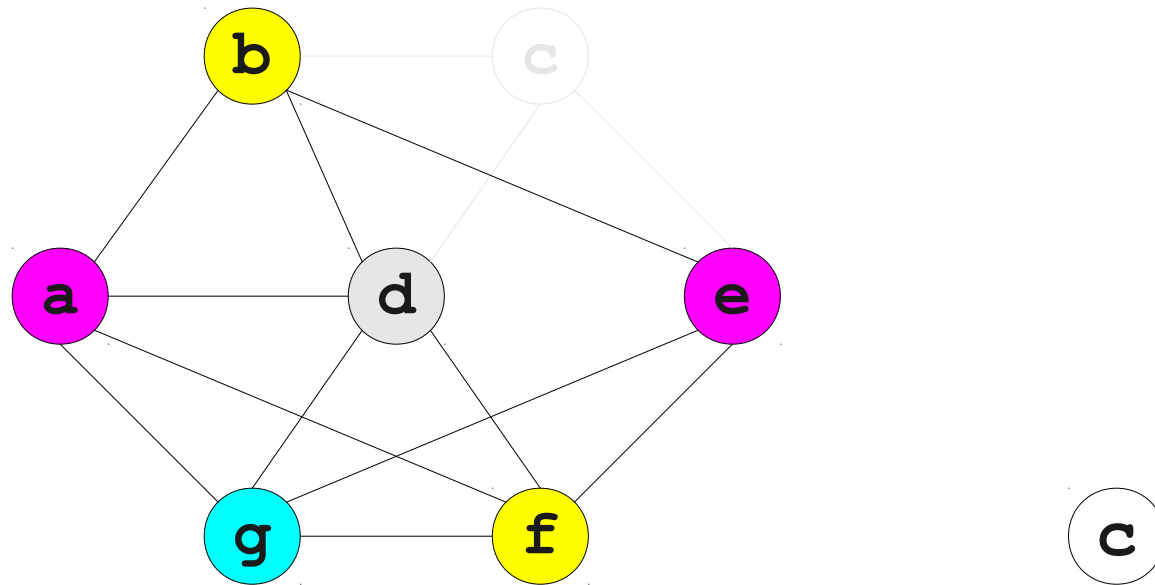
# Chaitin's Algorithm



**Registers**



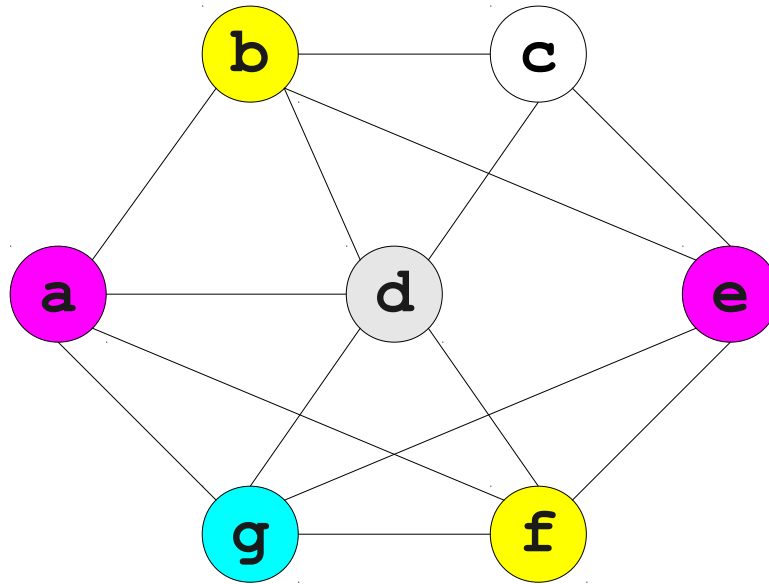
# Chaitin's Algorithm



**Registers**



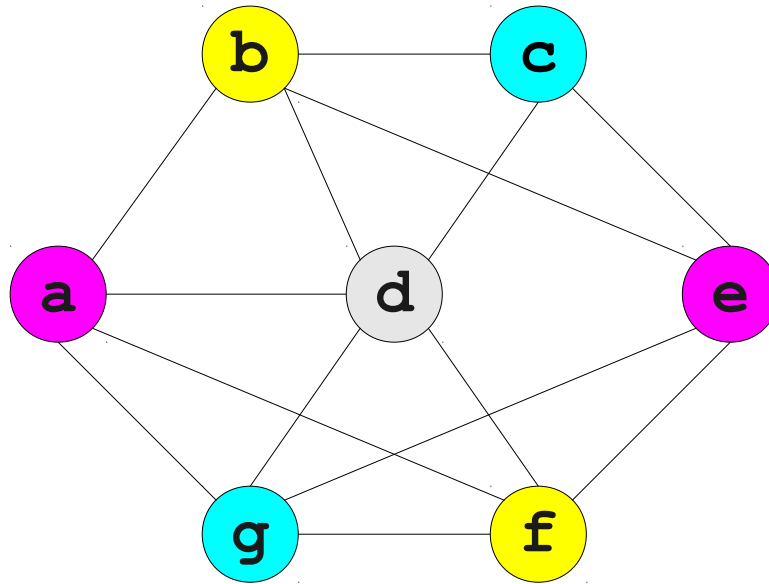
# Chaitin's Algorithm



## Registers



# Chaitin's Algorithm



## Registers

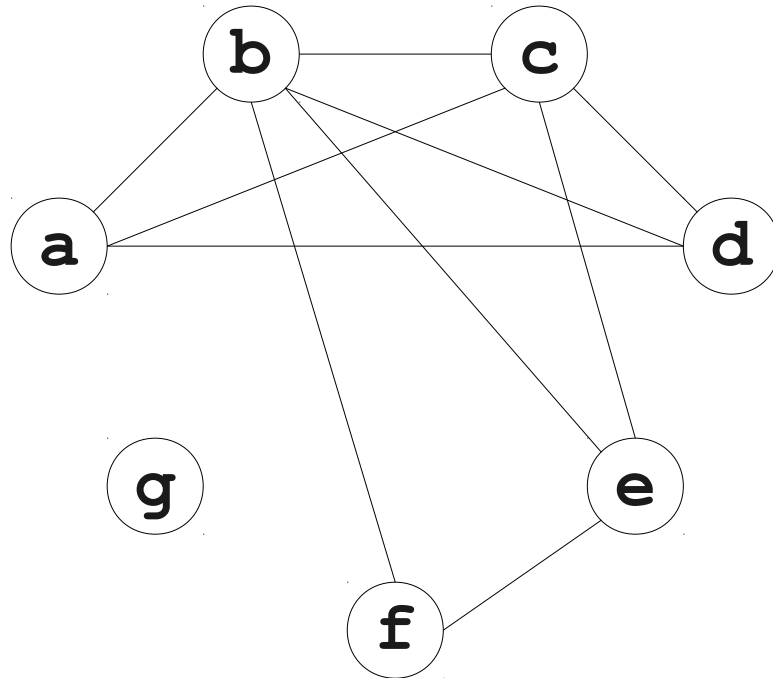


# One Problem

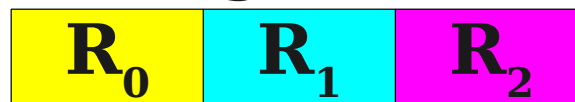
- What if we can't find a node with fewer than  $k$  neighbors?
- Choose and remove an arbitrary node, marking it “troublesome.”
  - Use heuristics to choose which one.
- When adding node back in, it may be possible to find a valid color.
- Otherwise, we have to spill that node.



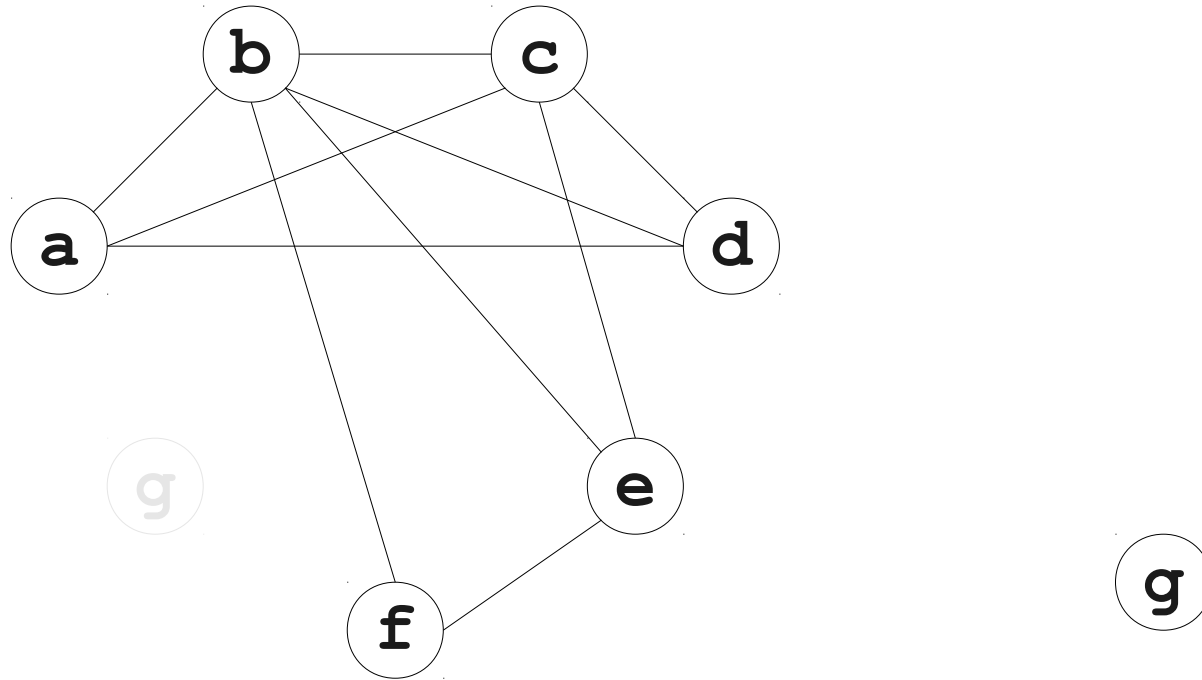
# Chaitin's Algorithm Reloaded



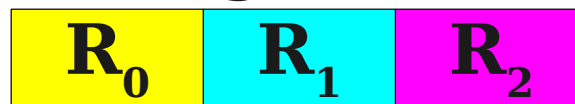
**Registers**



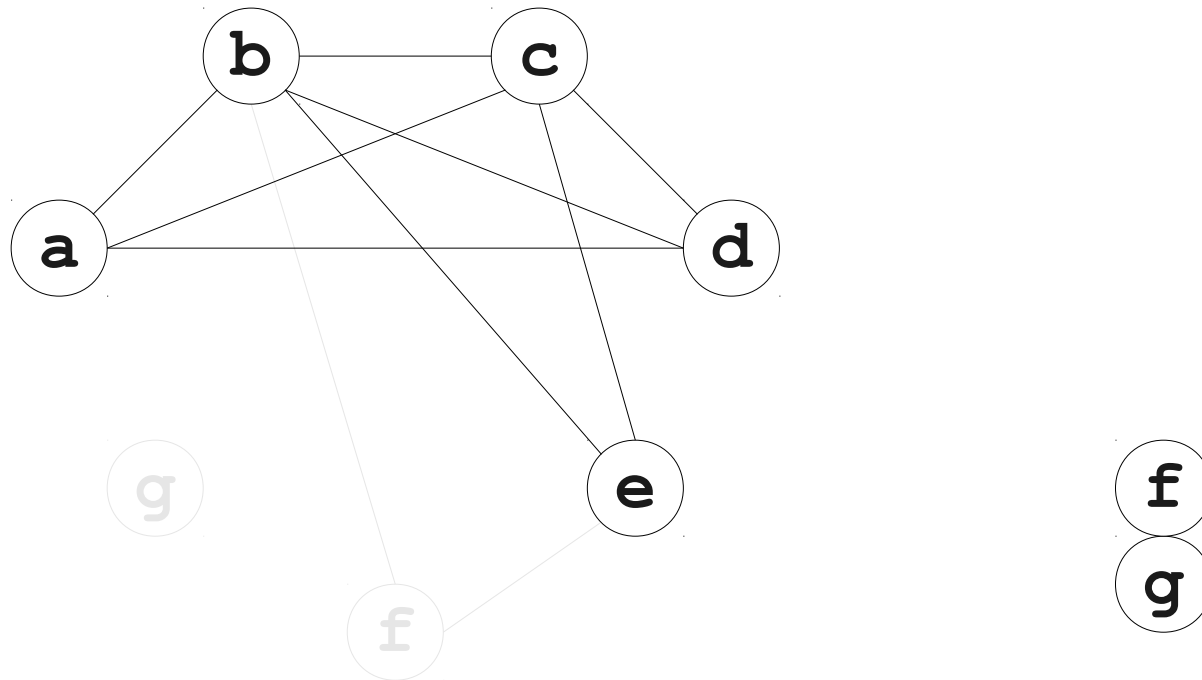
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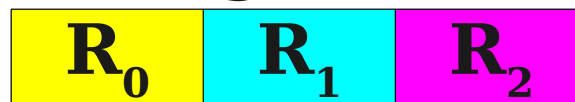
**Registers**



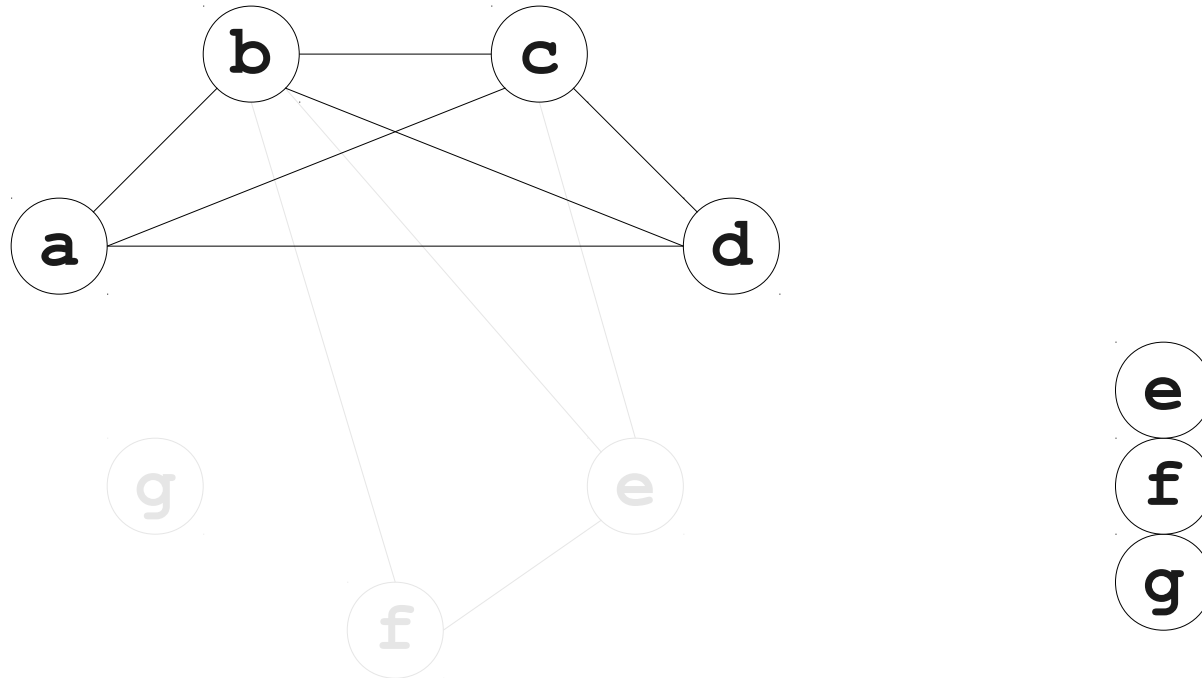
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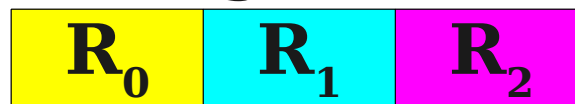
**Registers**



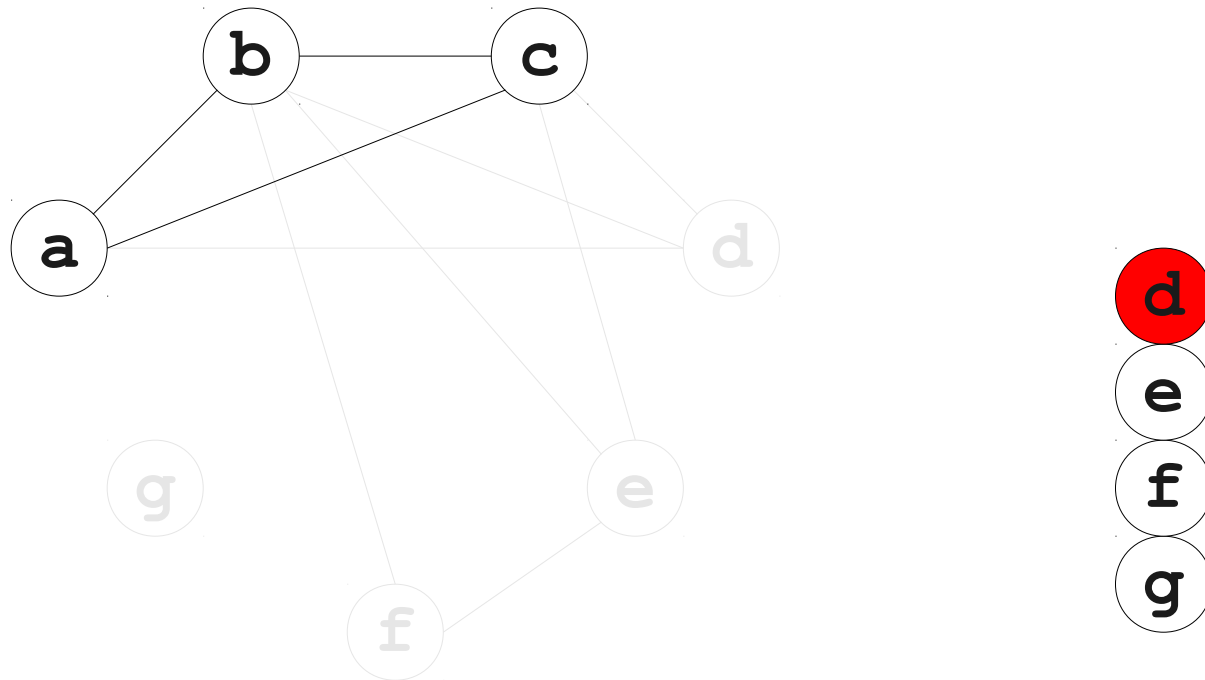
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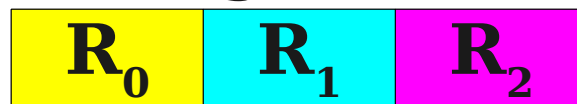
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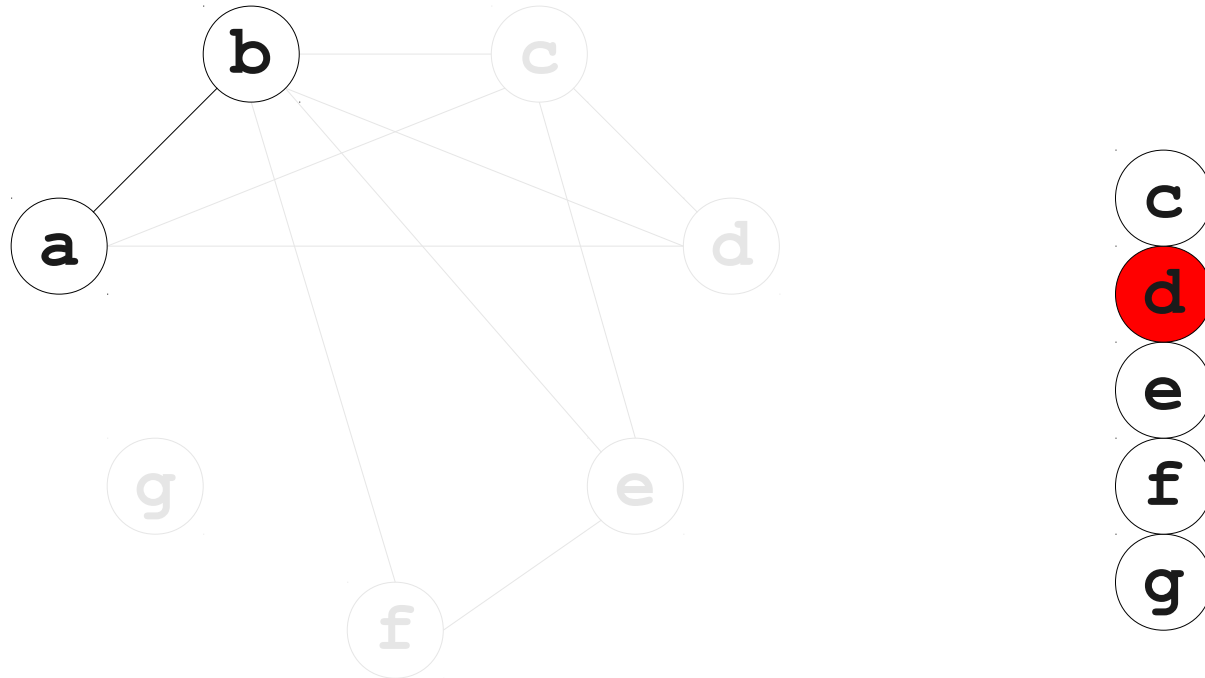
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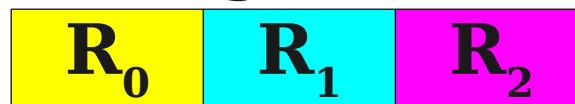
**Registers**



# Chaitin's Algorithm Reloaded



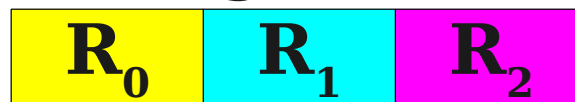
**Registers**



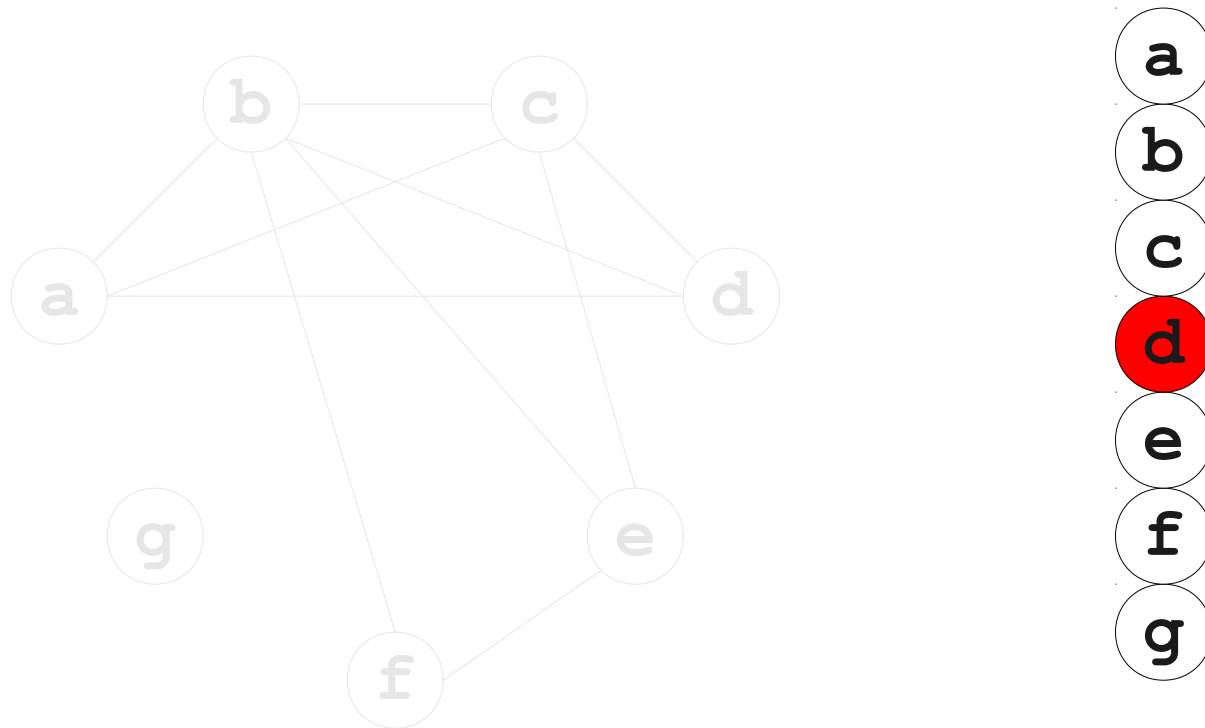
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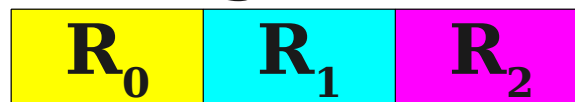
**Registers**



# Chaitin's Algorithm Reloaded



**Registers**

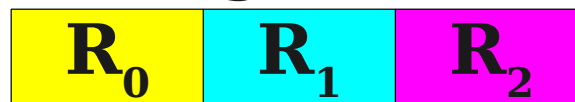




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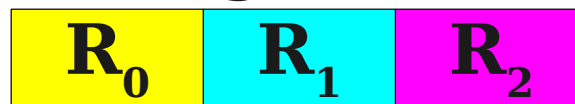
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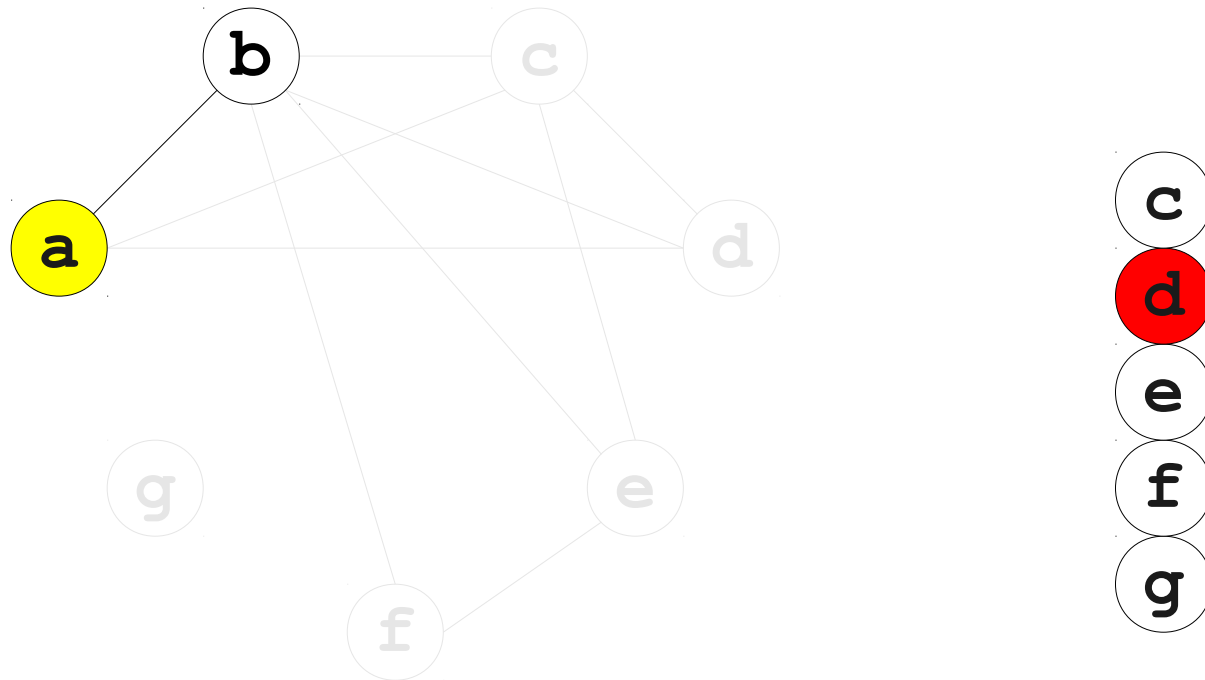
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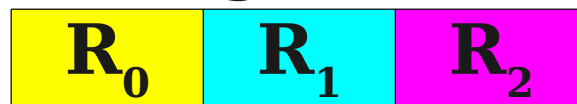
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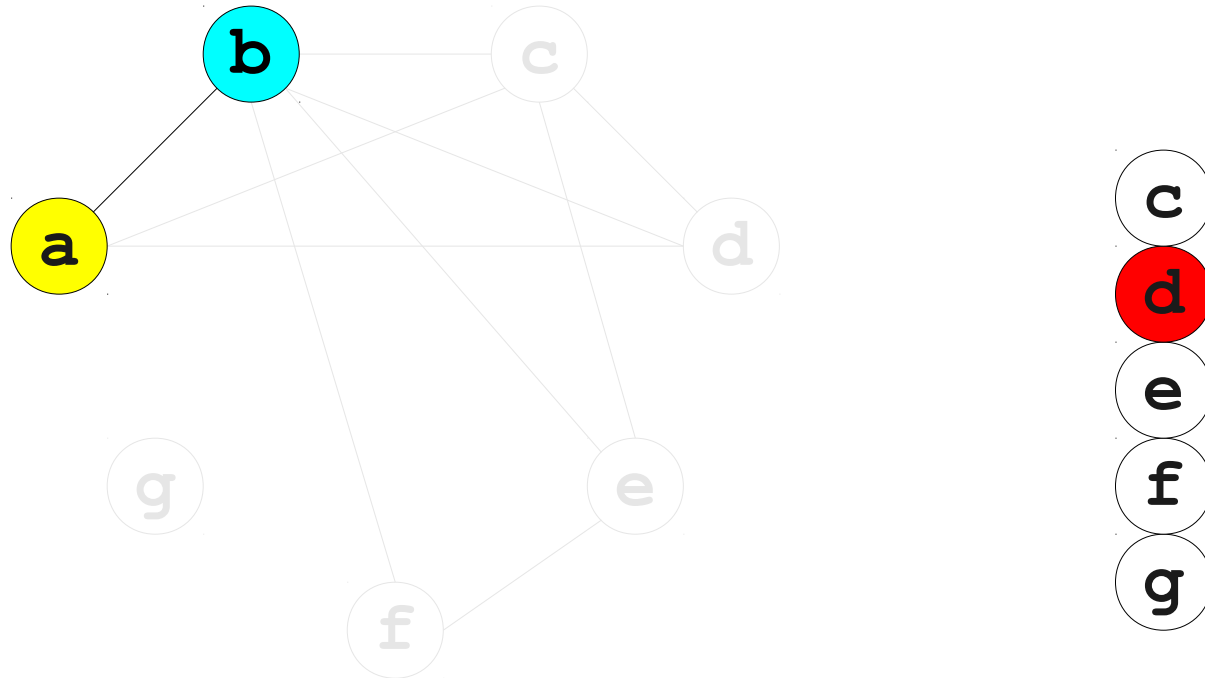
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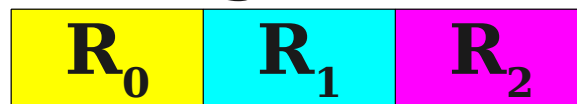
**Registers**



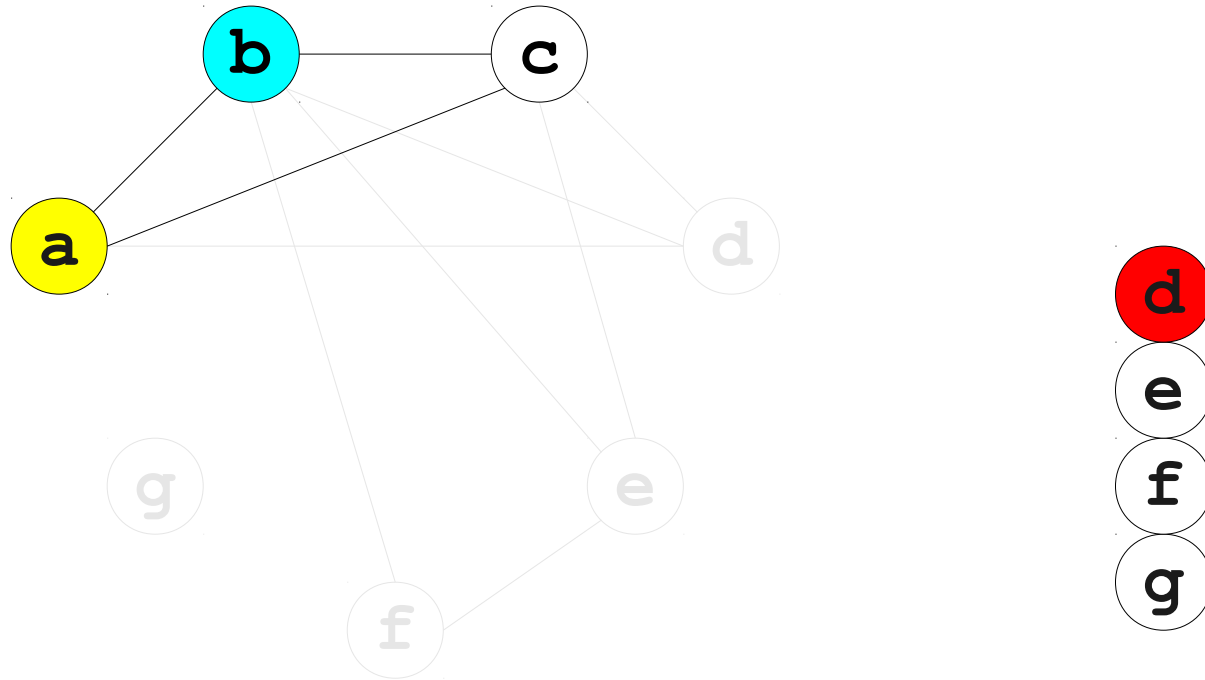
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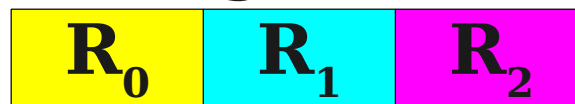
**Registers**



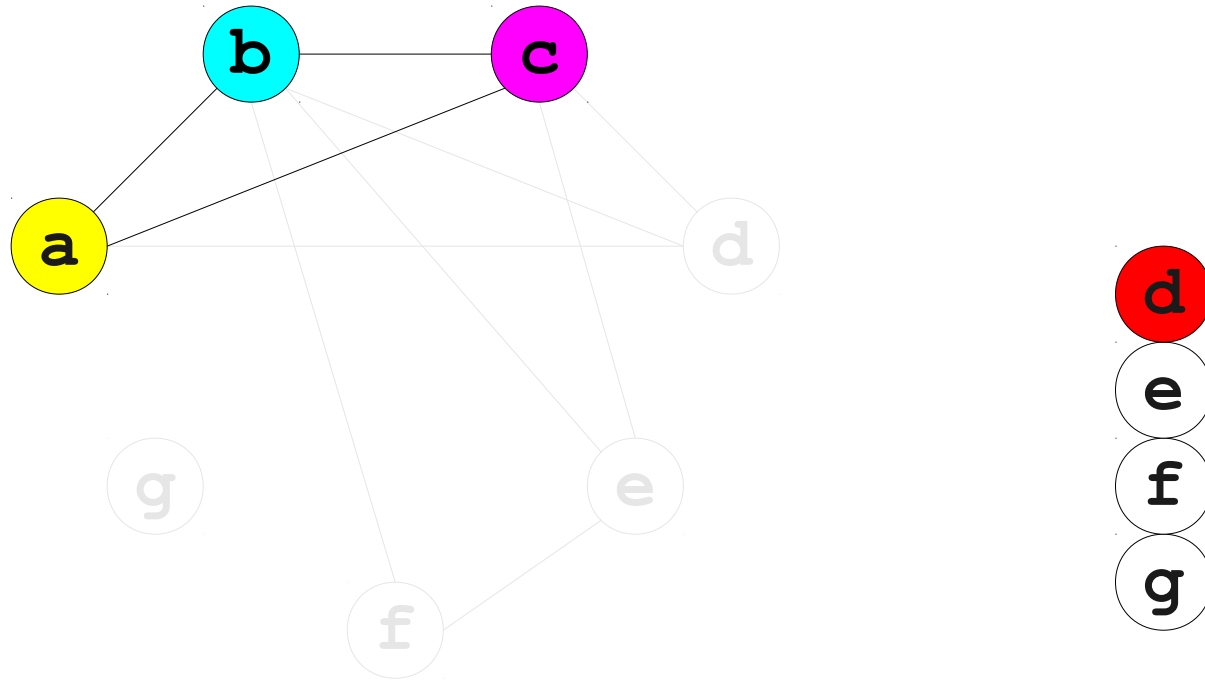
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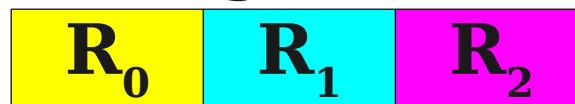
**Registers**



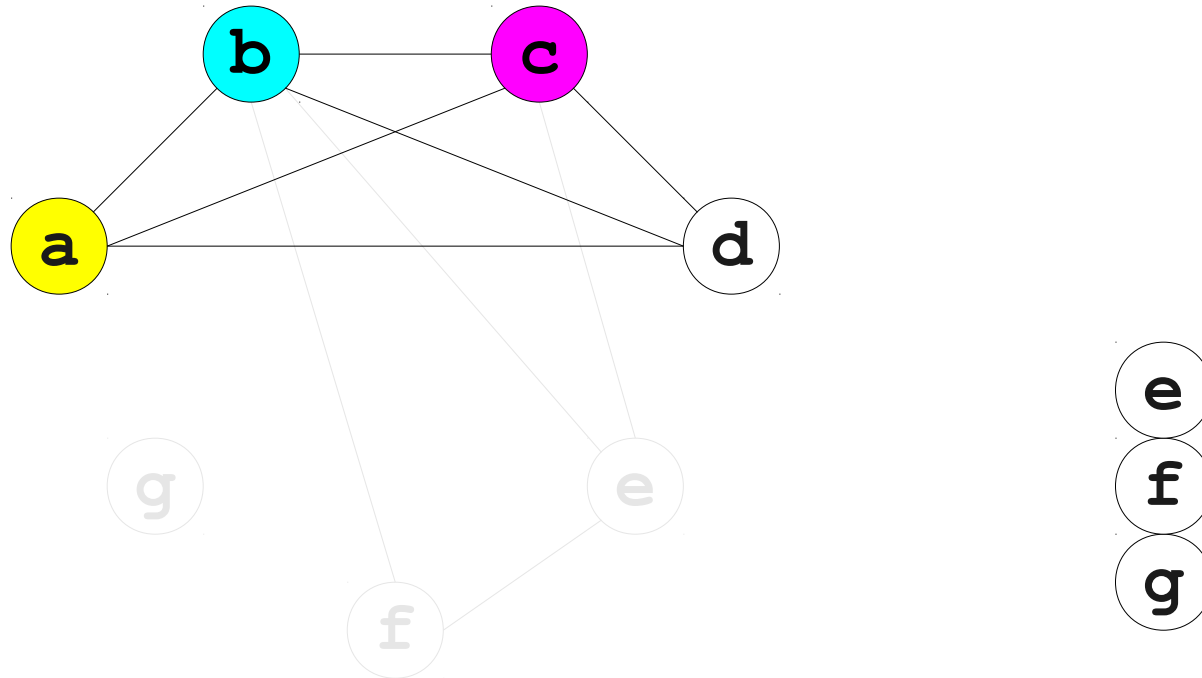
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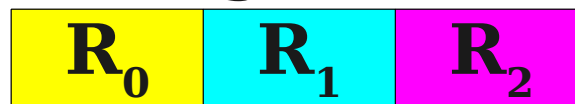
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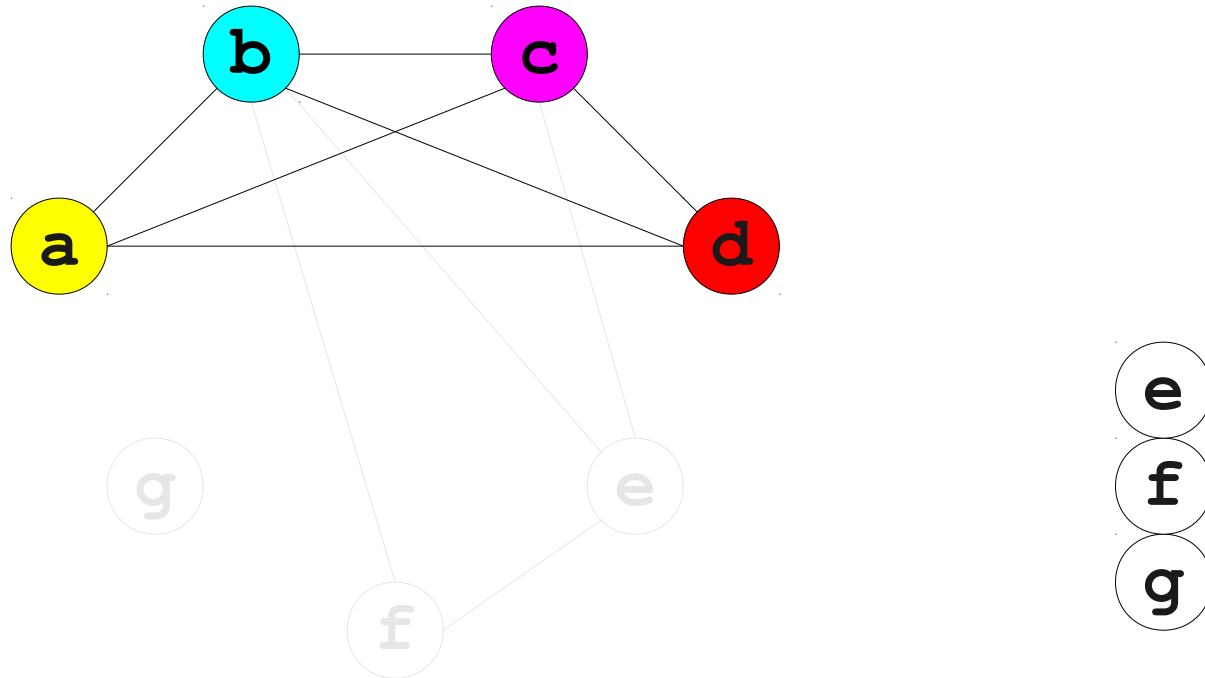
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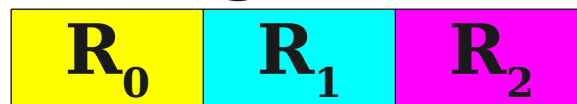
**Registers**



# Chaitin's Algorithm Reloaded

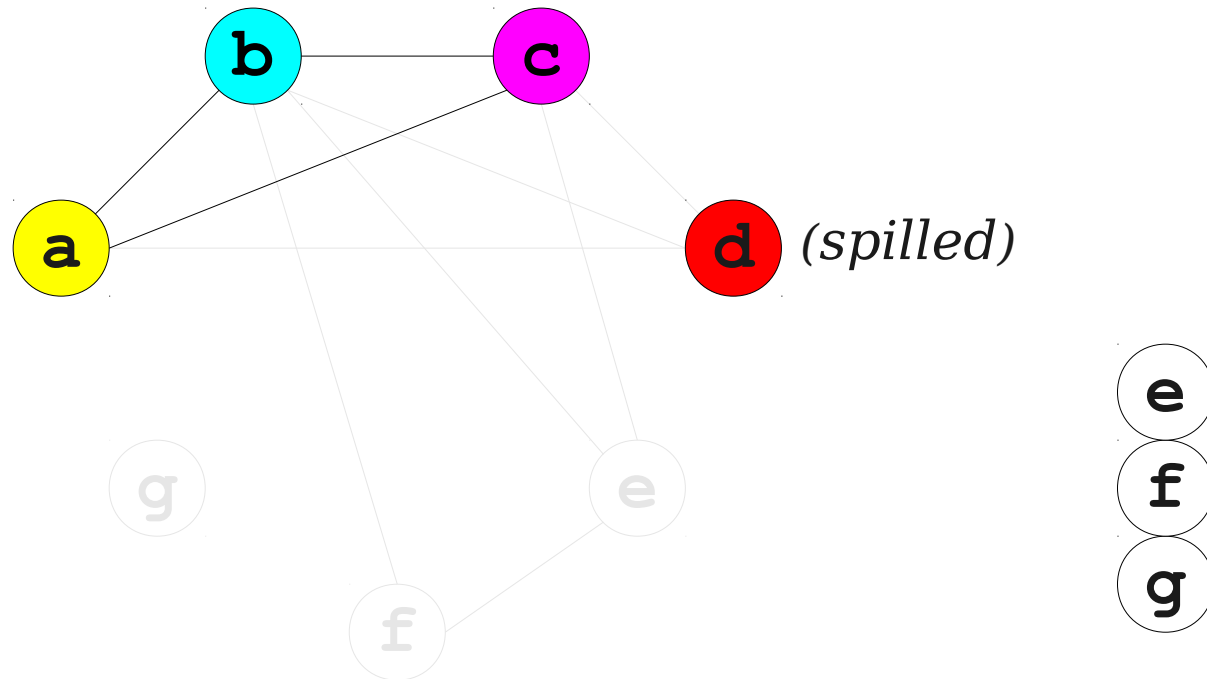


**Registers**

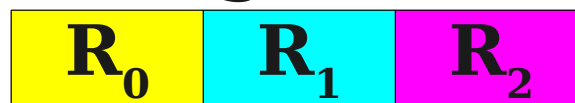




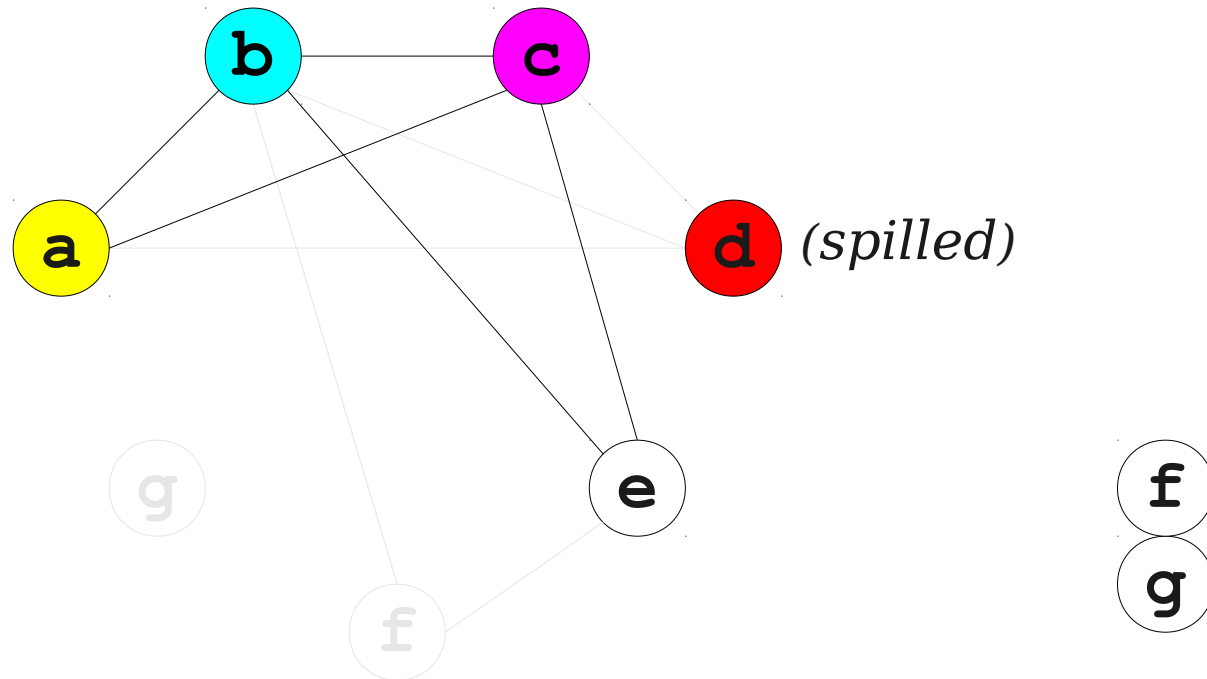
# Chaitin's Algorithm Reloaded



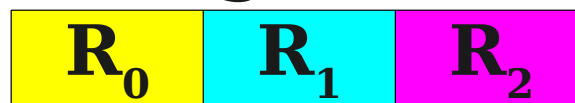
**Registers**



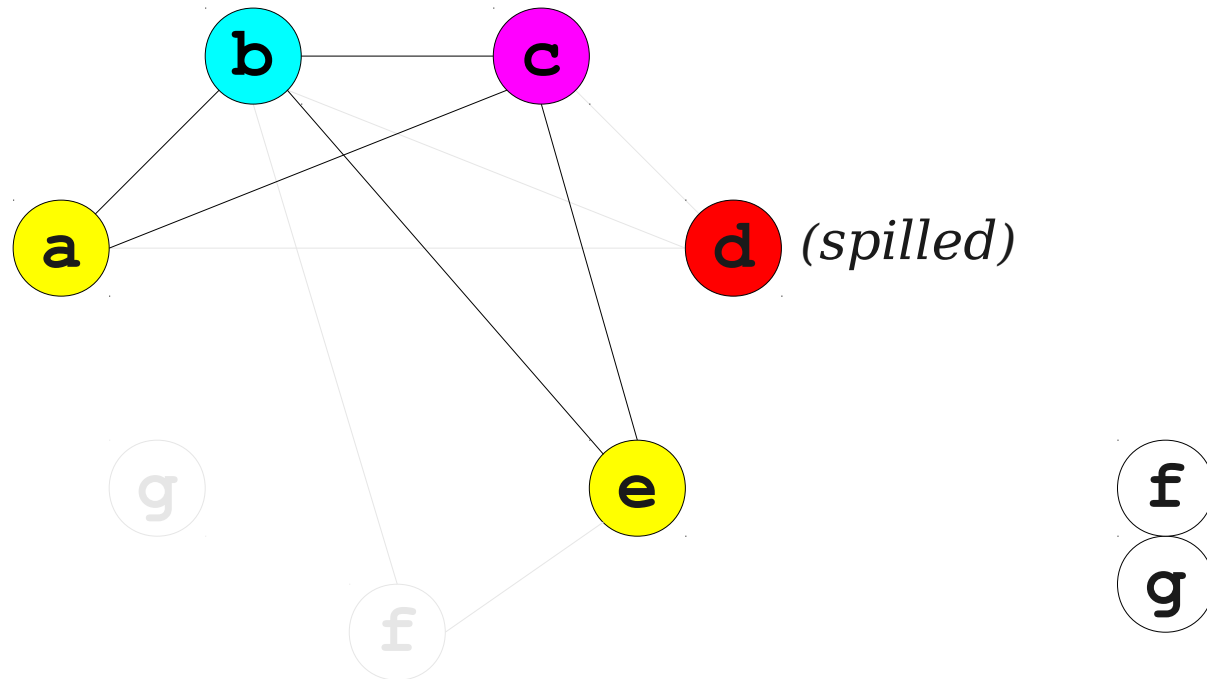
# Chaitin's Algorithm Reloaded



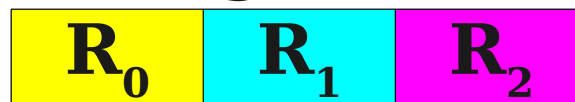
## Registers



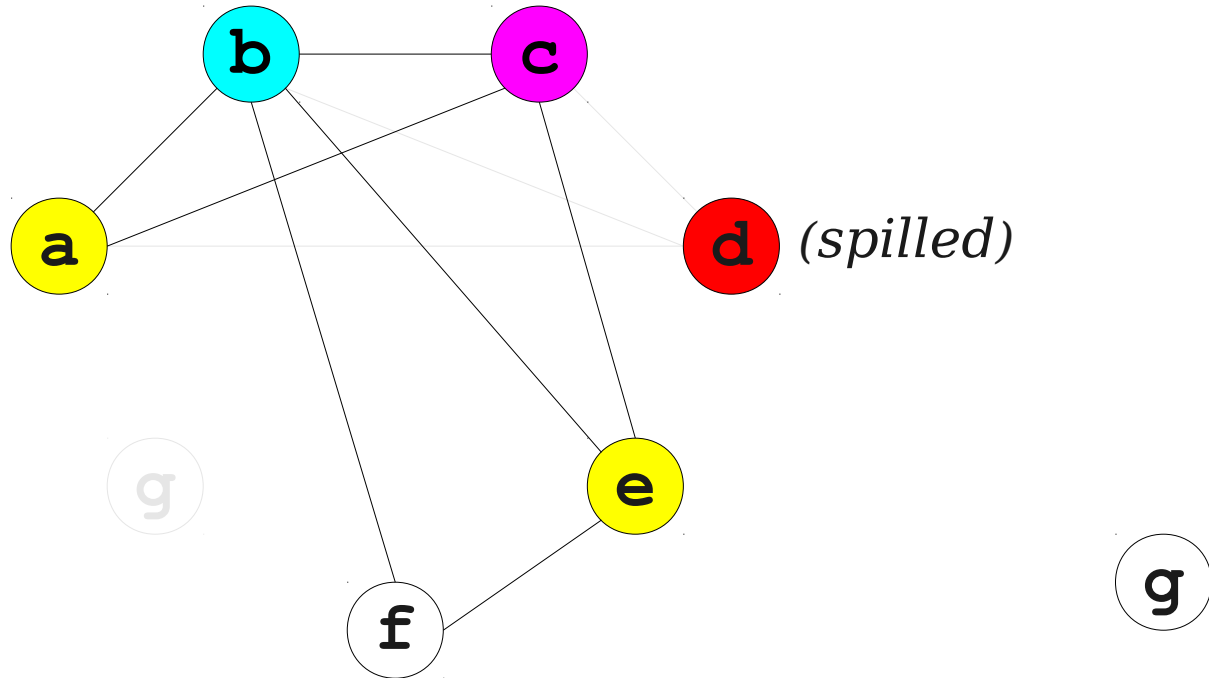
# Chaitin's Algorithm Reloaded



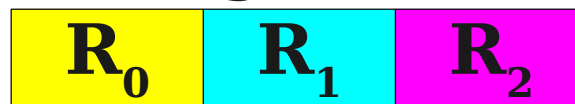
## Registers



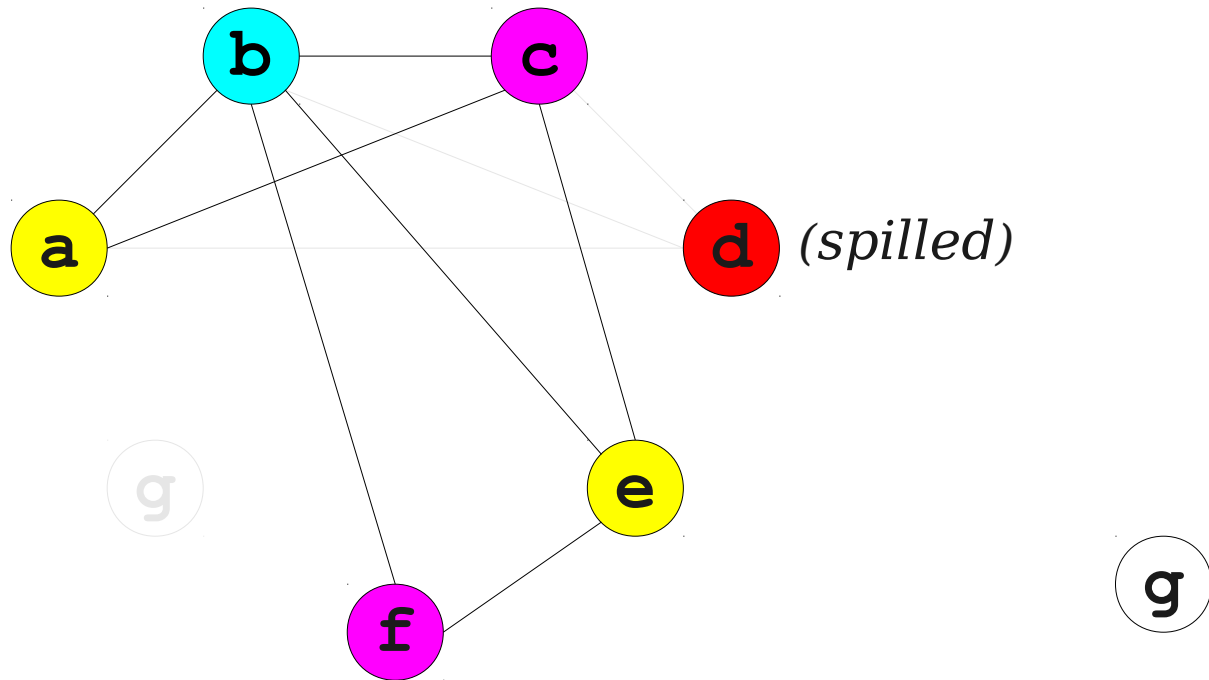
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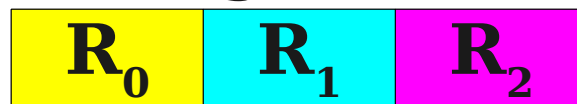
## Registers



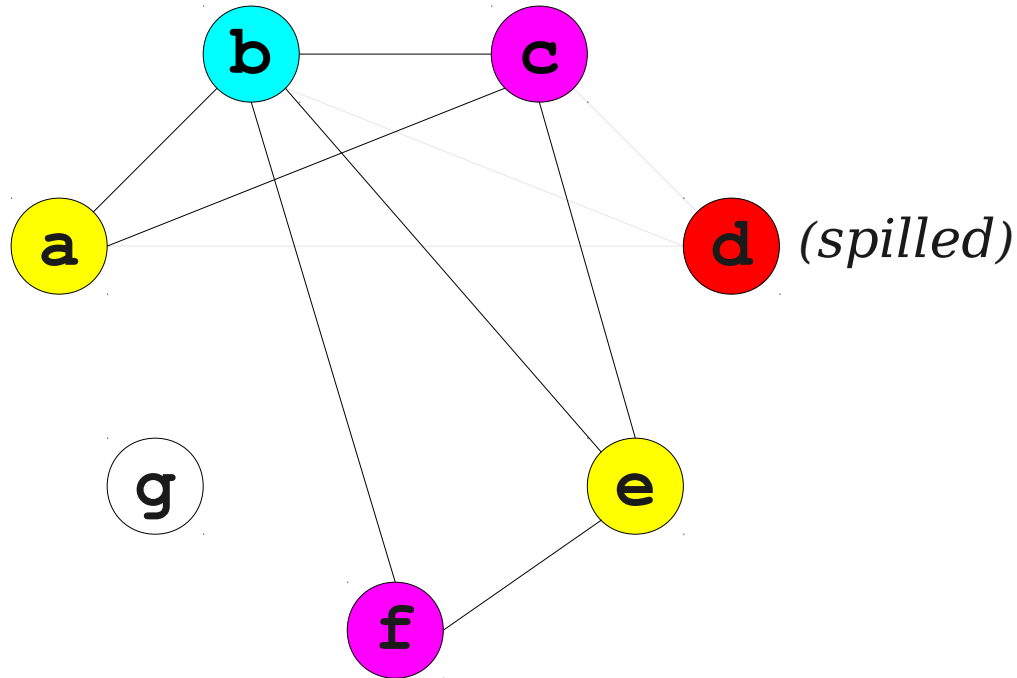
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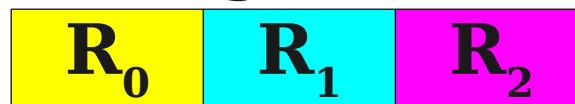
## Registers



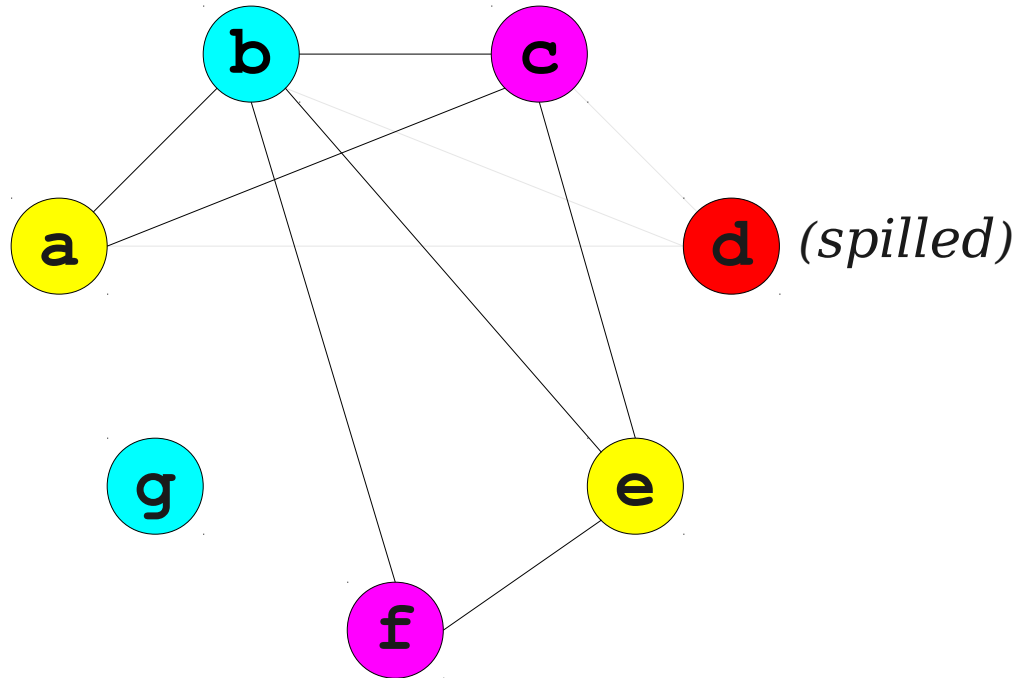
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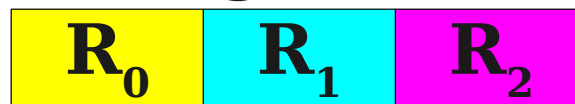
## Registers



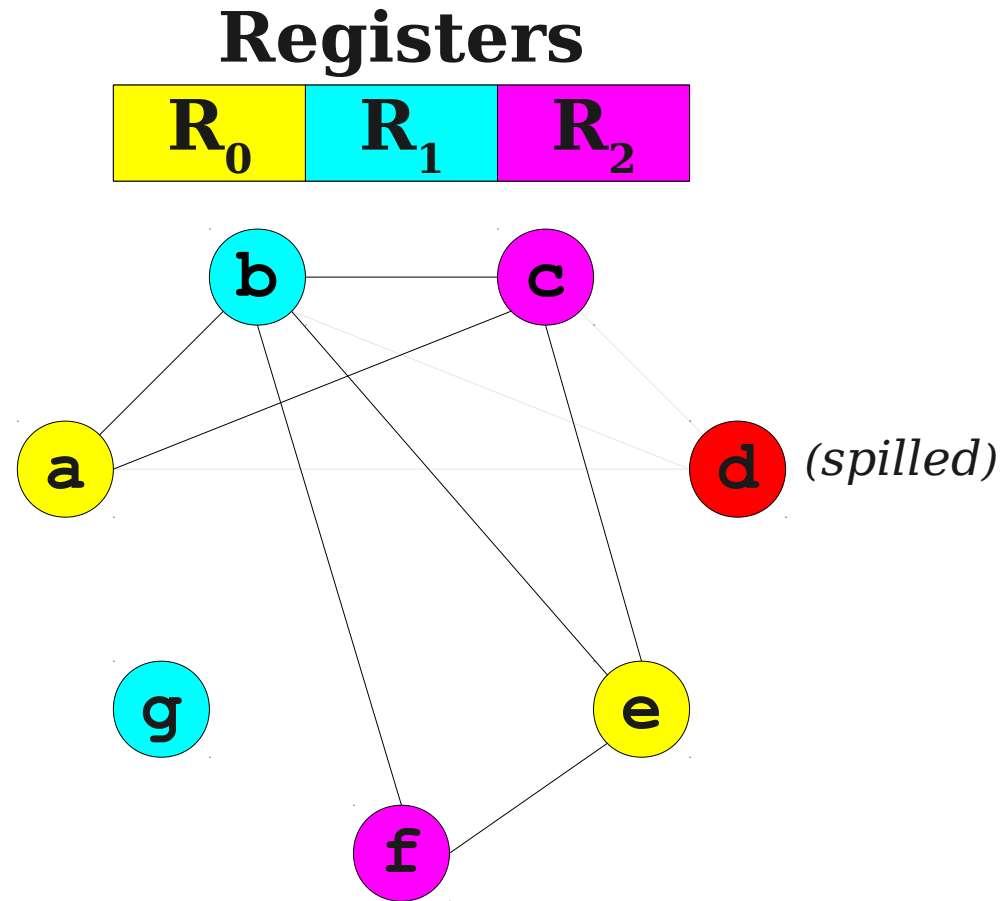
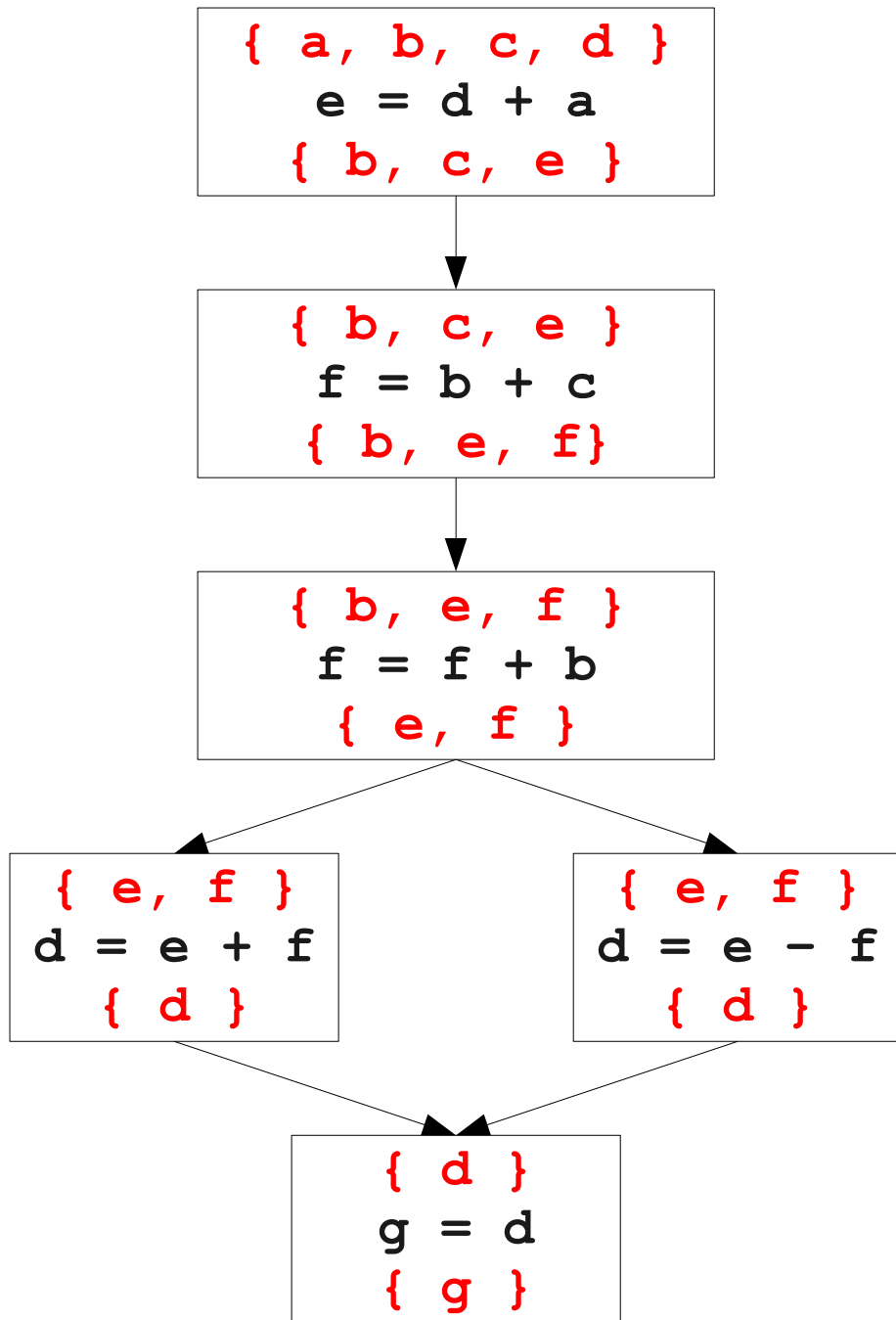
# Chaitin's Algorithm Reloaded



**Registers**

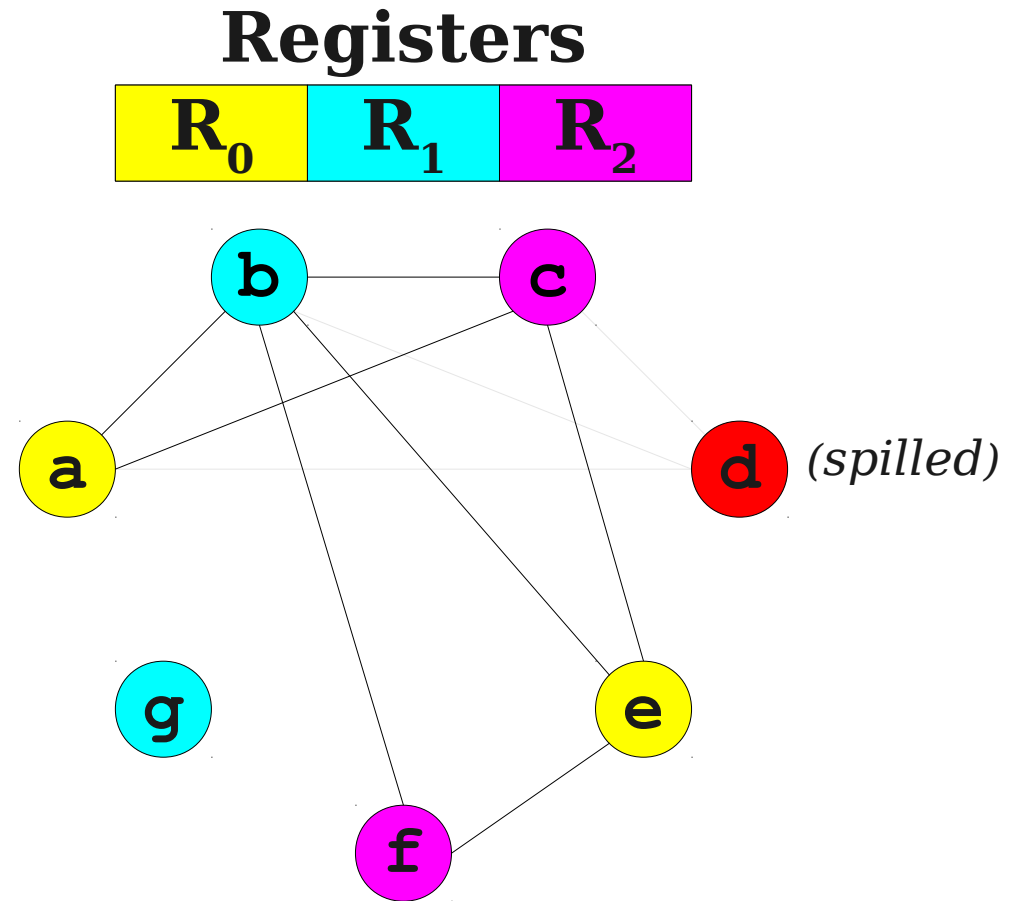
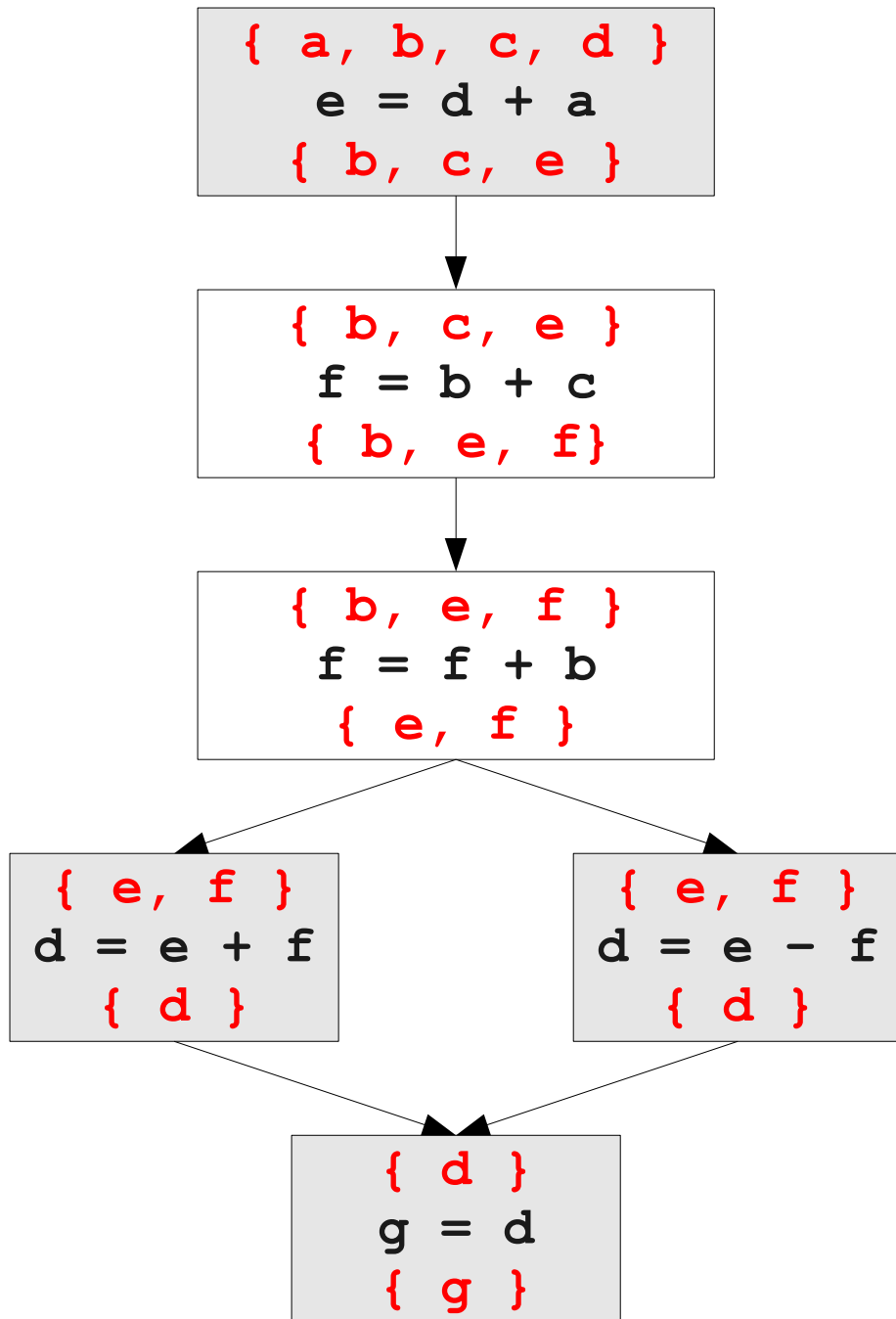


# A Smarter Algorithm

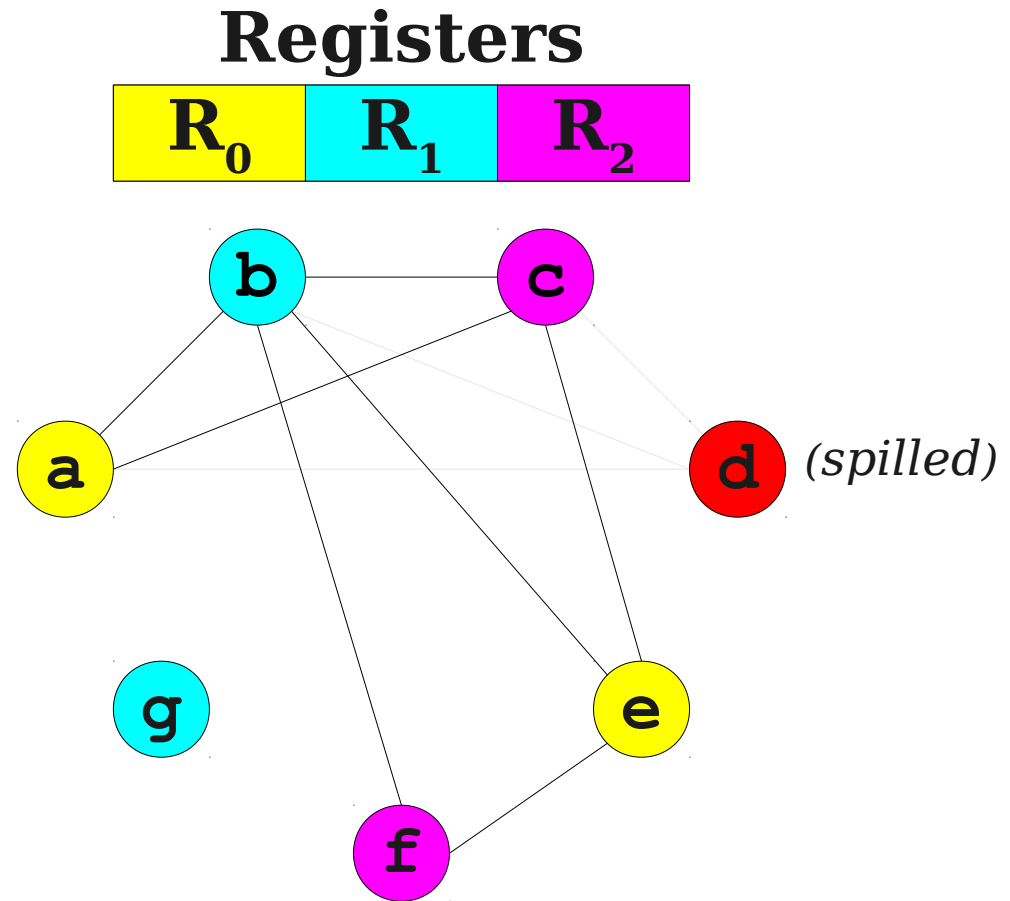
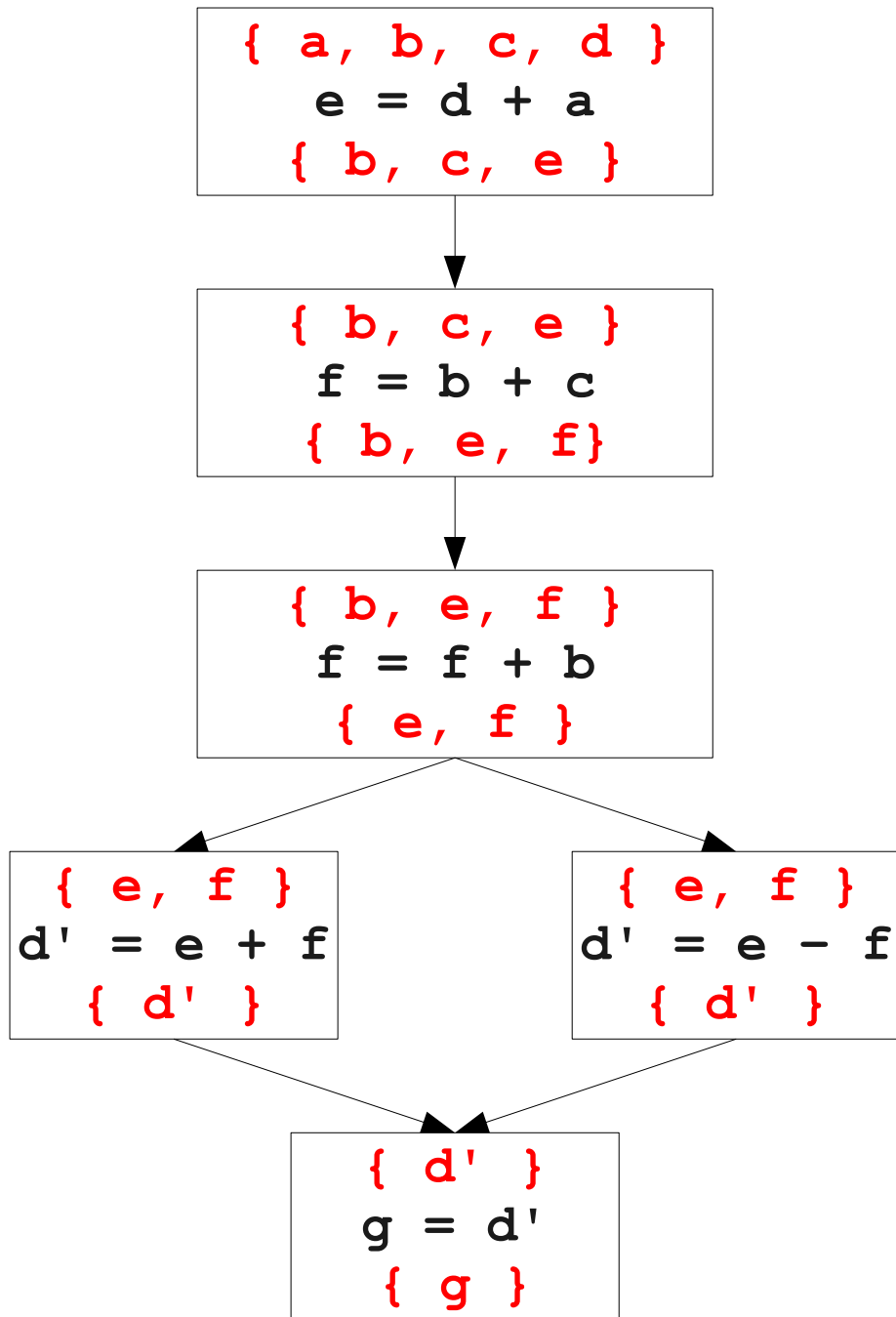




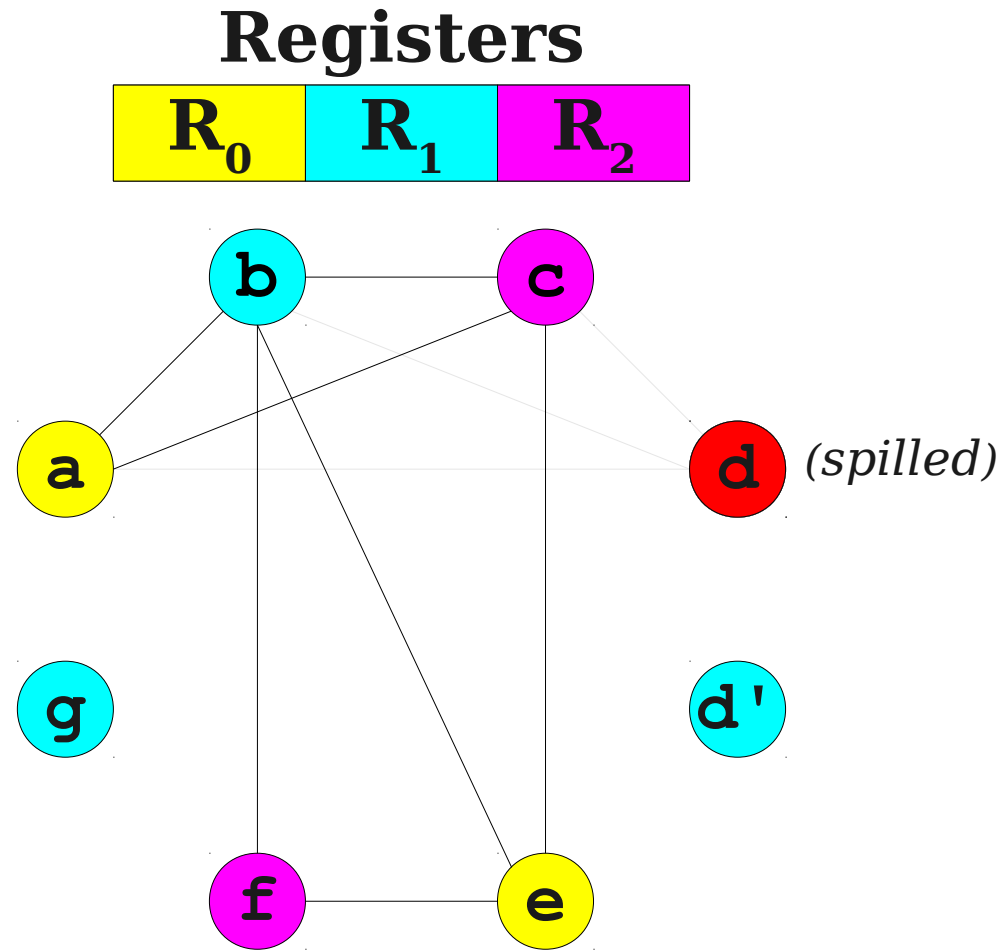
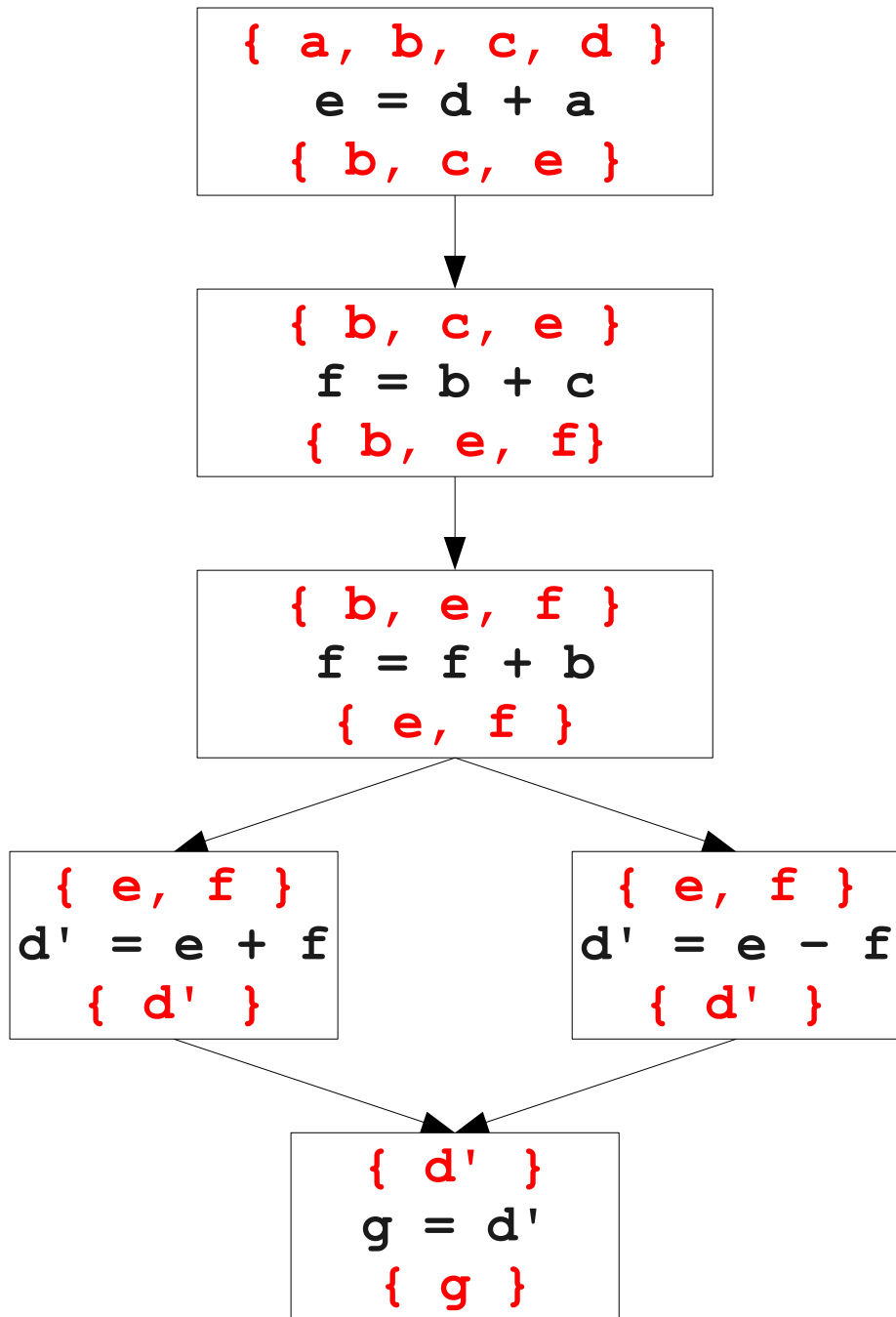
# A Smarter Algorithm



# A Smarter Algorithm

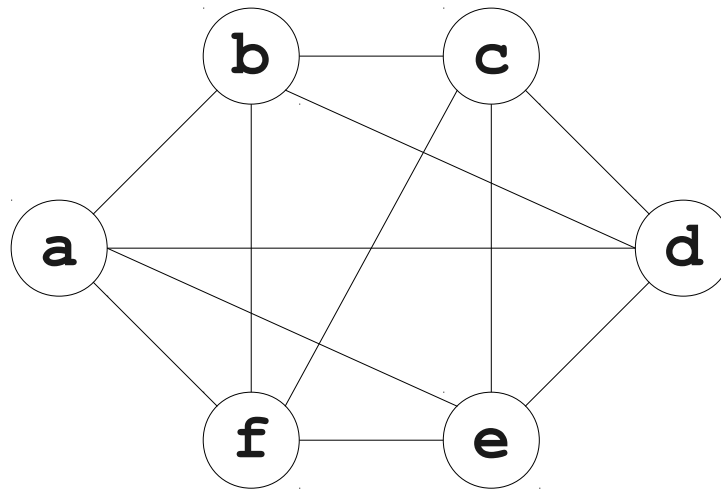


# A Smarter Algorithm

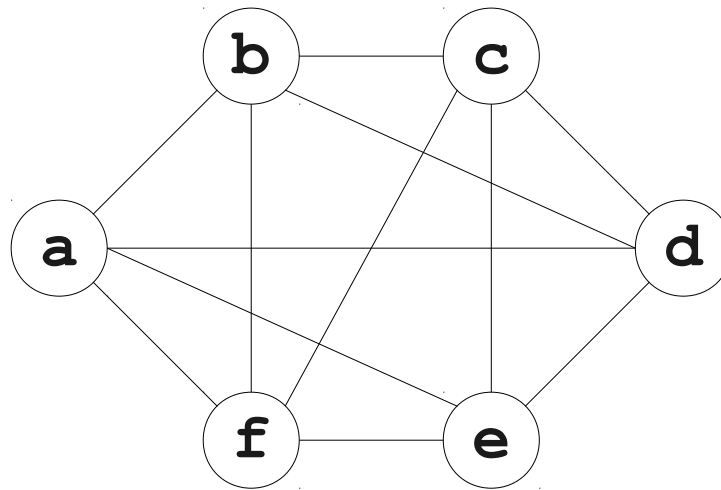


# Another Example

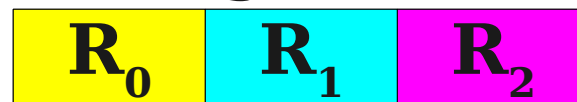
# Another Example



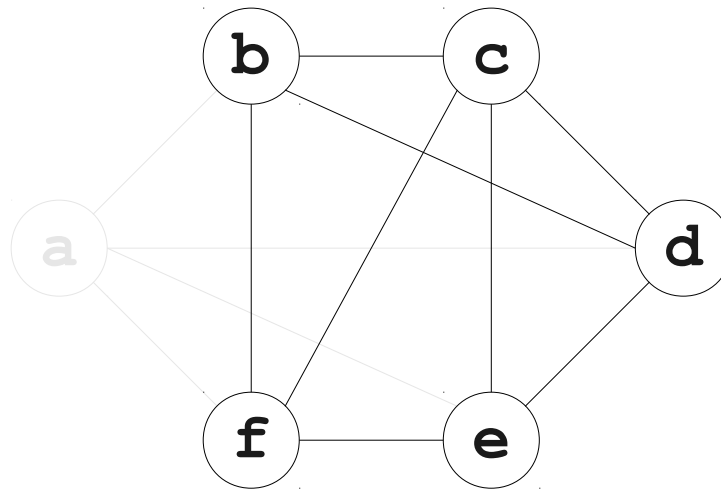
# Another Example



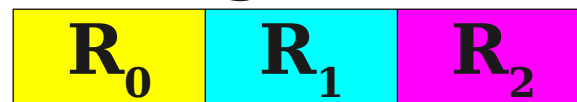
**Registers**



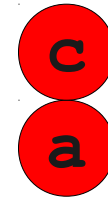
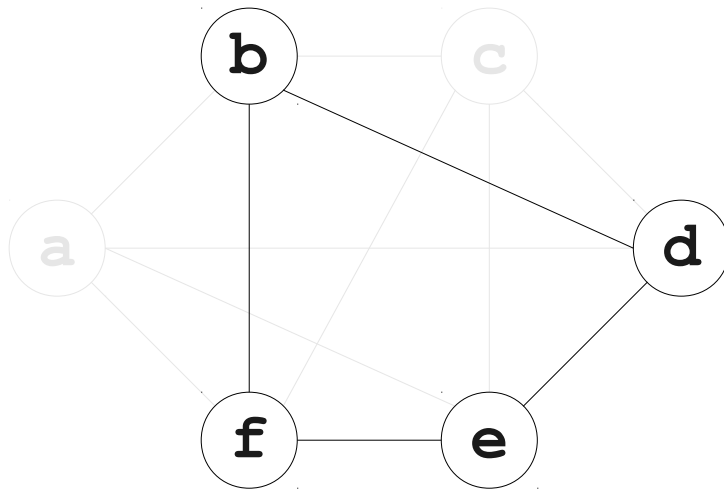
# Another Example



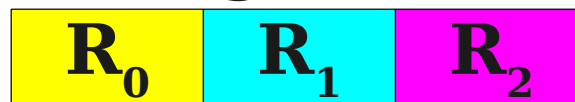
**Registers**



# Another Example

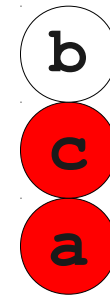
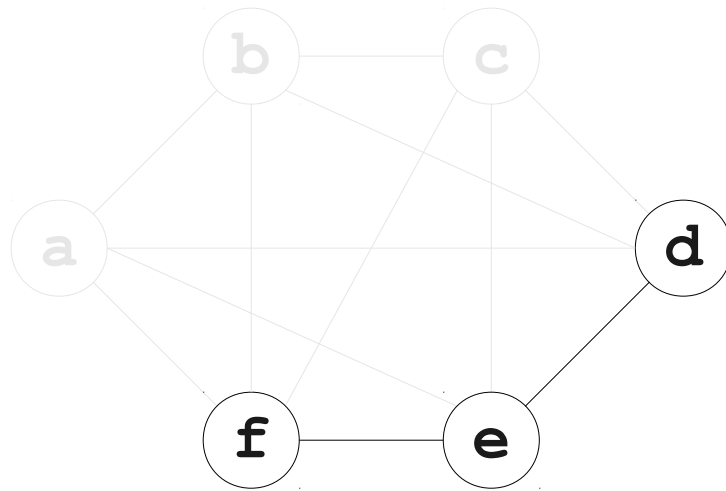


**Registers**

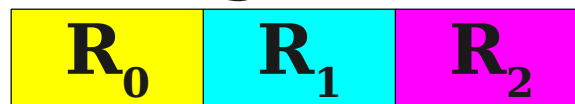




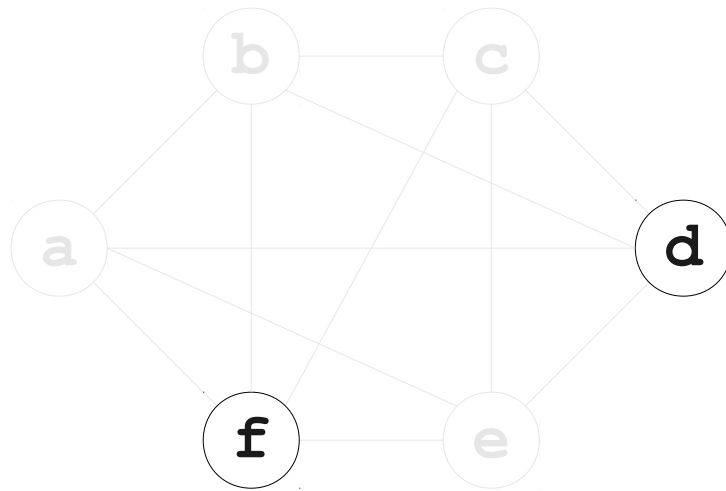
# Another Example



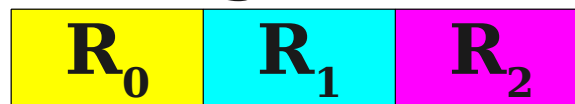
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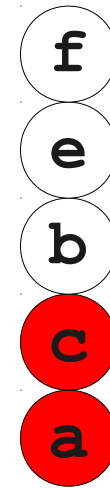
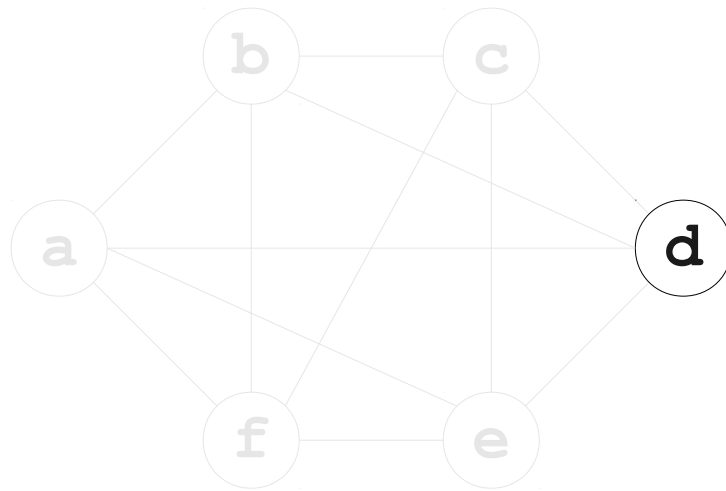
# Another Example



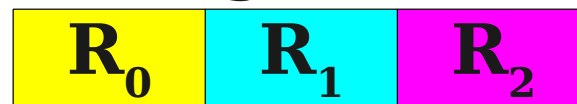
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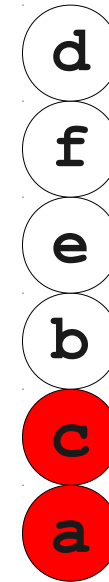
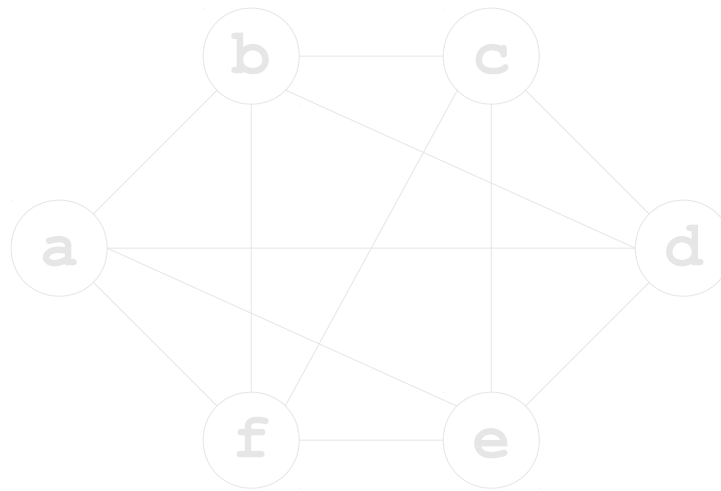
# Another Example



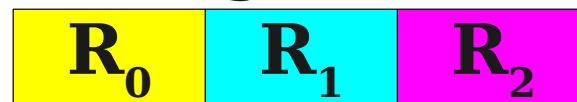
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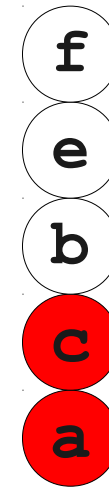
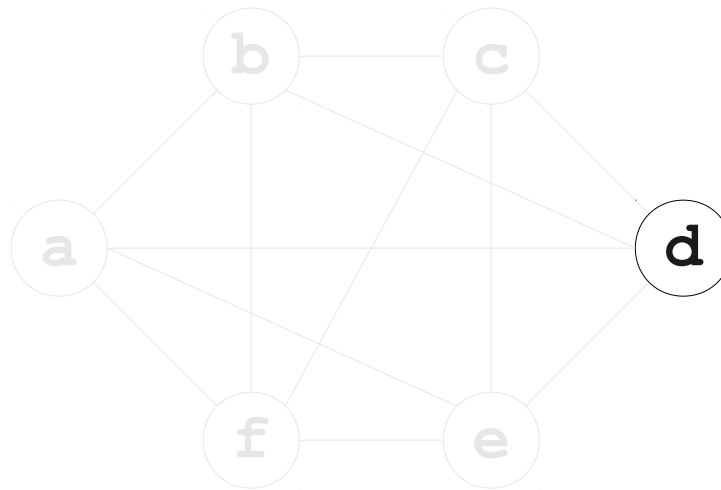
# Another Example



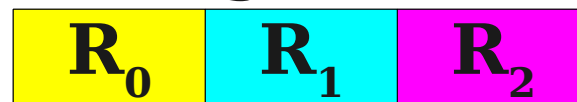
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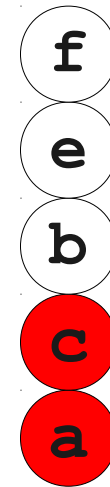
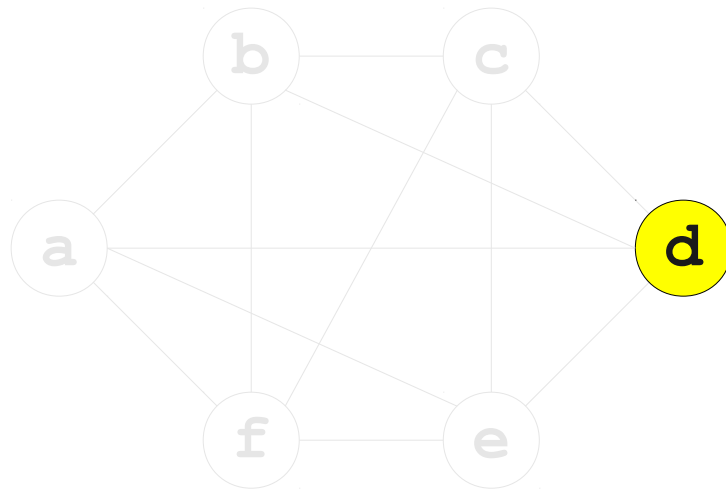
# Another Example



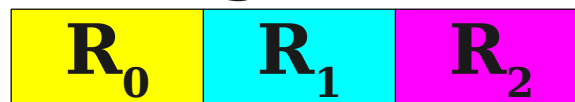
**Registers**



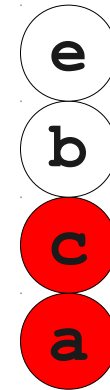
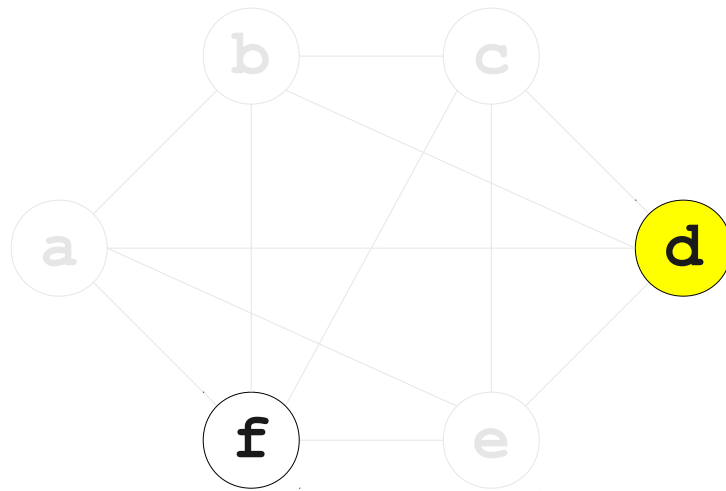
# Another Example



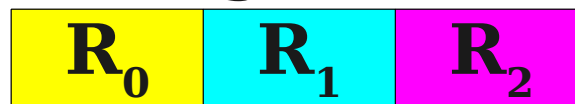
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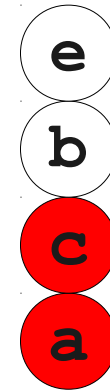
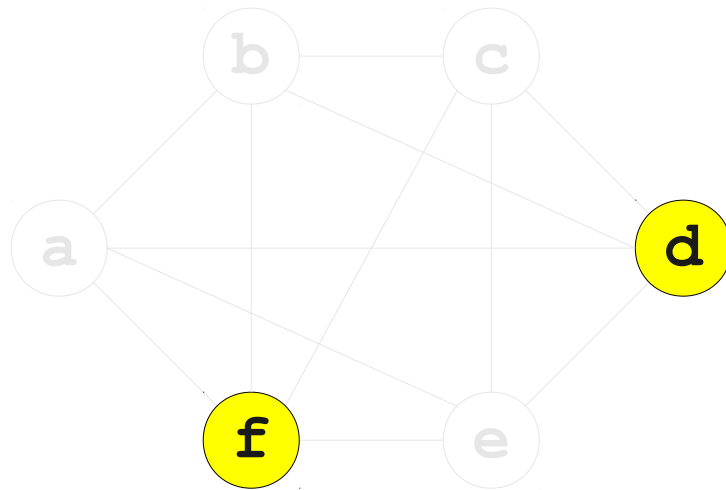
# Another Example



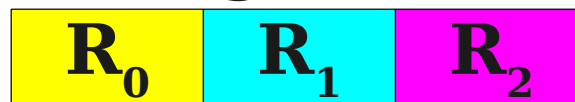
**Registers**



# Another Example

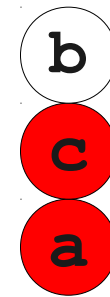
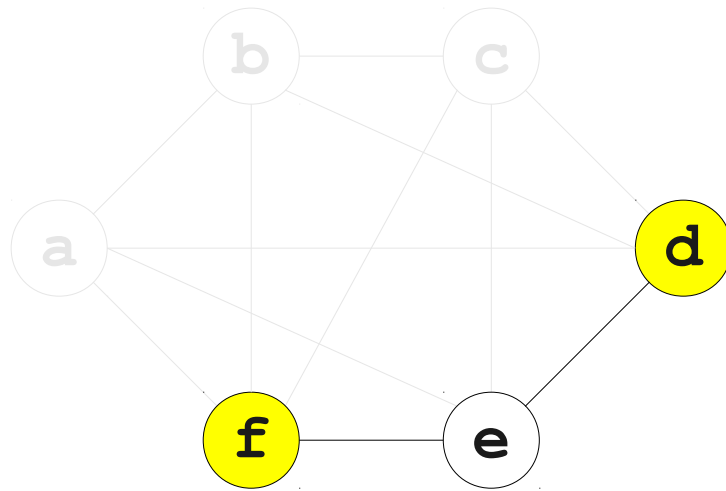


**Registers**

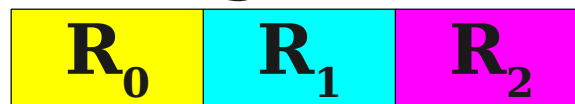




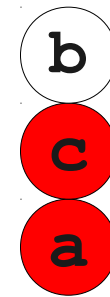
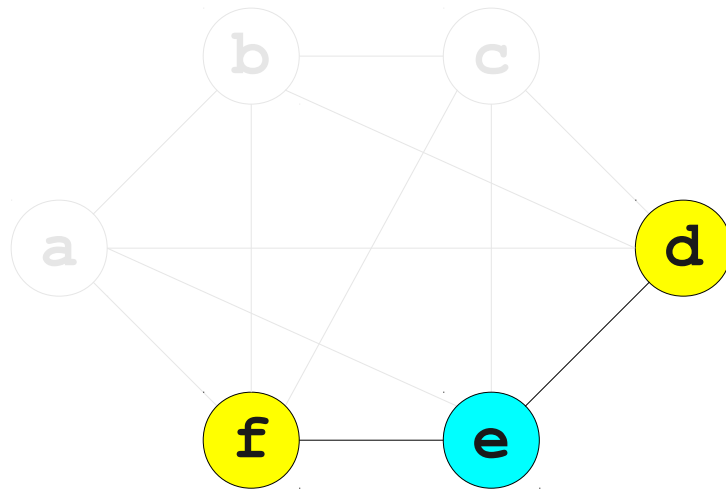
# Another Example



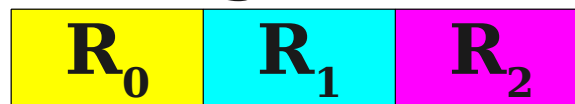
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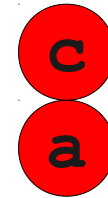
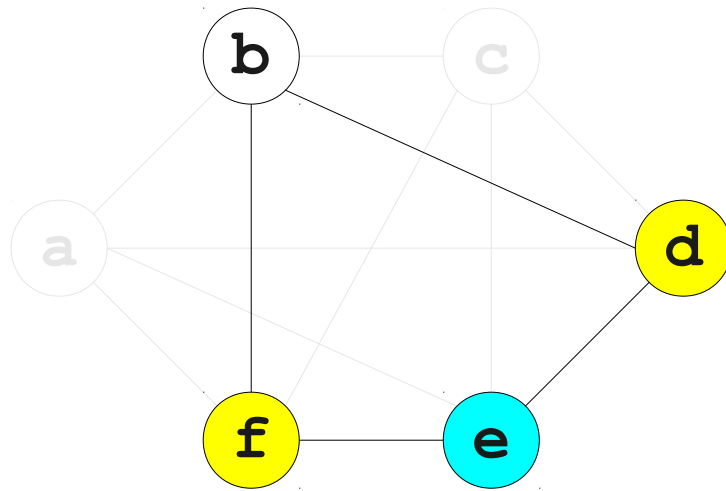
# Another Example



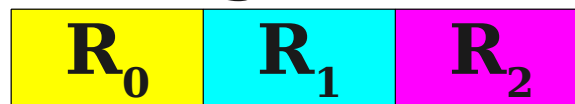
**Registers**



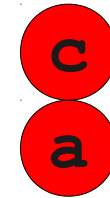
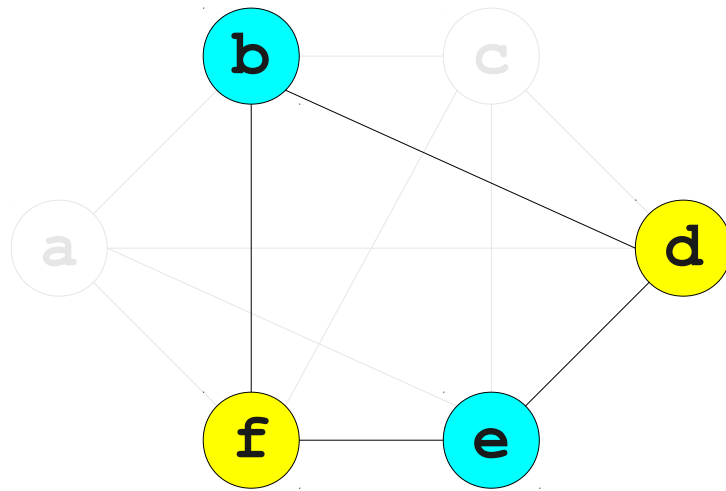
# Another Example



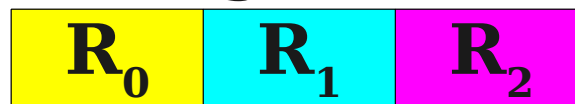
**Registers**



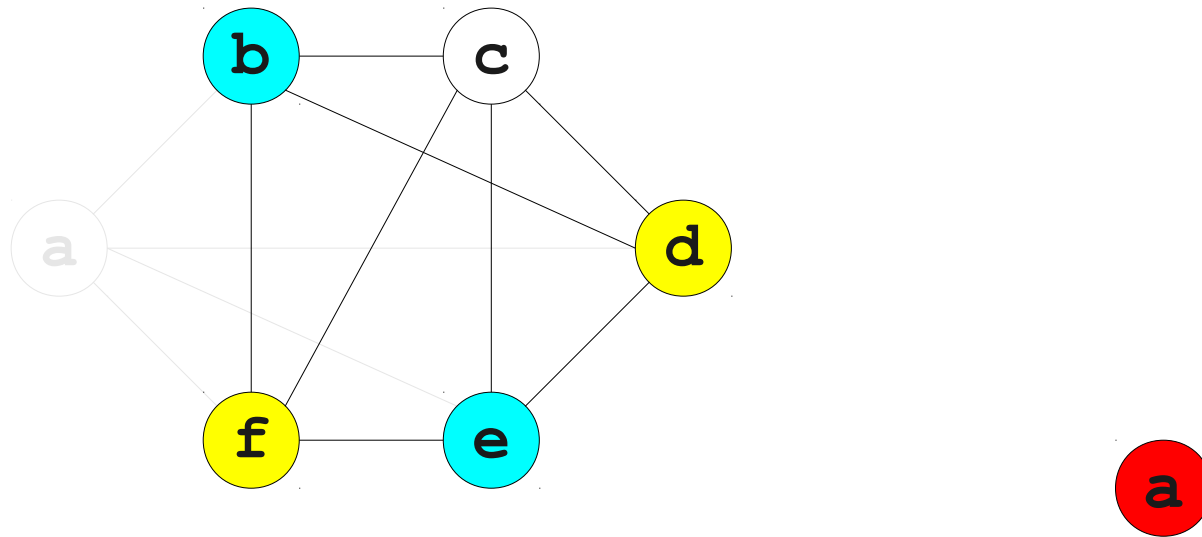
# Another Example



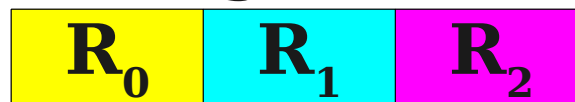
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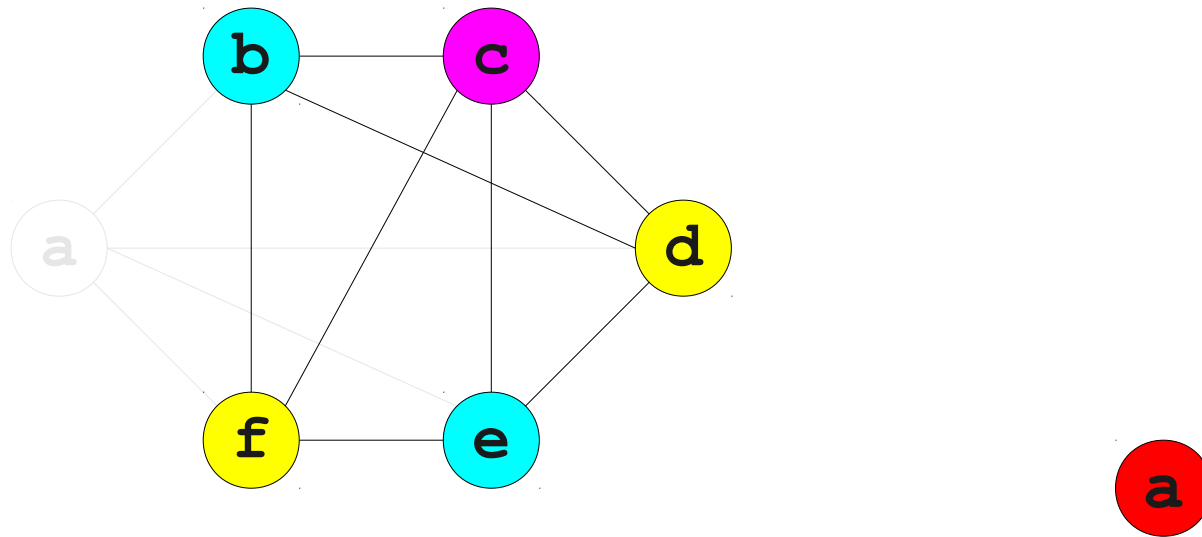
# Another Example



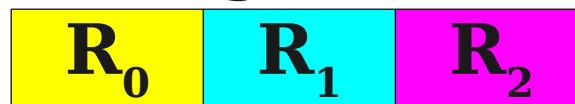
**Registers**



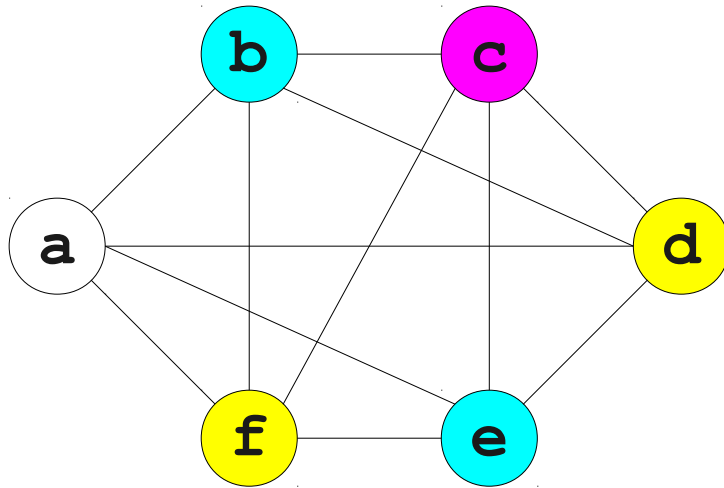
# Another Example



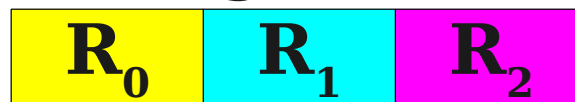
**Registers**



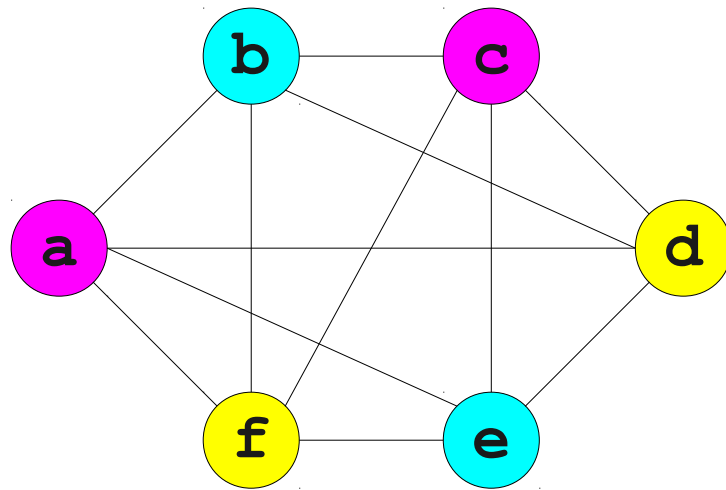
# Another Example



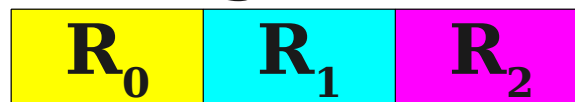
**Registers**



# Another Example

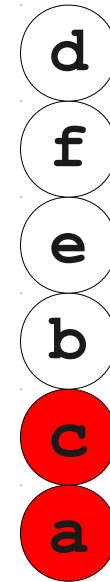
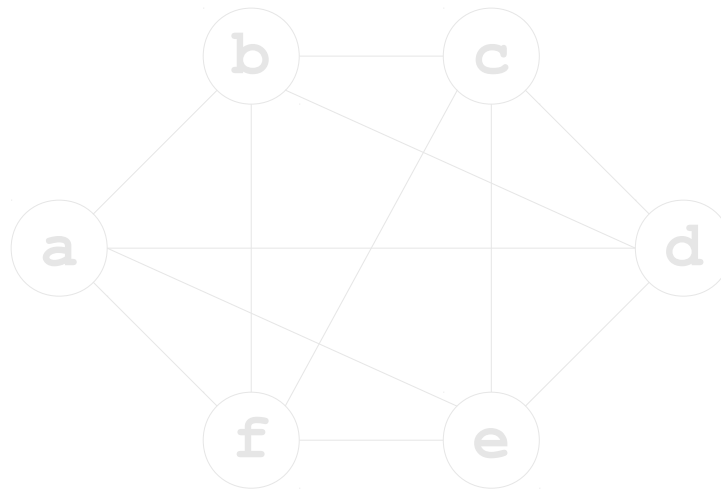


**Registers**

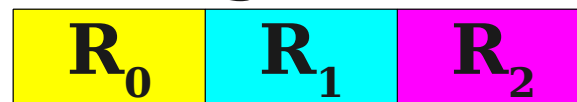




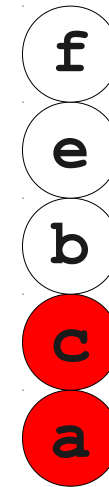
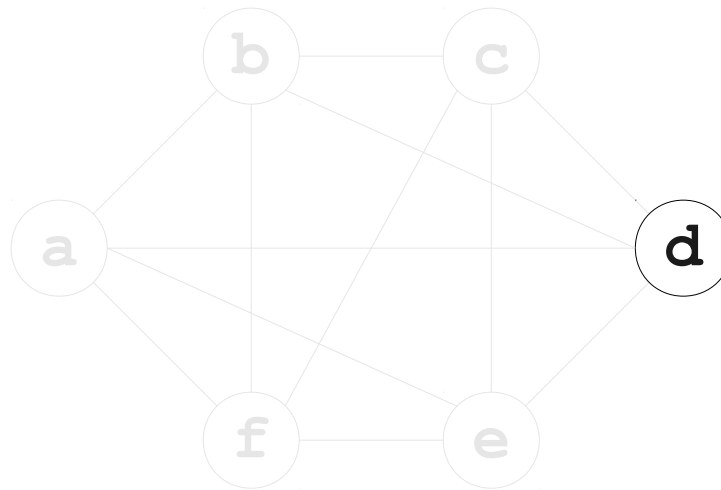
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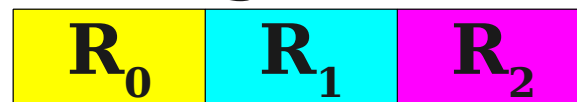
**Registers**



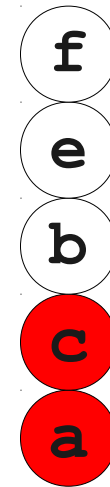
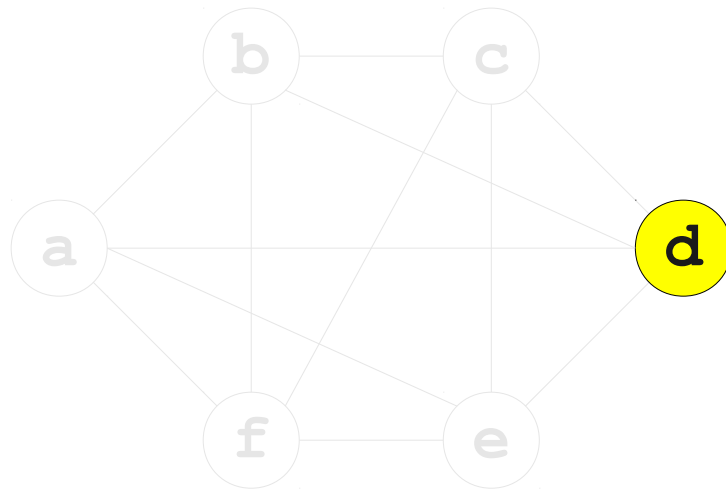
# Another Example



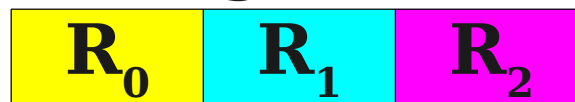
## Registers



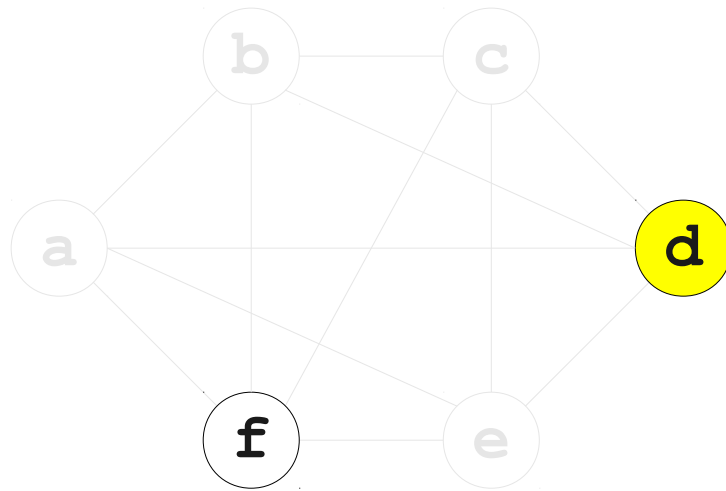
# Another Example



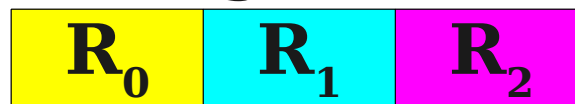
**Registers**



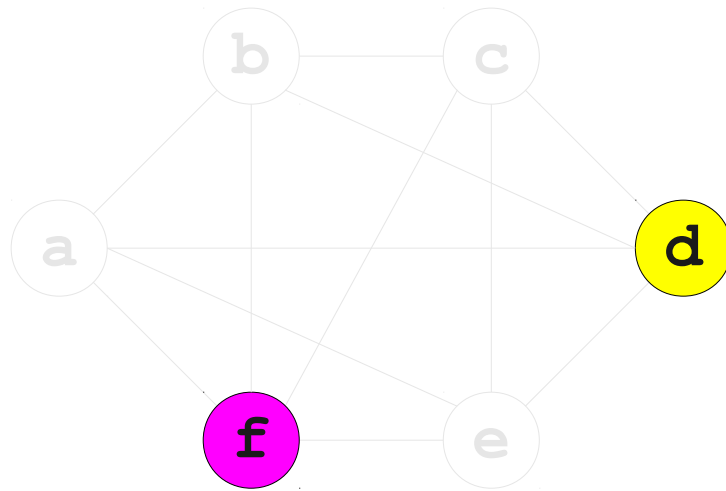
# Another Example



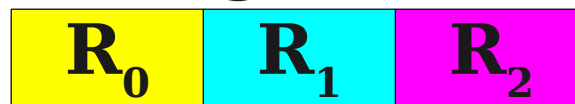
**Registers**



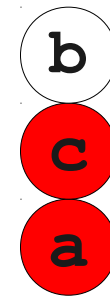
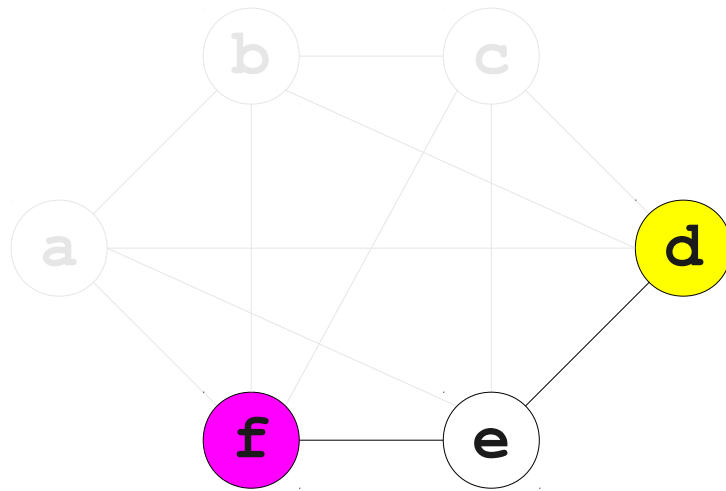
# Another Example



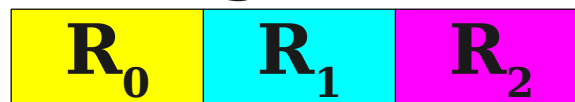
**Registers**



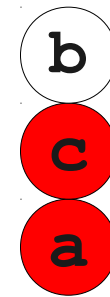
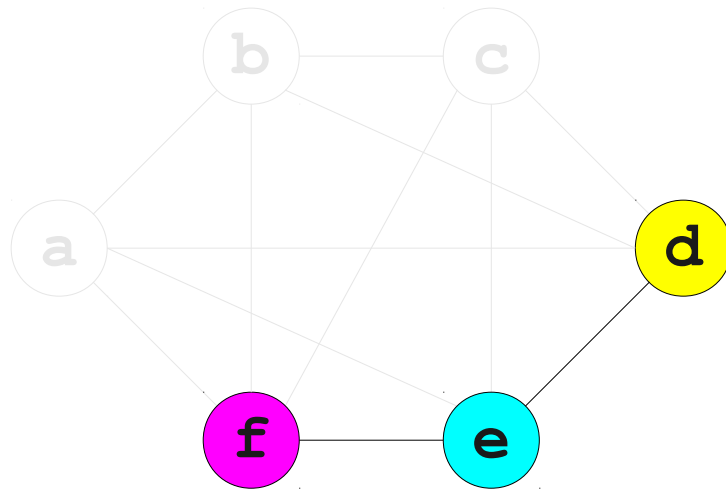
# Another Example



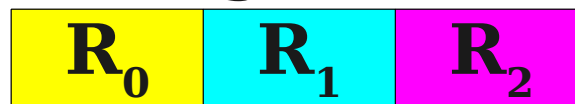
**Registers**



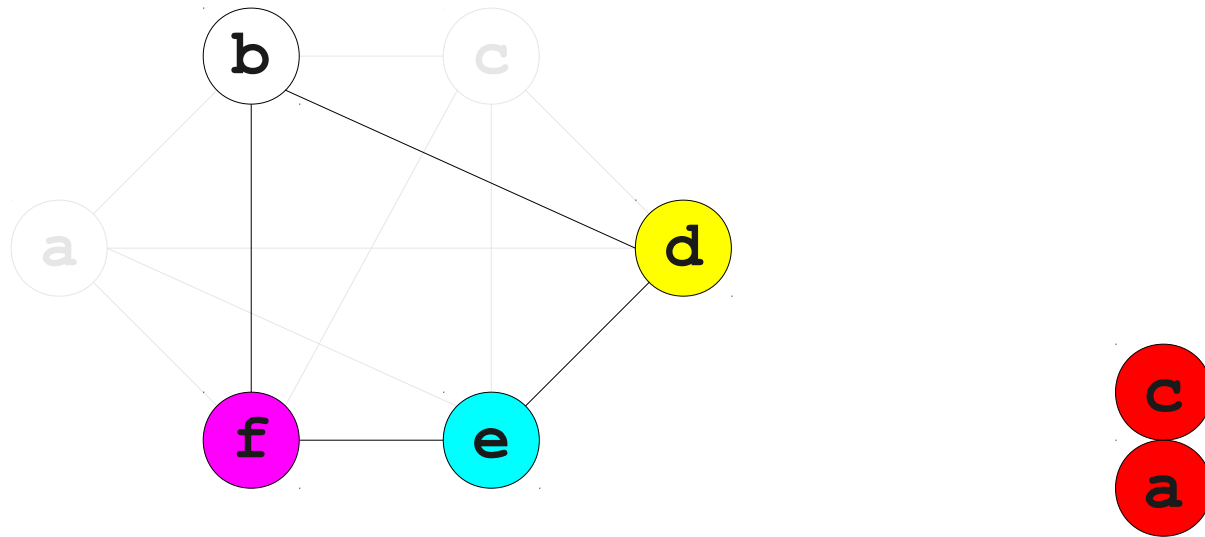
# Another Example



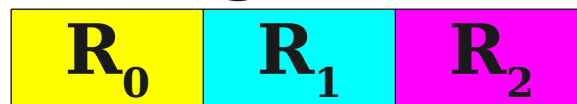
**Registers**



# Another Example

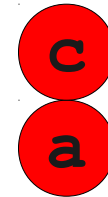
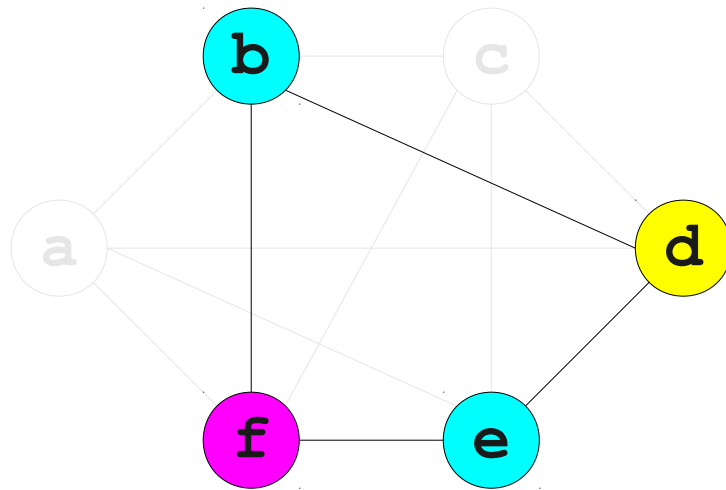


**Registers**

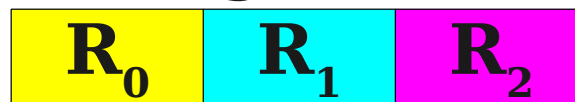




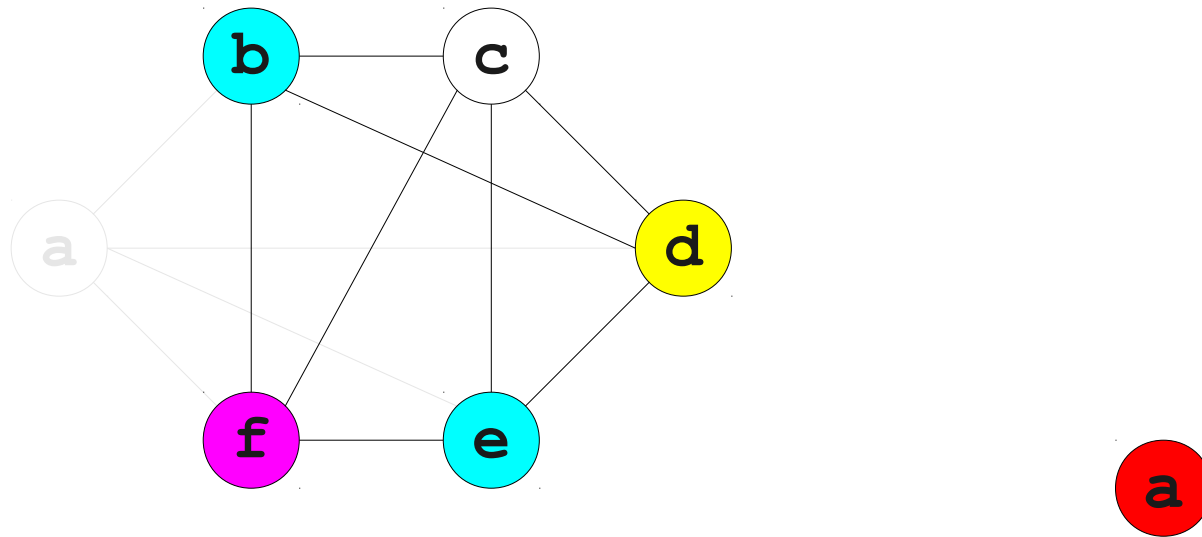
# Another Example



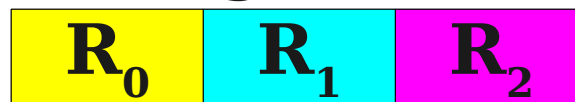
**Registers**



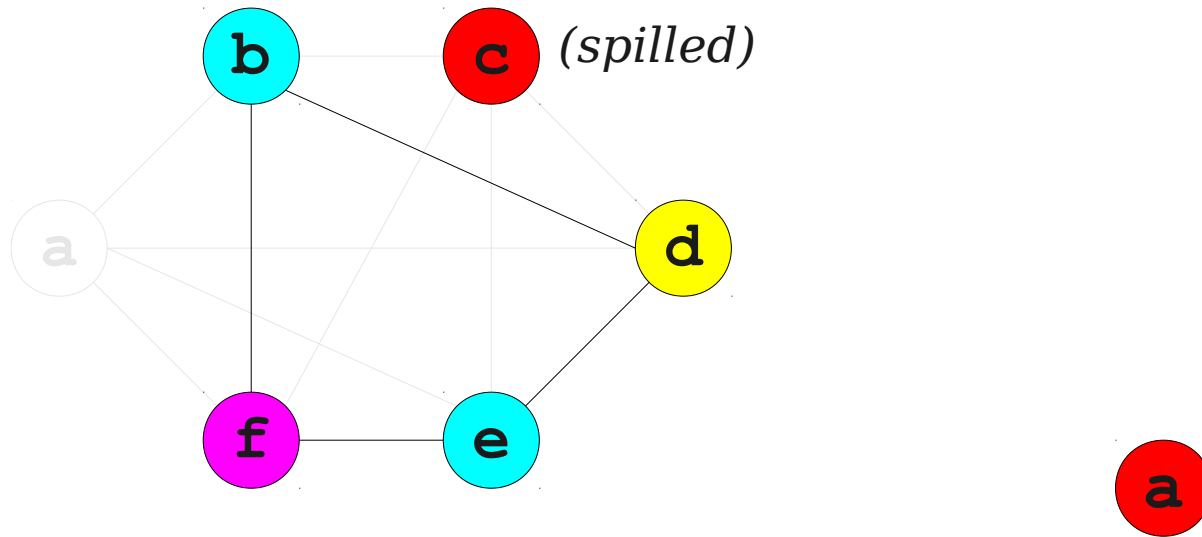
# Another Example



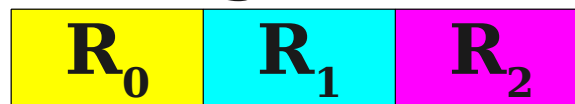
**Registers**



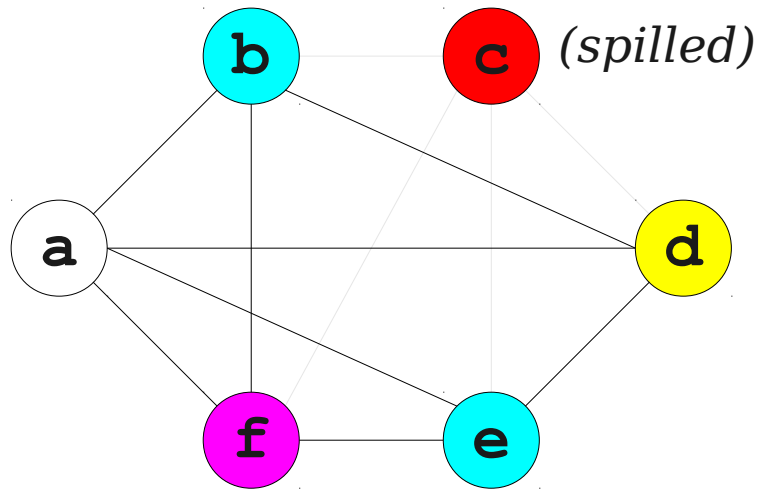
# Another Example



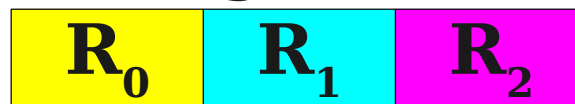
## Registers



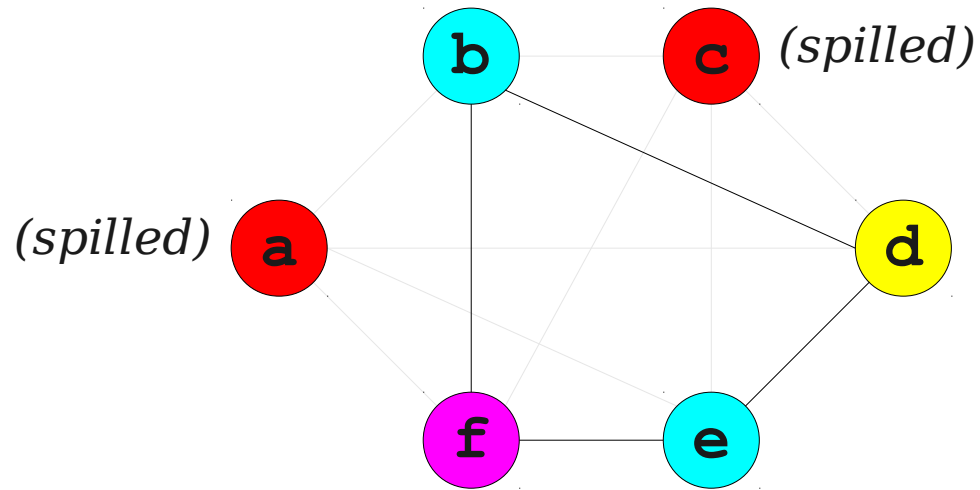
# Another Example



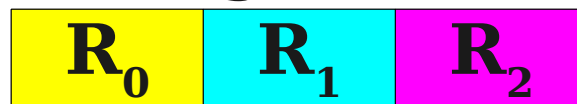
## Registers



# Another Example



## Registers



# Chaitin's Algorithm

- Advantages:
  - For many control-flow graphs, finds an excellent assignment of variables to registers.
  - When distinguishing variables by use, produces a precise RIG.
  - Often used in production compilers like GCC.
- Disadvantages:
  - Core approach based on the NP-hard graph coloring problem.
  - Heuristic may produce pathologically worst-case assignments.

# Correctness Proof Sketch

- No two variables live at some point are assigned the same register.
  - Forced by graph coloring.
- At any program point each variable is always in one location.
  - Automatic if we assign each variable one register.
  - Requires a few tricks if we separate by use case.

# Improvements to the Algorithm

- Choose what to spill intelligently.
  - Use heuristics (least-commonly used, greatest improvement, etc.) to determine what to spill.
- Handle spilling intelligently.
  - When spilling a variable, recompute the RIG based on the spill and use a new coloring to find a register.



# Summary of Register Allocation

- Critical step in all optimizing compilers.
- The **linear scan** algorithm uses **live intervals** to greedily assign variables to registers.
  - Often used in JIT compilers due to efficiency.
- **Chaitin's algorithm** uses the **register interference graph** (based on **live ranges**) and **graph coloring** to assign registers.
  - The basis for the technique used in GCC.

# Next Time

- **Garbage Collection**
  - Reference Counting
  - Mark-and-Sweep
  - Stop-and-Copy
  - Incremental Collectors